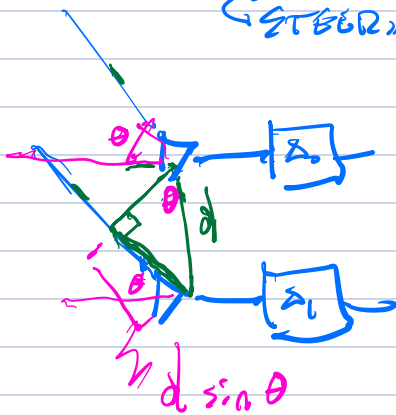
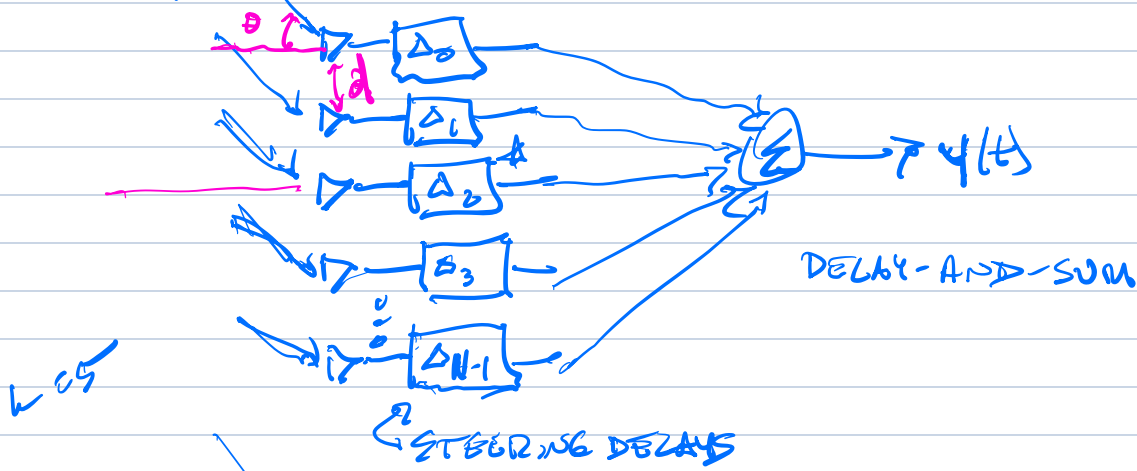


11/18/24

INTRO TO ADAPTIVE ARRAY PROCESSING

(NARROWBAND BEAM FORMING)

(WIDROW + ECCARDS CHAP 13, NOTES 9.1-9.3)



DIFFERENCE IN DISTANCE

$$= d \sin \theta \text{ meters}$$

DIFFERENCE IN TIME

$$\Delta t = \frac{d}{c} \sin \theta \text{ sec}$$

BEAM PATTERNS / POLAR RESPONSE $c \approx 340 \text{ m/s}$

Assumes $\sum \Delta_k^2 = 0$

$$\text{Let } x(t) = \cos(\omega t) = \text{Re} [e^{j\omega t}]$$

$$y(t) = \sum_{k=0}^{N-1} \cos(\omega(t - k\Delta t))$$

COMPLEX AMPLITUDE FOR $x(t) = A \cos(\omega t + \phi)$

$$= \text{Re} [A e^{j(\omega t + \phi)}]$$

$$= \text{Re} [A e^{j\phi} \cdot e^{j\omega t}]$$

Here $y(t) = \sum_{k=0}^{N-1} \cos(\omega t - k\omega t)$

$$= \sum_{k=0}^{N-1} \operatorname{Re} \{ e^{i\omega t} \cdot e^{-i k \omega t} \}$$

$$= \operatorname{Re} \left[e^{i\omega t} \sum_{k=0}^{N-1} e^{-i k \omega t} \right]$$

"Phase" $A(\omega)$

$$A(\omega) = \sum_{k=0}^{N-1} (e^{-i\omega t})^k = \frac{1 - e^{-i\omega t N}}{1 - e^{-i\omega t}}$$

$$= \frac{e^{-i\omega t \frac{N}{2}} (e^{i\omega t \frac{N}{2}} - e^{-i\omega t \frac{N}{2}})}{e^{-i\omega t \frac{1}{2}} (e^{i\omega t \frac{1}{2}} - e^{-i\omega t \frac{1}{2}})}$$

$$A(\omega) = e^{-i\omega t \frac{(N-1)}{2}} \frac{z^{\frac{1}{2}} \sin(\omega t \frac{N}{2})}{z^{\frac{1}{2}} \sin(\omega t \frac{1}{2})}$$

$$A(\omega) = e^{-i\omega t \frac{(N-1)}{2}} \frac{\sin(\omega t \frac{N}{2})}{\sin(\omega t \frac{1}{2})}$$

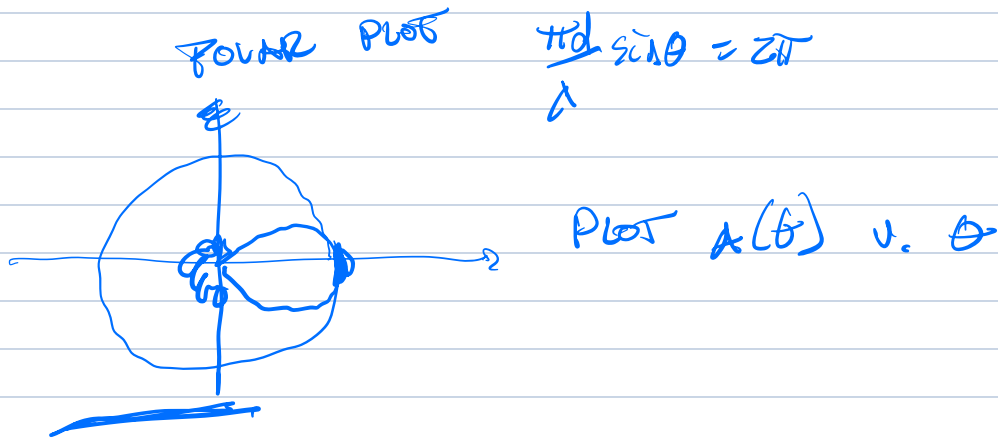
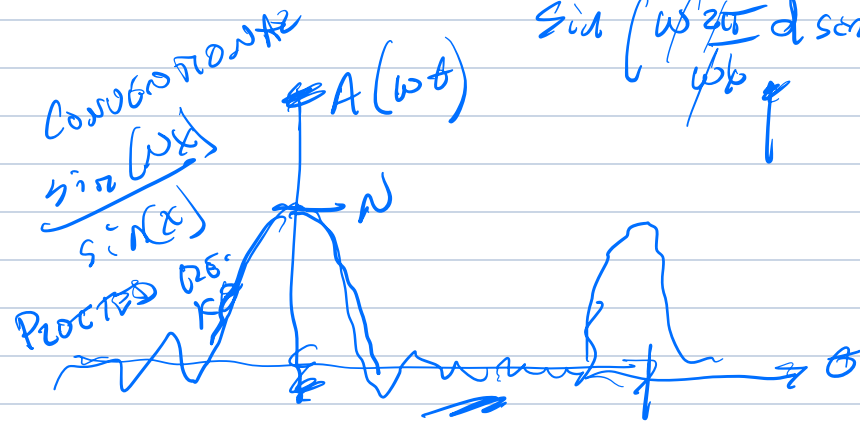
$$|A(\omega)| = \frac{\sin(\omega t \frac{N}{2})}{\sin(\omega t \frac{1}{2})}$$

$$C = 2d = \frac{\omega d}{\pi}$$

$$\Delta t = \frac{d}{C} \sin \theta = \frac{2\pi d}{\omega d} \sin \theta$$

$$\frac{d}{C} = \frac{2\pi d}{\omega d}$$

$$|A(\omega)| = \frac{\sin\left(\omega \frac{d}{2} \sin\theta \frac{N}{2}\right)}{\sin\left(\omega \frac{d}{2} \sin\theta\right)} = \frac{\sin\left(\frac{\pi d}{\lambda} N \sin\theta\right)}{\sin\left(\frac{\pi d}{\lambda} \sin\theta\right)}$$



SPATIAL ALIASING OCCURS WHEN $d \sin\theta > \frac{\lambda}{2}$

TO AVOID SPATIAL ALIASING, $c = \frac{\omega}{2\pi} d$

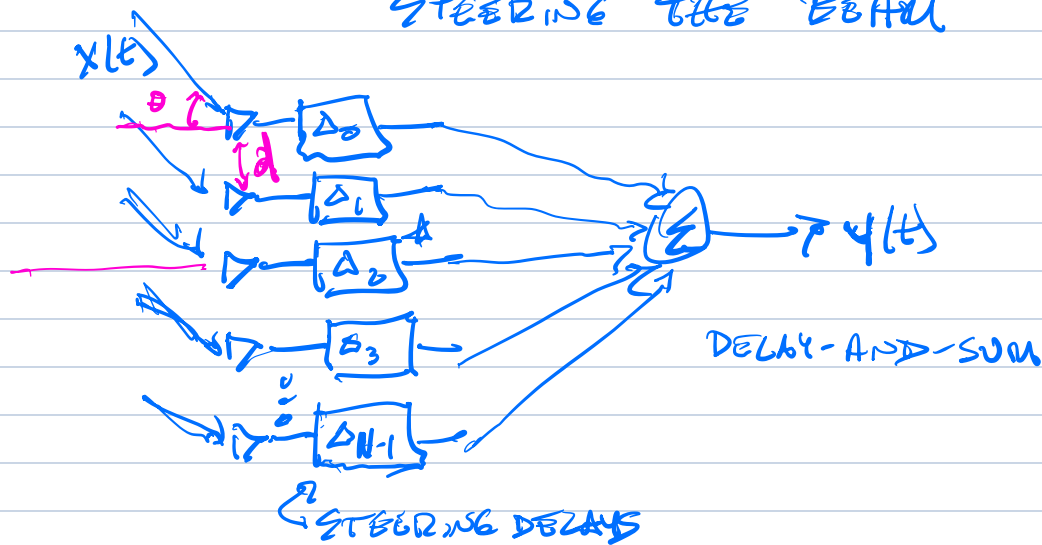
REQUIRES $d \sin\theta < \frac{\lambda}{2} = \frac{2\pi c}{2\omega}$

$\lambda = \frac{2\pi c}{\omega} = \frac{2\pi c}{2\pi N}$

$d < \frac{\pi c}{\omega \sin\theta} = \frac{c}{2 \sin\theta N}$

OR $N < \frac{c}{2 d \sin\theta}$

STEERING THE BEAM



FOR MAJOR LOBS @ $\theta = \theta_0$

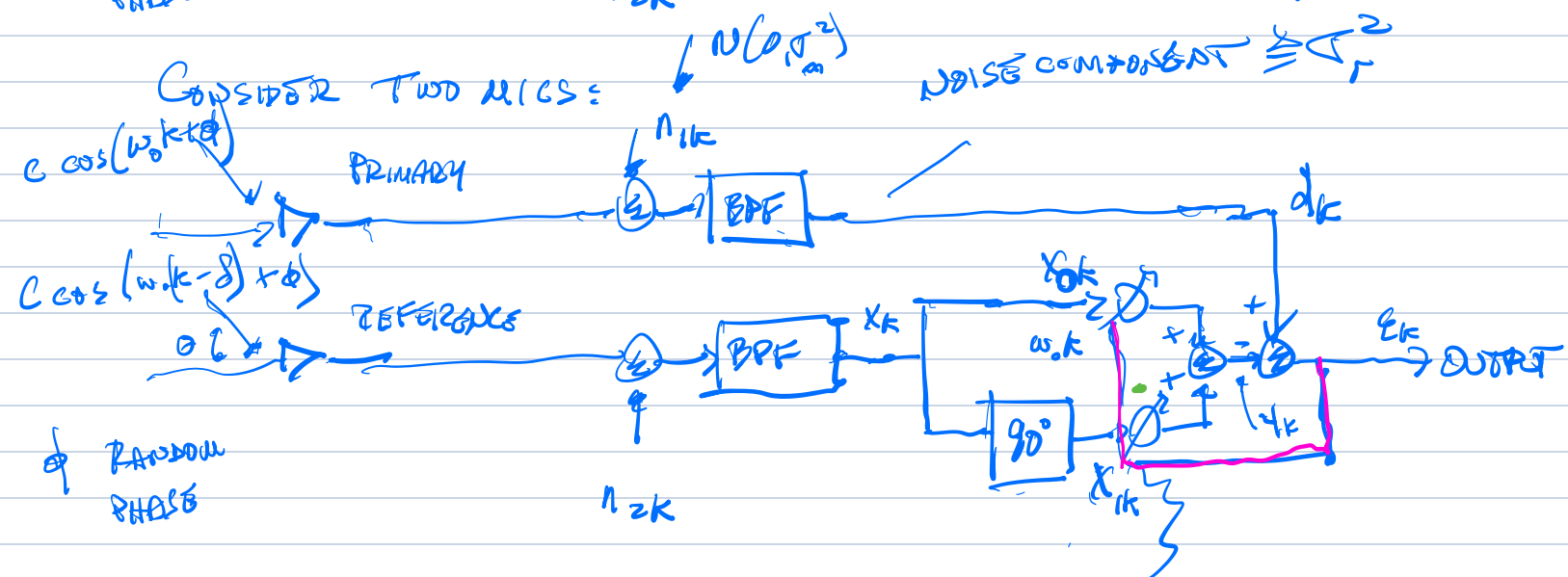
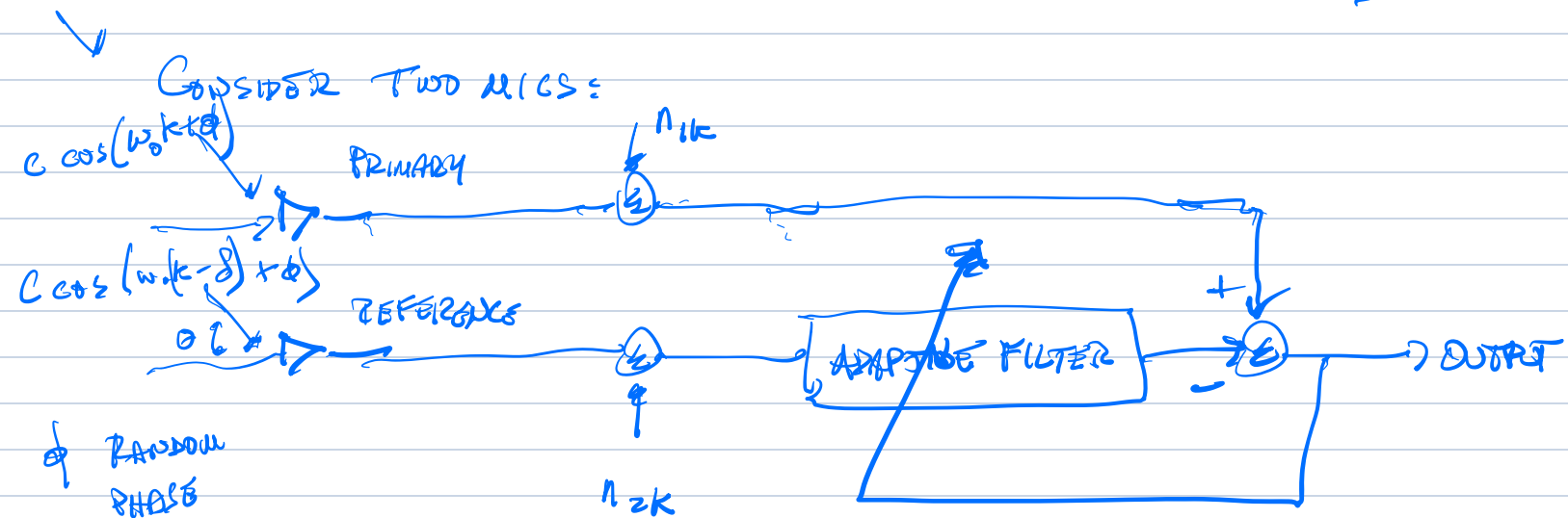
$$\text{let } \Delta_k = (N-1-k)\Delta t, \quad 0 \leq k \leq N-1, \quad \Delta t = \frac{d}{c} \sin(\theta_0)$$

Reminder: Review at 5, Htt B206 412 916-7386

Exam: coverage through PS 9, closed book, 2 sheets of notes

NARROW BAND ADAPTIVE ARRAY

[HOWELS-APPELBAUM SUBLOBE CANCELLER]



$$\delta = \frac{d \sin \theta}{c T} = \frac{2\pi d \sin \theta}{\lambda_0 \omega_0 T}$$

DELAY IN SAMPLES $\omega_0 k$
 / T SAMPLING FREQ

$$\underline{y}_k = \underline{y}_k^T \underline{\omega}_k$$

let $\underline{\omega}_k = \begin{pmatrix} \omega_{0k} \\ \omega_{1k} \end{pmatrix}$, $\underline{x}_k = \begin{pmatrix} x_{0k} \\ x_{1k} \end{pmatrix}$

$$\underline{R} = E[\underline{x} \underline{x}^T] = \begin{pmatrix} \overline{x_{0k} x_{0k}} & \overline{x_{0k} x_{1k}} \\ \overline{x_{1k} x_{0k}} & \overline{x_{1k} x_{1k}} \end{pmatrix} = \begin{pmatrix} \sigma_r^2 + \frac{c^2}{2} & 0 \\ 0 & \sigma_r^2 + \frac{c^2}{2} \end{pmatrix}$$

σ_r^2 = POWER IN n_{1k}, n_{2k} THAT GETS THROUGH BPF

$$\text{So } x_{0k} = c \cos((k-\delta)\omega_0 + \phi) + n_{2k}$$

$$x_{1k} = c \sin((k-\delta)\omega_0 + \phi) + n_{2k}$$

$$d_k = c \cos(\omega_0 k + \phi) + n_{1k}$$

$$\underline{\underline{R}} = \begin{pmatrix} \sigma_r^2 + \frac{c^2}{2} & 0 \\ 0 & \frac{c^2}{2} \end{pmatrix} \underline{\underline{I}}$$

$$\underline{\underline{P}} = \mathbb{E} [d_k \cdot \underline{\underline{x}}_k] = \frac{c^2}{2} \begin{bmatrix} \cos(\omega_0 \delta) \\ \sin(\omega_0 \delta) \end{bmatrix}$$

$$\underline{\underline{w}}^* = \underline{\underline{R}}^{-1} \underline{\underline{P}} = \frac{1}{\sigma_r^2 + \frac{c^2}{2}} \cdot \frac{c^2}{2} \begin{bmatrix} \cos(\omega_0 \delta) \\ \sin(\omega_0 \delta) \end{bmatrix}$$

$\underline{\underline{V}}(\theta)$

For $\delta = 0$

