

6/13/24

THE ADAPTIVE LATTICE FILTER

FREQUENCY-DOMAIN ADAPTIVE FILTERING (FDAF)

(LO 5.8, NOTES 8.8, SHYUK ARTICLE)

Q2 NEXT WEEK

REGULATION FRIDAY

QUIZ REVIEW SESSION MONDAY EVE 5

RE ADAPTIVE FILTERS,

LMS IS SLOW WHEN THE COMPONENTS OF $\underline{x}_k$ ARE CORRELATED
WAYS OF DEALING W CORRELATION PROBLEM

1. RLS ALGORITHM

NEWTON GRADIENT DESCENT

$$\underline{w}_{k+1} = \underline{w}_k - \mu \underline{P}^{-1} \underline{\nabla}$$

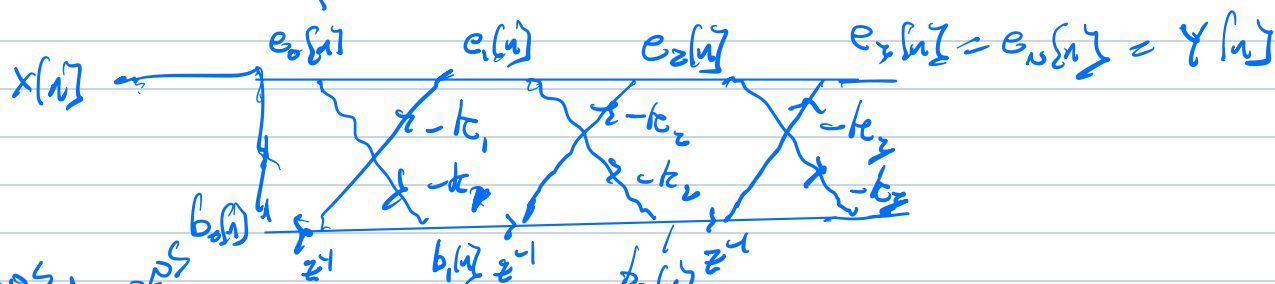
2. ADAPTIVE LATTICE FILTER (DECORRELATES OBSERVATIONS IMPLICITLY)

3. FREQUENCY-DOMAIN ADAPTIVE FILTERS (FDAF)

ADAPTIVE LATTICE FILTERS

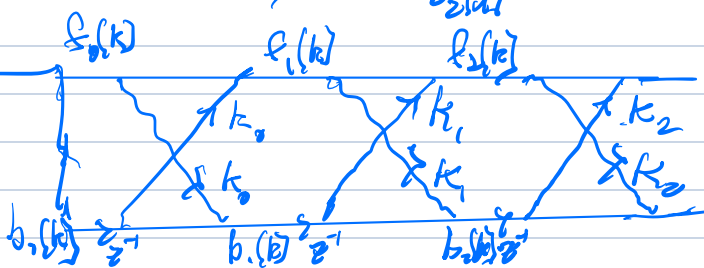
FOR LATTICE RLS, 054P

NOS



STEADY-STATE, WIDEROAD + STEADY-STATE

x_k



$$y_k = f_3[k] = f_2[k]$$

UPDATE Eqs

$$f_{i+1}[k] = f_i[k] + k_i b_i[k-1]$$

$$b_{i+1}[k] = k_i f_i[k] + b_i[k-1]$$

$$\text{let } \xi^2 = E[f_{i+1}[k]] = E[(f_i[k] + k_i b_i[k-1])^2]$$

$$\text{To find } k_i^* \quad \frac{\partial \xi^2}{\partial k_i} = E[2(f_i[k] + k_i b_i[k-1]) b_i[k-1]] = 0$$

$$E[f_i[k] b_i[k-1]] = -k_i b_i^2[k-1]$$

$$k_i^* = \frac{-E[f_i[k] b_i[k-1]]}{E[b_i^2[k-1]]}$$

CORRELATION of $\{f_i[k]\}$

$$E[f_{i+1}[k] f_i[k]] = E[(f_i[k] + k_i b_i[k-1]) f_i[k]]$$

for $k_i = k_i^*$

$$E[f_{i+1}[k] f_i[k]] = E\left[\left(f_i[k] - \frac{f_i[k] b_i[k-1]}{b_i^2[k-1]}\right) f_i[k]\right]$$

$$= E\left[f_i[k] - \frac{f_i[k] b_i[k-1]}{b_i^2[k-1]} f_i[k]\right]$$

$$= 0$$

LMS ADAPTIVE LATTICE

$$\text{CONVENTIONAL LMS } \underline{w}_{k+1} = \underline{w}_k - \mu \nabla_{\underline{w}_k} z$$

$$= \underline{w}_k - \mu (z \underline{p} - \underline{p} \underline{p}^H)$$

$$\underline{p} = \frac{z}{\|z\|}$$

LMS LATTICE

$$k_i[k+1] = k_i[k] - \mu_i \nabla \quad \nabla = \frac{\partial \varepsilon^2}{\partial k_i}$$

$$\frac{\partial \varepsilon^2}{\partial k_i} = \frac{\partial}{\partial k_i} \left[z \left(f_i[k] + k_i b_i[k-1] \right) b_i[k-1] \right]$$

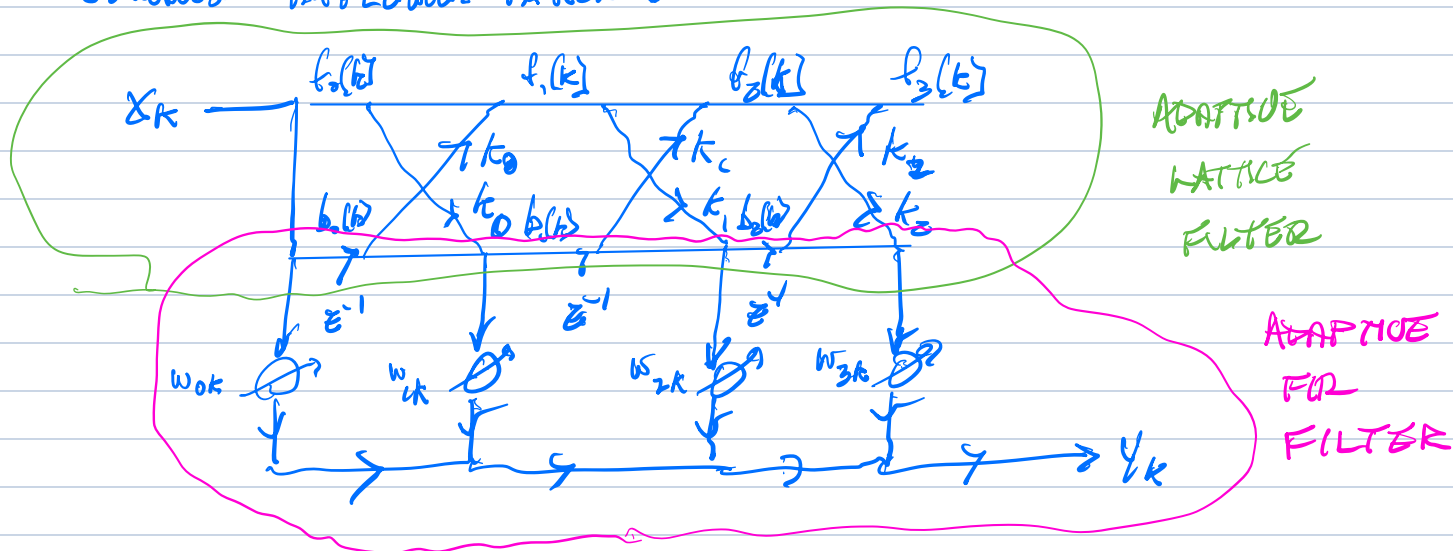
$$k_i[k+1] = k_i[k] - \mu_i z \underbrace{\left(f_i[k] + k_i b_i[k-1] \right)}_{f_{i+1}[k]} b_i[k-1]$$

$$k_i[k+1] = k_i[k] - z \mu_i f_{i+1}[k] b_i[k-1]$$

IMPLEMENTATION of ADAPTIVE LATTICE:

1. $f_0[k] = b_0[k] = x_k$
2. $k_i[k+1] = k_i[k] - z \mu_i f_{i+1}[k] b_i[k-1]$
3. CALCULATE $f_i[k], b_i[k]$
4. REPEAT FOR ALL STAGES

COMMON IMPLEMENTATION =



PRINCIPLES OF FREQUENCY-DOMAIN ADAPTIVE FILTERING (FDAF)

LMS
$$\underline{w}_{k+1} = \underline{w}_k + 2 \mu \underline{x}_k \underline{e}_k$$

SHANK

$$w[n+1] = w[n] + 2\mu x[n] e[n]$$

let N be size of ADAPTIVE FIR FILTER

$$e[n] = d[n] - y[n]$$

$$y[n] = \underline{x}^T[n] \underline{w}[n] = \underline{w}^T[n] \underline{x}[n]$$

$$\hat{\nabla}[n] = \underline{x}[n] e[n]$$

BLOCK UPDATES i.e. CHANGES ONLY AFTER L SAMPLES

$$\underline{w}[n+L] = \underline{w}[n+L-1] + 2 \mu \underline{x}[n+L-1] e[n+L-1]$$

$$\underline{w}[n+L] = \underline{w}[n] + 2 \mu \sum_{u=0}^{L-1} \underline{x}[n+u] e[n+u]$$

$$y[n+u] = \underline{x}^T[n+u] \underline{w}[n]$$

let $\underline{w}[k] = \begin{bmatrix} w_0[k] \\ w_1[k] \\ w_2[k] \\ \vdots \\ w_{N-1}[k] \end{bmatrix}$

↑
WEIGHT
COEFFS

let $\underline{\Sigma}[k] = \text{DIAGONAL OF } [\underline{x}_0[k], \underline{x}_1[k], \underline{x}_2[k], \dots]$

↑ DFT of $\underline{x}[u]$

$$\underline{y}[k] = \underline{\Sigma}[k] \underline{w}[k]$$

$$\underline{w}[k+1] = \underline{w}[k] + 2 \underline{\mu}[k] \underline{\Sigma}[k] \underline{e}[k]$$

DIAG. MATRIX