

18-600: Recitation #5

Arch Lab (Y86-64 Basics)

27th September 2016

Agenda

- Go over important points for Arch Lab
- Y86-64
 - Introduction
 - Registers
 - Instructions
 - Instruction Encoding
 - An example

Why learn processor design?

- Aid the learning of how the overall computer system works
- Many real-world systems like automobiles and appliances have embedded processors

Y86-64: Introduction

- A simple instruction set inspired by x86-64
- Y86-64 processor based on sequential operation
i.e. executes an instruction on every clock cycle
- Has fewer data types, and instructions in comparison to x86-64

Registers (or visible states)

%rax	%rsp	%r8	%r12
%rcx	%rbp	%r9	%r13
%rdx	%rsi	%r10	%r14
%rbx	%rdi	%r11	

- 15 program registers (16 in x86-64) with 4-bit ID
- Each store a 64-bit word
- %rsp is used as a stack pointer by push, pop, call, and return instructions; others don't have a fixed purpose

Registers

- Condition Codes (CC): Set by most recent arithmetic or logical instruction

ZF: Zero Flag	SF: Sign Flag	OF: Overflow Flag
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- PC: Program Counter holds address of the instruction currently being executed
- Stat: Program Status; Indicates the overall state of the program; either normal or some sort of exception occurred
- Memory: Large array of bytes; stored in little-endian byte order

mov Instructions

- irmovq: immediate to register (ex: irmovq \$18600, %r8)
- rrmovq: register to register (ex: rrmovq %r8, %r9)
- mrmovq: memory to register (ex: mrmovq (%rbp), %rdx)
- rmmovq: register to memory (ex: rmmovq %rdx, (%rbp))

Integer & Jump Instructions

■ Integer

- addq
- subq
 - subq rA, rB: subtract rA from rB
- andq
- xorq

Integer operation instructions set the three condition codes (ZF, SF, and OF)

■ Jump

- jmp
- jle
- jl
- je
- jne
- jge
- jg

Conditional Move Instructions

- cmovle
- cmovl
- cmove
- cmovne
- cmovge
- comvg

Destination register updated only when condition code satisfied

Other Instructions

- call: pushes the return address on stack, and jumps to the destination address
- pushq and popq: similar to x86-64
- halt: stops instruction execution

Instruction Encoding

Initial byte of any instruction is used for identification

Byte split into two 4-bit parts:

1. High-order or instruction code
2. Low-order or function code

addq	6	0
------	---	---

jmp	7	0
-----	---	---

jne	7	4
-----	---	---

rrmovq	2	0
--------	---	---

cmovne	2	4
--------	---	---

subq	6	1
------	---	---

jle	7	1
-----	---	---

jge	7	5
-----	---	---

cmovle	2	1
--------	---	---

cmovge	2	5
--------	---	---

andq	6	2
------	---	---

jl	7	2
----	---	---

jg	7	6
----	---	---

cmovl	2	2
-------	---	---

cmovg	2	6
-------	---	---

xorq	6	3
------	---	---

je	7	3
----	---	---

cmove	2	3
-------	---	---

Determine the byte code

```
.pos 0x100
    irmovq $15,%rbx
    rrmovq %rbx,%rcx
loop:
    rmmovq %rcx,-3(%rbx)
    addq    %rbx,%rcx
    jmp    loop
```

Let's try it out on shark...

Exceptions

Name	Meaning
AOK	Normal operation
HLT	halt instruction
ADR	Invalid address
INS	Invalid instruction

Program Structure

```
init:          # Initialization
    ...
    call Main
    halt

    .align 8      # Program data
array:
    ...

Main:          # Main function
    ...
    call len    ...
    ...

len:           # Length function
    ...

    .pos 0x100  # Placement of stack
Stack:
```

- Program starts at address 0
- Must set up stack
- Must Initialize data

Example program: asum.ys

```
# Execution begins at address 0
.pos 0
irmovq stack,%rsp      # Set up stack pointer
call main               # Execute main program
halt                   # Terminate program

# Array of 4 elements
.align 8
array: .quad 0x000d000d000d
        .quad 0x00c000c000c0
        .quad 0xb000b000b00
        .quad 0xa000a000a000

main:  irmovq array,%rdi
       irmovq $4,%rsi
       call sum            # sum(array, 4)
       ret

# long sum(long *start, long count)
# start in %rdi, count in %rsi
sum:   irmovq $8,%r8      # Constant 8
       irmovq $1,%r9      # Constant 1
       xorq %rax,%rax    # sum = 0
       andq %rsi,%rsi    # Set CC
       jmp   test          # Goto test
loop:  mrmovq (%rdi),%r10  # Get *start
       addq %r10,%rax    # Add to sum
       addq %r8,%rdi    # start++
       subq %r9,%rsi    # count--. Set CC
test:  jne   loop          # Stop when 0
       ret               # Return

# Stack starts here and grows to lower addresses
.stack 0x200
stack:
```

Running the Simulator

1. ./yas asum.ys - to generate the object code file asum.yo
2. ./yis asum.yo - to run the simulator

Archlab Part B

- **Modify ncopy.ys and pipe-full.hcl with the goal of making ncopy run as fast as possible**
- **Optimize y86 assembly as well as pipeline code for efficiency**
- **ncopy must work for arbitrary array sizes**
- **More on this next week....**

Questions?