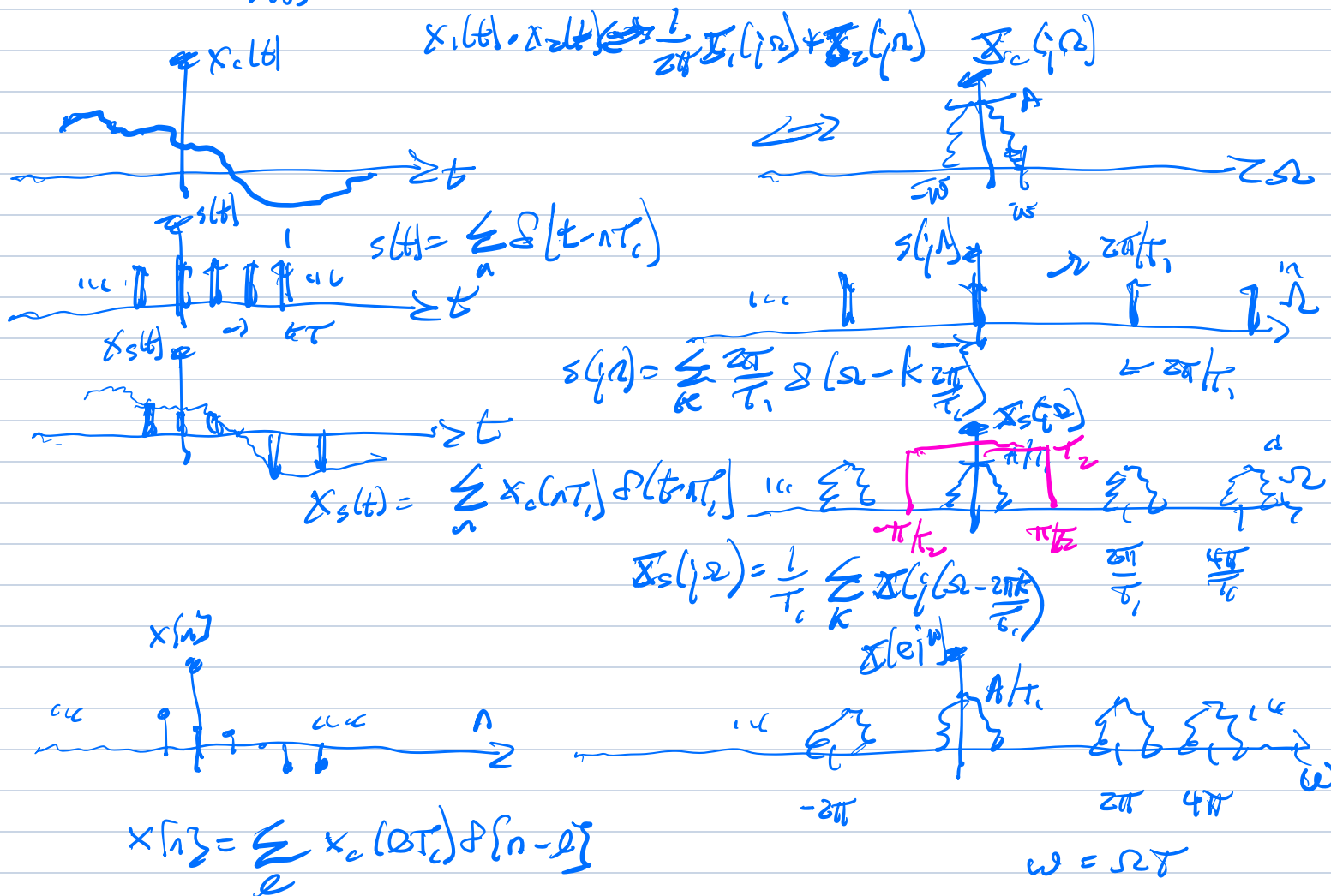
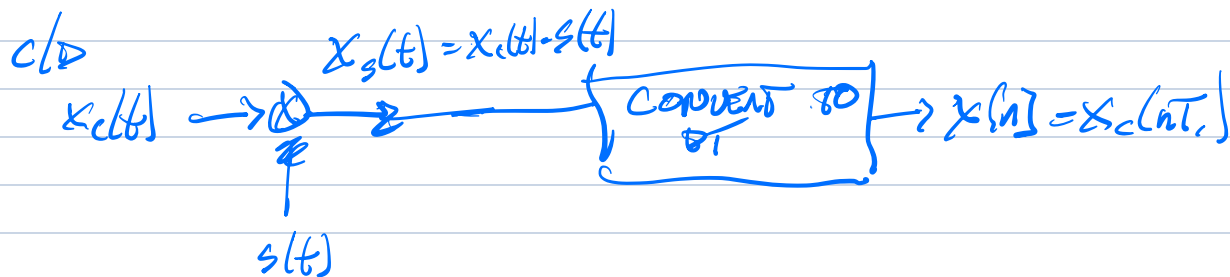
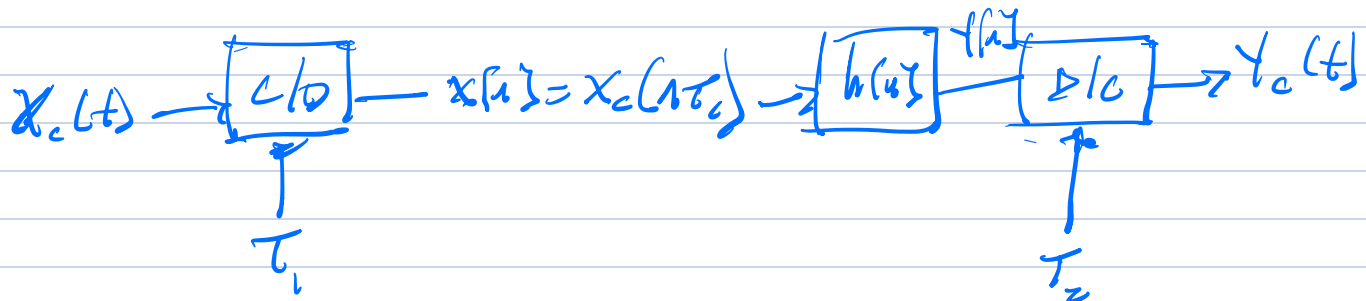


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RECITATION 1

REVIEW OF CT/DT SAMPLING



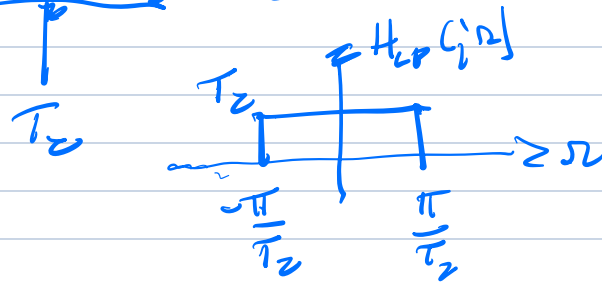
$$X(e^{j\omega}) = \frac{1}{T_1} \sum_k X_c(j(\frac{\omega}{T_1} - 2\pi k))$$

D/O CONVERSION

$$y_s(t) = \sum_n y[n] \delta(t - nT_2)$$

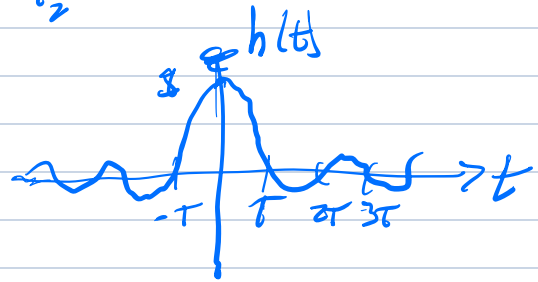


$$y_r(t) = y_s(t) * h_{LP}(t)$$



$$\text{Let } T_1 = T_2 = T$$

$$h_{LP}(t) = \frac{\sin\left(\frac{\pi t}{T}\right)}{\frac{\pi t}{T}}$$



$$y_s(t) = \sum_{n=-\infty}^{\infty} y[n] \delta(t - nT) = y_s(t) * h_{LP}(t)$$

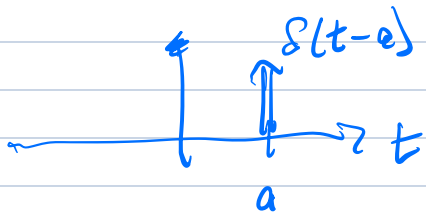
$$= \int_{-\infty}^{\infty} y_s(\tau) h_{LP}(t - \tau) d\tau$$

$$= \int_{-\infty}^{\infty} \sum_{n=-\infty}^{\infty} y[n] \delta(\tau - nT) h_{LP}(t - \tau) d\tau$$

$$= \sum_{n=-\infty}^{\infty} y[n] \underbrace{\int_{-\infty}^{\infty} \delta(\tau - nT) h_{LP}(t - \tau) d\tau}_{h_{LP}(t - nT)}$$

$$= \sum_{n=-\infty}^{\infty} y[n] h_{LP}(t - nT)$$

PROPERTIES OF DELTA FUNCTIONS



$$\int_{-\infty}^{\infty} \delta(t-a) \phi(t) dt = \phi(a)$$

consider

$$\int_{-\infty}^{\infty} \delta(t) \phi(t) dt = \phi(0)$$

$$\int_{-\infty}^{\infty} \delta(zt) \phi(t) dt$$

$$\text{let } zt = t'; \quad t = \frac{t'}{z}$$

$$dt = \frac{dt'}{z}$$

$$= \int_{-\infty}^{\infty} \delta(t') \phi\left(\frac{t'}{z}\right) \frac{dt'}{z} = \frac{1}{z} \int_{-\infty}^{\infty} \delta(t') \phi\left(\frac{t'}{z}\right) dt'$$

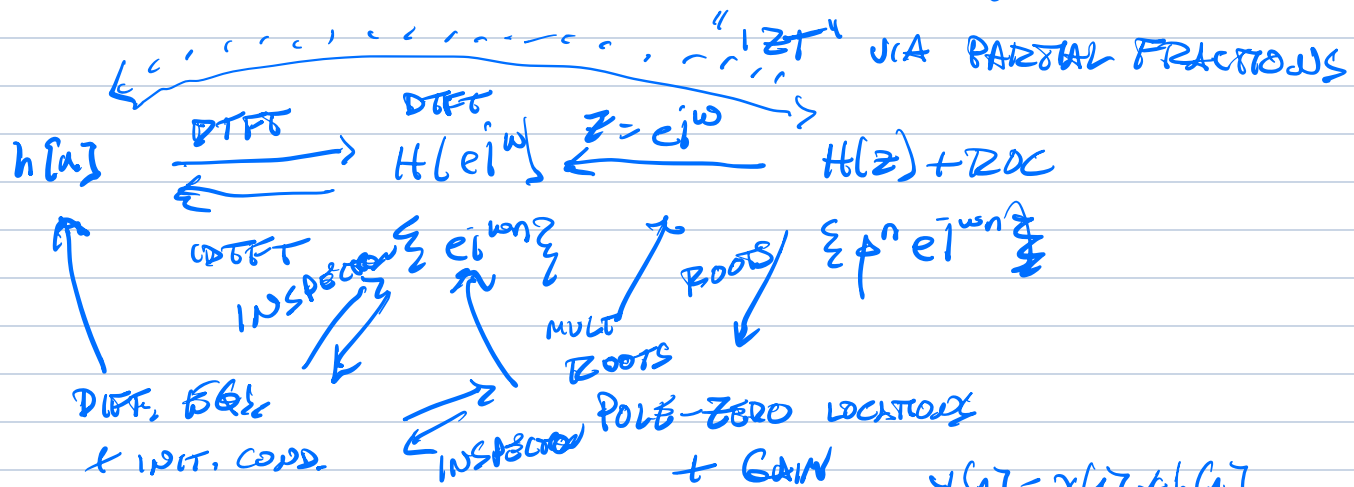
$$= \frac{1}{z} \phi(0)$$

$$\int_{-\infty}^{\infty} e^{-3t} \delta(4t-5) dt$$

$$\text{let } t' = 4t; \quad t = \frac{t'}{4}, \quad dt = \frac{dt'}{4}$$

$$= \frac{1}{4} \int_{-\infty}^{\infty} e^{-3t'/4} \delta(t'-5) dt' = \frac{1}{4} e^{-15/4}$$

REPRESENTATION OF DT SIGNALS + SYSTEMS



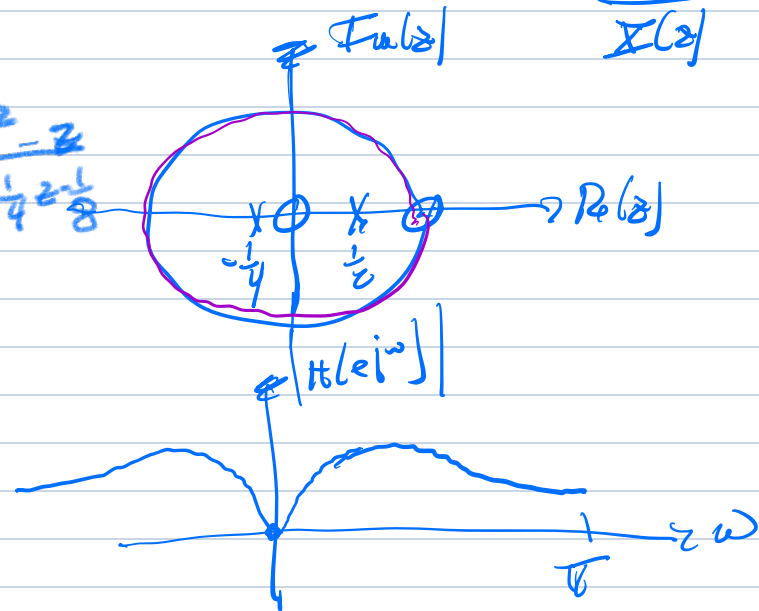
$$y[n] = x[n] * h[n]$$

$$Y(z) = X(z) \cdot H(z)$$

$$H(z) = \frac{Y(z)}{X(z)}$$

Ex: $H(z) = \frac{z(z-1)}{(z+\frac{1}{4})(z-\frac{1}{8})} = \frac{z^2 - z}{z^2 - \frac{1}{4}z - \frac{1}{8}}$

$$H(z) = \frac{1 - z^{-1}}{1 - \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2}} = \frac{Y(z)}{X(z)}$$



$$X(z) - z^{-1}X(z) = Y(z) - \frac{1}{4}z^{-1}Y(z) - \frac{1}{8}z^{-2}Y(z)$$

$$x[n] - x[n-1] = y[n] - \frac{1}{4}y[n-1] - \frac{1}{8}y[n-2]$$

$$y[n] = \frac{1}{4}y[n-1] + \frac{1}{8}y[n-2] + x[n] - x[n-1]$$

SIGNAL-FLOW DIAGRAMS

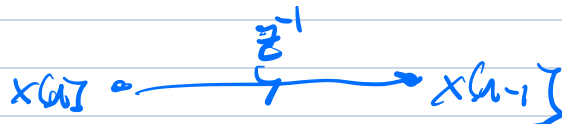
ADDITION



MULT. BY CONST.



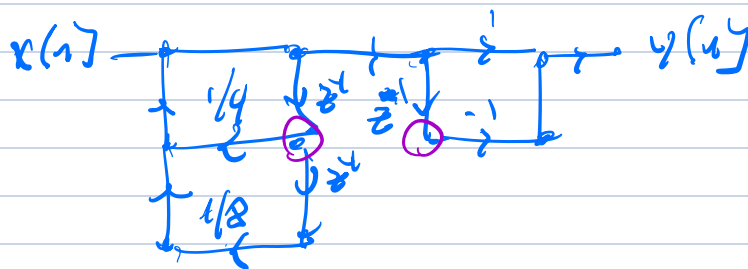
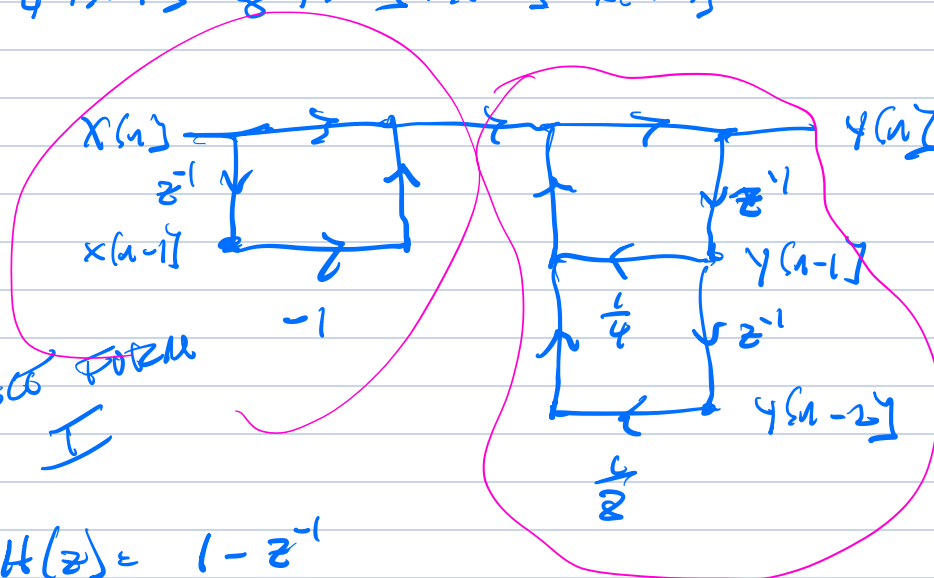
DELAY



$$y[n] = \frac{1}{4} y[n-1] + \frac{1}{8} y[n-2] + x[n] - x[n-1]$$

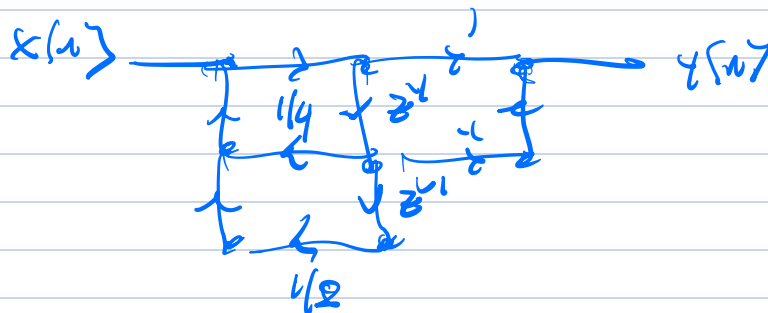
DIRECT FORM
I

$$H(z) = \frac{1 - z^{-1}}{1 - \frac{1}{4}z^{-1} - \frac{1}{8}z^{-2}}$$

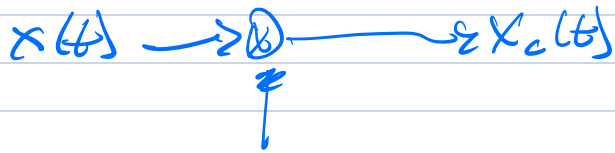


DIRECT FORM
II

CANONICAL
FORM



BASIC DSB/SC



$$c(t) = \cos(\omega_0 t)$$

$$= \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2}$$

$$x_c(t) = x(t) c(t)$$

$$\Downarrow$$

$$X_c(j\omega) = \frac{1}{2\pi} X(j\omega) * C(j\omega)$$

