

18-540

Distributed Embedded Systems

Prof. Philip Koopman

Fall, 2000

Lecture: Mon/Wed 12:30-2:20 PM -- PH A18A

Recitations: Fridays 1:30-2:20 -- PH A18C

Recommended Text: Kopetz, *Real-Time Systems: design principles for distributed embedded applications*, Kluwer Academic Publishers

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Mellon**

18-540 Distributed Embedded Systems

- ◆ **Based on lecture notes & practitioner-oriented papers**

- Book offers additional info, but is not testable beyond lecture coverage

- ◆ **Course objectives detailed on web pages**

- System Engineering
 - Requirements, design, verification/validation, certification, management-lite
 - System Architecture
 - Modeling/Abstraction, Design Methodology, Business Issues
 - Embedded Systems
 - Design Issues, scheduling, time, distributed implementations, performance
 - Embedded Networks
 - Protocol mechanisms, performance, CAN, TTP, embedded Internet
 - Critical Systems
 - Basic Techniques (FMEA), software safety, network safety, certification, ethics, testing, graceful degradation
 - Case Studies
 - Elevator as lab project, guest speakers and other discussions

Policies

- ◆ See <http://www.ece.cmu.edu/~ece540> for official versions
- ◆ **Grading: straight scale** $A \geq 90$; $B \geq 80$; $C \geq 70$; $D \geq 65$
 - Three in-class tests: 20% each (no final exam)
 - Homeworks: 15%; lowest one dropped; due at 4 PM
 - Course project: 25% (a few bonus points are competitive)
 - Homework & project late penalty: grade is multiplied by $0.9^{\text{\#days_late}}$
- ◆ **Slightly unusual policy on cheating**
 - Discussion of homework & project problems is acceptable and encouraged
 - But no direct copying
 - Information must stay in your brain for at least 5 minutes before you put it down on your own paper
 - Researching techniques is good, but cite source if beyond class coverage
 - Test are closed book; one 8.5"x11" sheet (2 sides) of paper notes permitted, bring your own calculator and pencils
- ◆ **Office hours: after every lecture and as posted**

Classroom Protocol

◆ Please arrive on time; lecture begins promptly

- I also promise to end on time
- Please put extra handouts in pile by door for the few latecomers

◆ Questions are encouraged

- If you don't understand, ask, because probably other students are struggling too
- Sometimes a long answer will be deferred to recitation or office hours
- Philosophical questions are welcome in remaining time at end of class

◆ There is no way to cover everything

- Embedded systems is a huge area; we will cover things I've found to be core topics in industry
- I'm electing to cover fundamentals rather than latest fad topics (little emphasis on internet toaster ovens in this course)
- There is a “digging deeper” section for each lecture if you want to expand what you are learning

1

Embedded Systems in the Real World

18-540 Distributed Embedded Systems

Philip Koopman

August 28, 2000

Required Reading: **Tennenhouse, “Proactive Computing”**

**Carnegie
Mellon**



Assignments

◆ Reading for this lecture

- *Required:* Tennenhouse, “Proactive Computing”

◆ Reading for next lecture

- *Required:* Koopman, “Embedded System Design Issues: the rest of the story”
- *Recommended:* Kopetz Chapter 1
- *Required:* Lecture is always on-line ahead of time as a preview

◆ Homework #0 due via e-mail Friday 9/1 at 4 PM

- (Most other homeworks will be hard-copy; projects will be on-line submissions)

◆ Project #1 due Wednesday 9/13 at 4 PM

- Assemble project groups by this Friday per HW #0
- Waiting until the night before is a bad idea

Where Are We Now?

◆ Where we're going today:

- General discussion of embedded systems
(they're not the same as desktop or “general purpose” computers)

◆ Where we're going next:

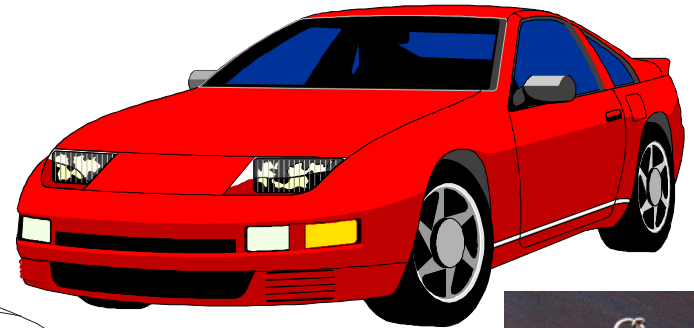
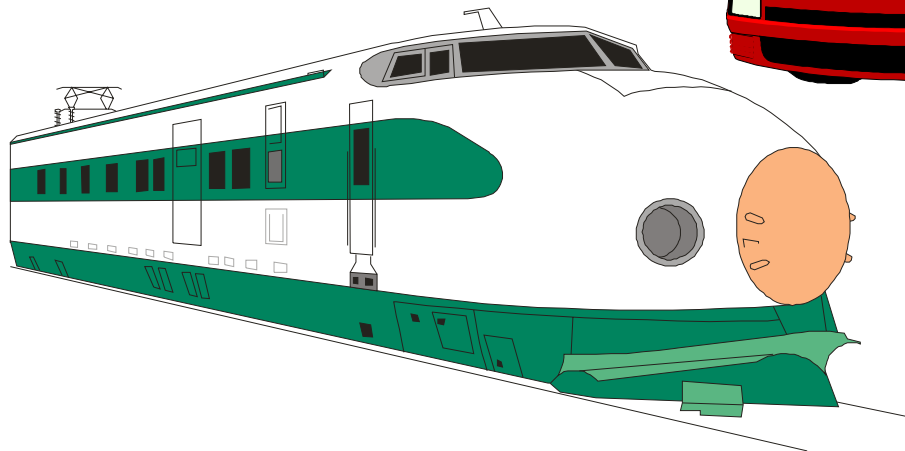
- Details of embedded+real-time+control systems
- Elevator as a detailed example (basis of course project)

Preview

- ◆ **What is an embedded system?**
 - More than just a computer
- ◆ **What makes them different?**
 - Real time operation
 - Many sets of constraints on designs
- ◆ **What embedded system designers need to know**
 - The big picture
 - Skills required to “play” in this area



Embedded System = *Computers Inside a Product*



Definition of an Embedded Computer

- ◆ **Computer purchased as part of some other piece of equipment**
 - Typically dedicated software (may be user-customizable)
 - Often replaces previously electromechanical components
 - Often no “real” keyboard
 - Often limited display or no general-purpose display device

- ◆ **But, every system is unique -- there are always exceptions**

- ◆ **Course scope focuses on distributed embedded systems, and not other embedded areas such as:**
 - Military systems: Radar, Sonar, Command & Control
 - Consumer electronics: set-top boxes, digital cameras
 - Telecommunications/DSP: cell phones, central office switches
 - Robotics

An All-Too-Common View of Computing

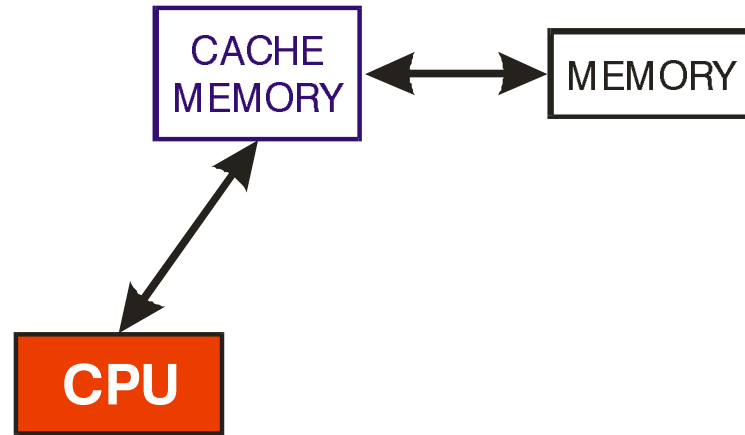
- ◆ **Measured by: Performance**



CPU

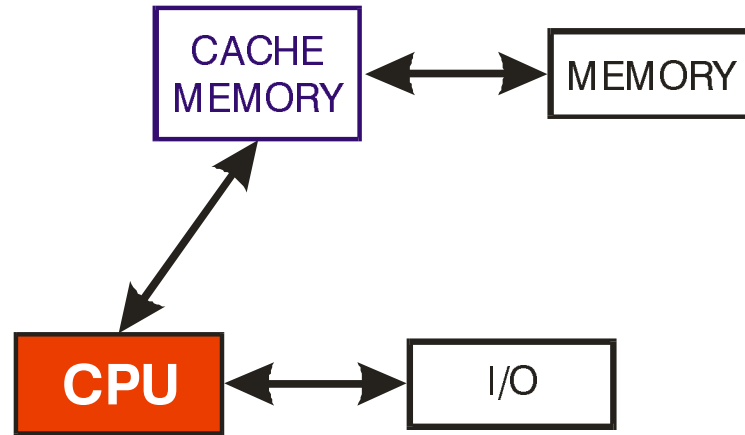
An Advanced Computer Engineer's View

- ◆ **Measured by: Performance**
 - Compilers matter too...



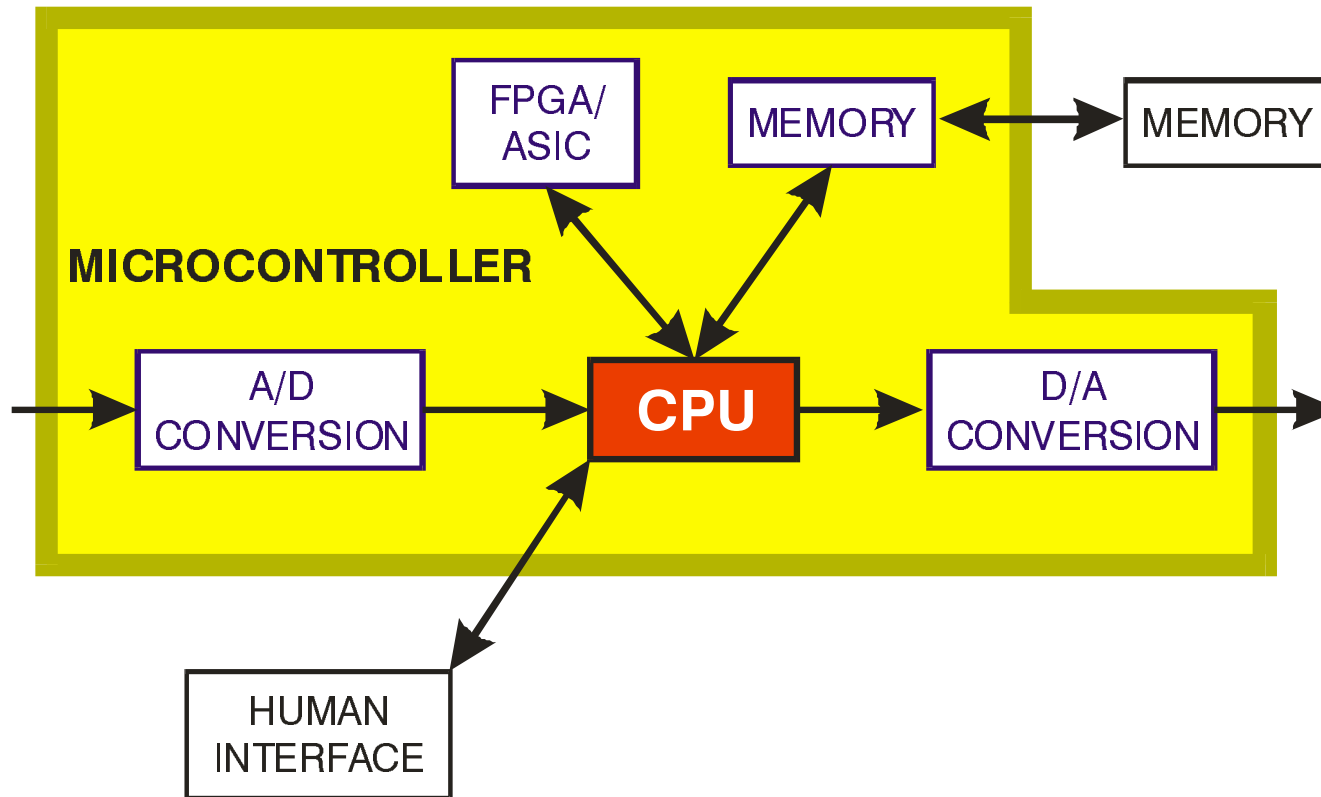
An Enlightened Computer Engineer's View

- ◆ **Measured by: Performance, Cost**
 - Compilers & OS matter



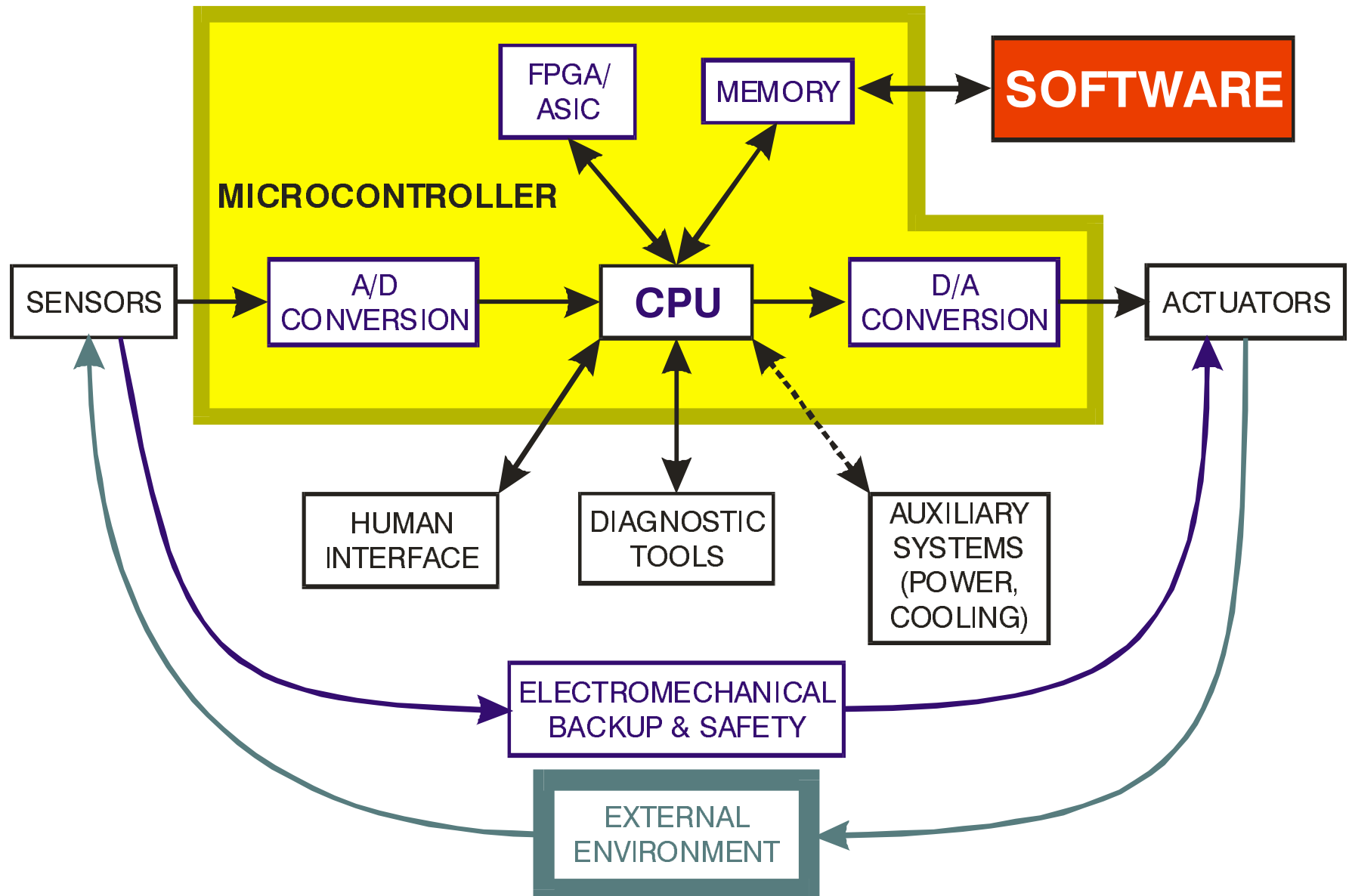
An Embedded Computer Designer's View

- ◆ Measured by: Cost, I/O connections, Memory Size, Performance



An Embedded Control System Designer's View

- ◆ Measured by: Cost, Time-to-market, Cost, Functionality, Cost & Cost.



Three Embedded Examples

◆ Pocket remote control RF transmitter

- 100 KIPS, water/crush-proof, small, 5-year battery life
- Software hand-crafted for small size (less than 1 KB)



◆ Industrial equipment controller (e.g., elevator; jet engine)

- 1-10 MIPS for 1 to 10 CPUs, 1 - 8 MB memory
- Safety-critical software; real-time control loops

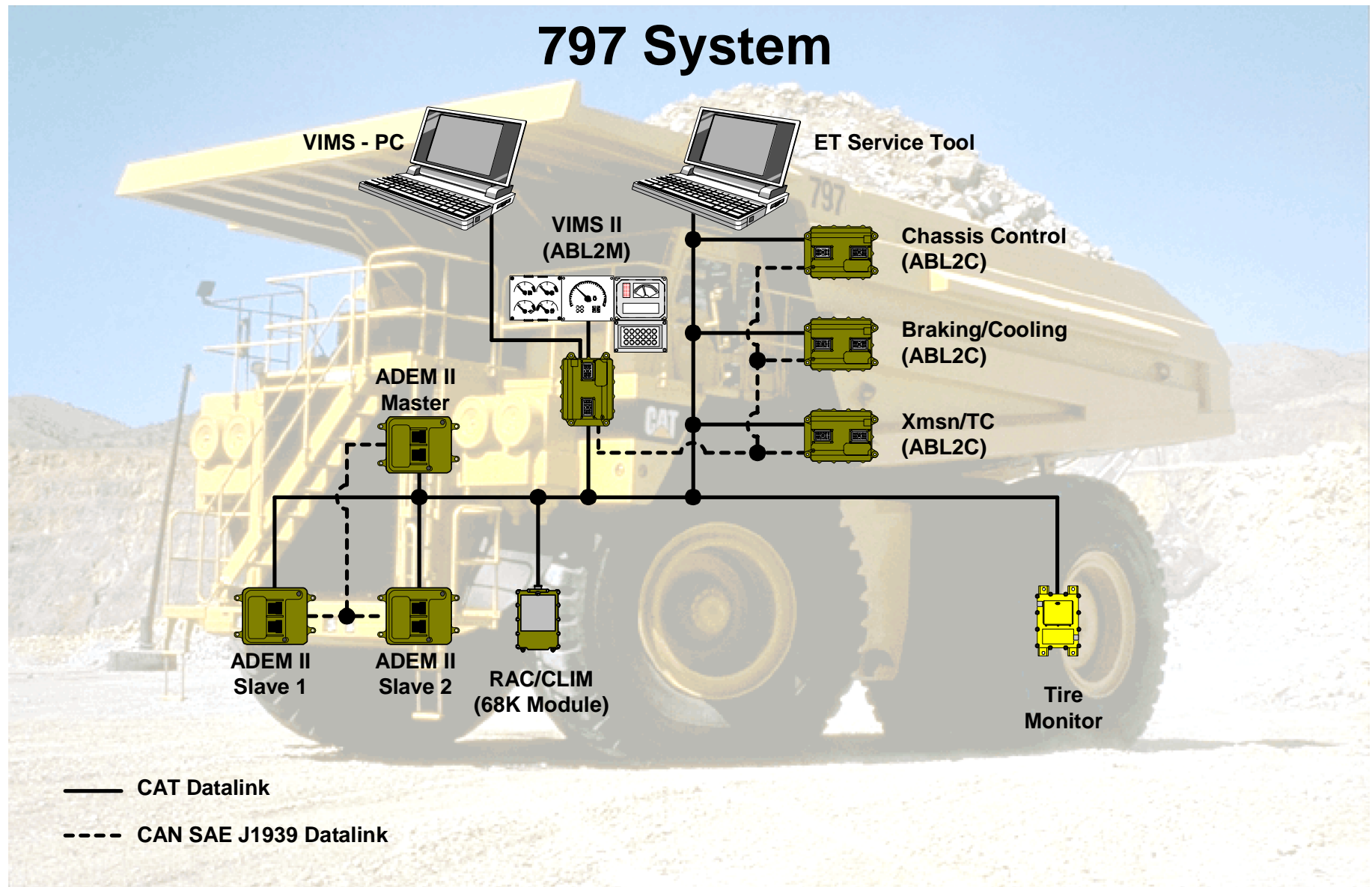


◆ Military signal processing (e.g., Radar/Sonar)

- 1 GFLOPS, 1 GB/sec I/O, 32 MB memory
- Software hand-crafted for high performance



Embedded + Distributed – Caterpillar 797



A Customer View

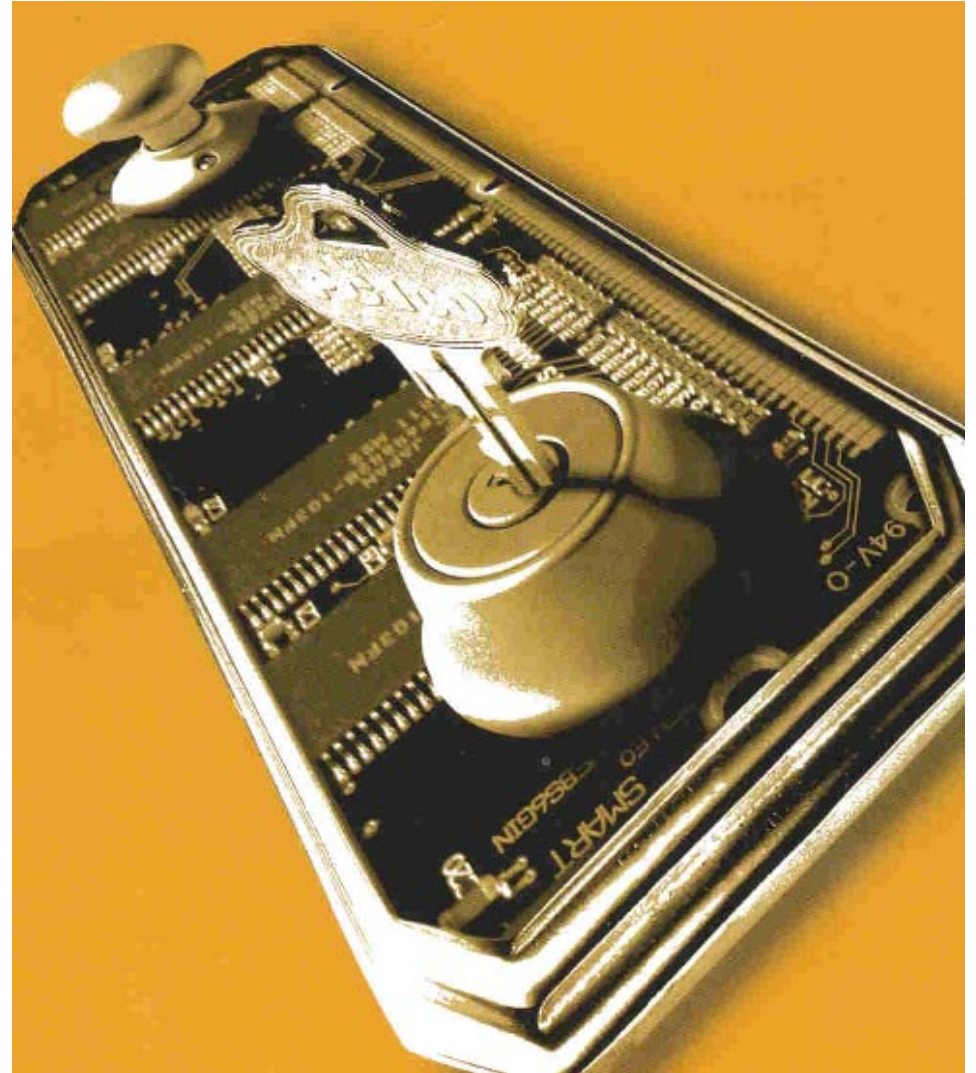


- ◆ **Reduced Cost**
- ◆ **Increased Functionality**
- ◆ **Improved Performance**
- ◆ **Increased Overall Dependability**
 - (Debatable, but can be true)



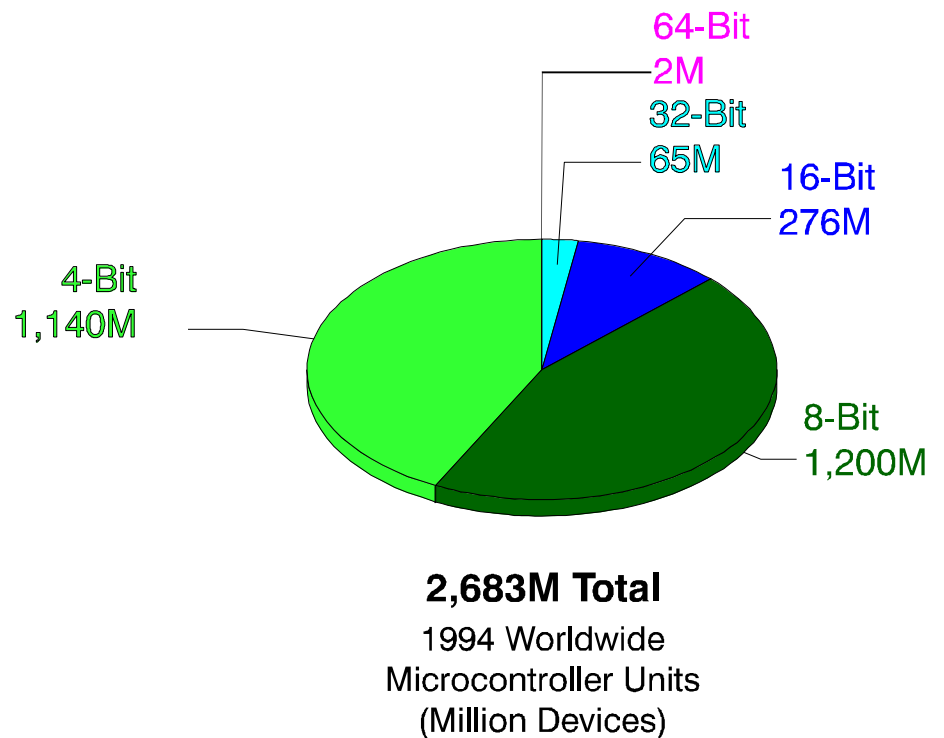
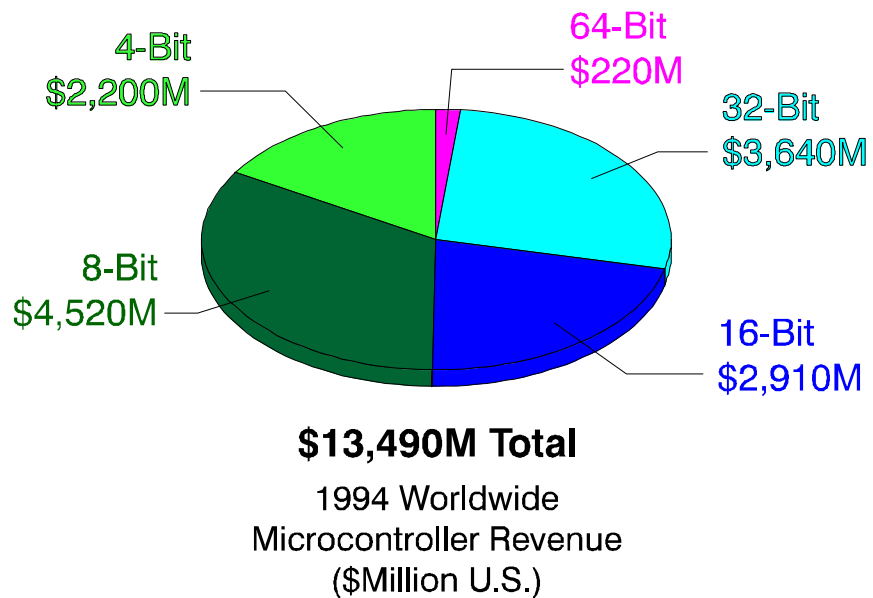
**What in the world are you going to
do with all those computers?
It's not as if you want one in every
doorknob!**

- Danny Hillis, circa 1980, as told by
Guy Steele at 1996 CMU SCS
commencement



Small Computers Rule The Marketplace

- ◆ ~80 Million PCs vs. ~3 Billion Embedded CPUs Annually in 1995
 - 150 Million PCs and 7.5 Billion embedded CPUs + in 2000

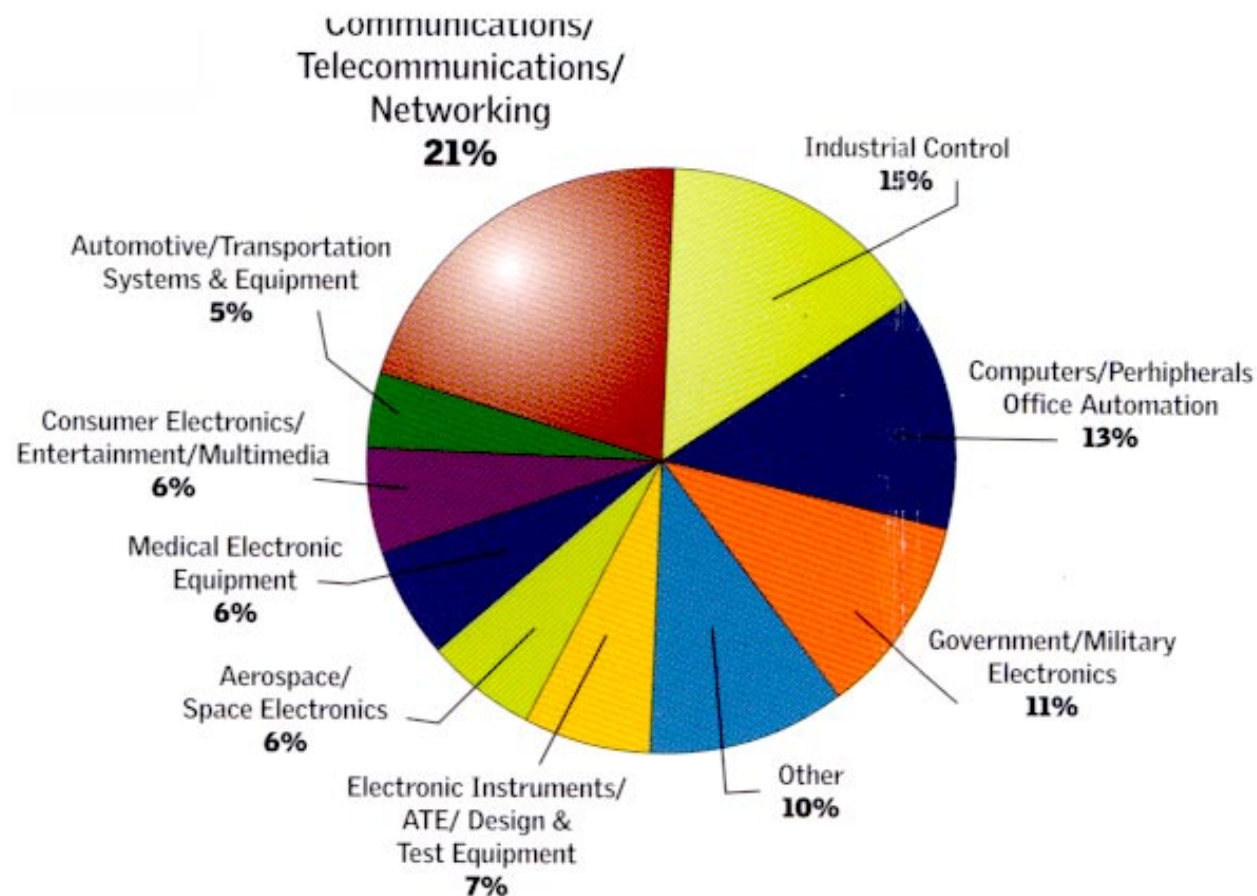


Approximated from EE Times, March 20, 1995
Source: The Information Architects

There Are Many Application Areas

Primary End Product of Embedded Subscribers

Source: *ESP* Dec. 1998 BPA Audit



Four General Embedded System Types

◆ General Computing

- Applications similar to desktop computing, but in an embedded package
- Video games, set-top boxes, wearable computers, automatic tellers

◆ Signal Processing

- Computations involving large data streams
- Radar, Sonar, video compression

◆ Communication & Networking

- Switching and information transmission
- Telephone system, Internet

◆ Control Systems

- Closed-loop feedback control of real-time system
- Vehicle engines, chemical processes, nuclear power, flight control



Types of Embedded System Functions

◆ Control Laws

- PID control
- Fuzzy logic, ...

◆ Sequencing logic

- Finite state machines
- Switching modes between control laws

◆ Signal processing

- Multimedia data compression
- Digital filtering

◆ Application-specific interfacing

- Buttons, bells, lights,...
- High-speed I/O

◆ Fault response

- Detection & reconfiguration
- Diagnosis



Distinctive Embedded System Attributes

- ◆ **Reactive: computations occur in response to external events**
 - Periodic events (*e.g.*, rotating machinery and control loops)
 - Aperiodic events (*e.g.*, button closures)

- ◆ **Real Time: correctness is partially a function of time**
 - Hard real time
 - Absolute deadline, beyond which answer is useless
 - (May include minimum time as well as maximum time)
 - Soft real time
 - Approximate deadline
 - Utility of answer degrades with time difference from deadline
 - In general Real Time \neq “Real Fast”



Typical Embedded System Constraints

◆ Small Size, Low Weight

- Hand-held electronics
- Transportation applications -- weight costs money

◆ Low Power

- Battery power for 8+ hours (laptops often last only 2 hours)
- Limited cooling may limit power even if AC power available

◆ Harsh environment

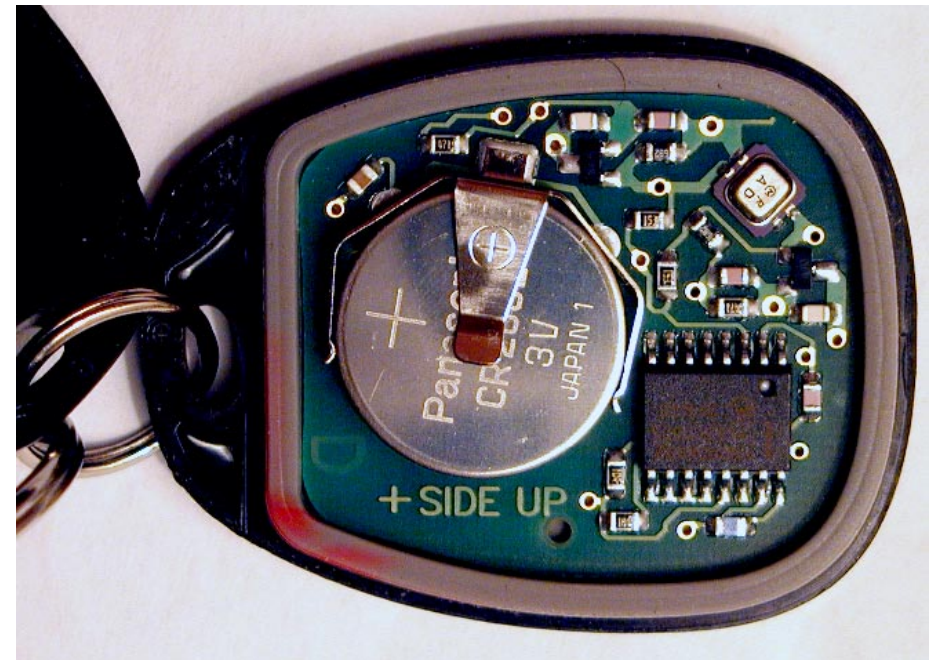
- Power fluctuations, RF interference, lightning
- Heat, vibration, shock
- Water, corrosion, physical abuse

◆ Safety-critical operation

- Must function correctly
- Must *not* function *incorrectly*

◆ Extreme cost sensitivity

- \$.05 adds up over 1,000,000 units



Embedded System Design World-View

◆ A complex set of tradeoffs

- Optimize for more than just speed
- Consider more than just the computer
- Take into account more than just initial product design

Multi-Objective

- Dependability
- Affordability
- Safety
- Security
- Scalability
- Timeliness



Multi-Discipline

- Electronic Hardware
- Software
- Mechanical Hardware
- Control Algorithms
- Humans
- Society/Institutions



Life Cycle

- Requirements
- Design
- Manufacturing
- Deployment
- Logistics
- Retirement

Mission-Critical Applications Require Robustness

- ◆ **June, 1996 loss of inaugural flight**
 - Lost \$400 million scientific payload (the rocket was extra)
- ◆ **Efforts to reduce system costs led to the failure**
 - Re-use of Inertial Reference System software from Ariane 4
 - Improperly handled exception caused by variable overflow during new flight profile (that wasn't simulated because of cost/schedule)
 - 64-bit float converted to 16-bit int assumed not to overflow
 - Exception caused dual hardware shutdown (because it was assumed software doesn't fail)
- ◆ **What really happened here?**
 - The narrow view: it was a software bug -- fix it
 - The broad view: the loss was caused by a lack of system robustness in an exceptional (unanticipated) situation
- ◆ **Many embedded systems must be *robust***



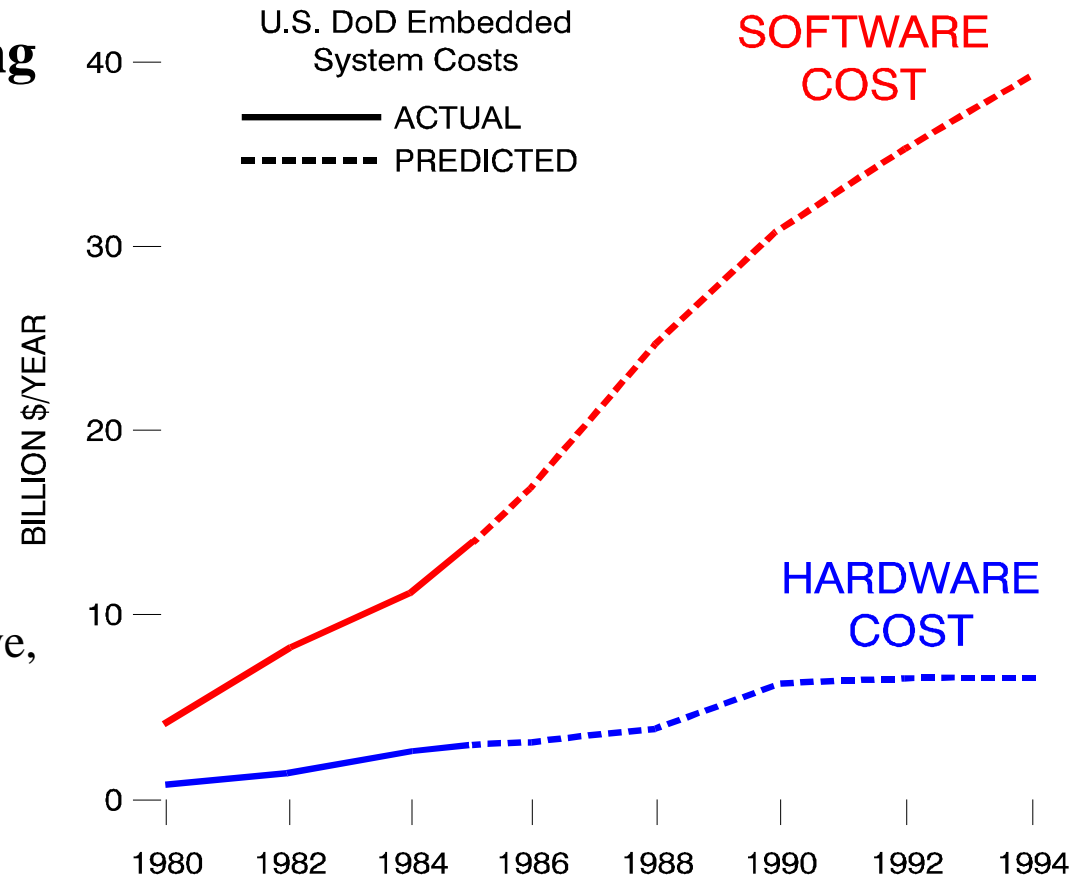
Software Drives Designs

◆ Hardware is mostly a recurring cost

- Cost proportional to number of units manufactured

◆ Software is a “one-time” non-recurring engineering design cost (NRE)

- Paid for “only once”
 - But bug fixes may be expensive, or impossible
- Cost is related to complexity & number of functions
- Market pressures lead to feature creep
- **SOFTWARE Is Not FREE!!!!**

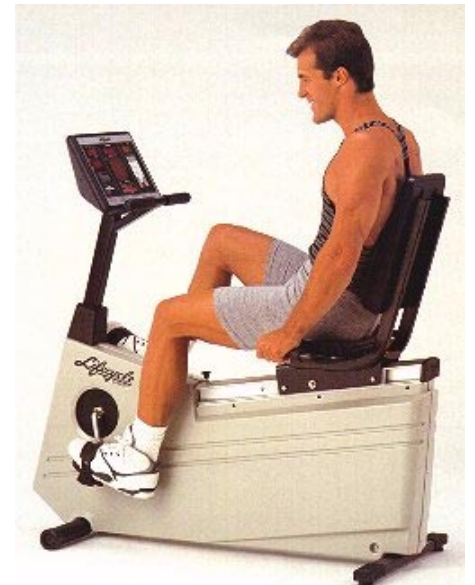


Source: *Software Requirements: objects, functions, states*; Davis, 1993.

Life-Cycle Concerns Figure Prominently

- ◆ **“Let’s use a CAD system to re-synthesize designs for cost optimization”**
 - Automatically use whatever components are cheap that month
 - Would permit quick responses to bids for new variants
 - Track record of working fine for PC motherboards

- ◆ **Why wouldn’t it work for an automotive application?**
 - Embedded system had more analog than digital -- mostly digital synthesis tool
 - Cost of re-certification for safety, FCC, warranty repair rate
 - Design optimized for running power, not idle power
 - Car batteries must last a month in a parking lot
 - Parts cost didn’t take into account life-cycle concerns
 - Price breaks for large quantities
 - Inventory, spares, end-of-life buy costs
 - Tool didn’t put designs on a single sheet of paper
 - Archive system paper-based -- how else do you read 20-year-old files?



Generic Embedded System Designer Skill Set

◆ **Appreciation for multi-disciplinary nature of design**

- System skills; system = HW + SW + ...
- Understanding of engineering beyond digital logic
- Ability to take a project from specification through production

◆ **Communication & teamwork skills**

- Work with other disciplines, manufacturing, marketing
- Work with customers to understand the real problem being solved
- Make a good presentation; even better -- write “trade rag” articles

◆ **And, by the way, technical skills too...**

- Low level: Microcontrollers, FPGA/ASIC, assembly language, A/D, D/A
- High level: Object-oriented Design, C/C++, Real Time Operating Systems, Critical System design
- Meta level: Creative solutions to highly constrained problems
- Likely in the future: Unified Modeling Language, embedded networks
- Uncertain future: Java, Windows CE

Review

◆ What is an embedded system?

- More than just a computer -- it's a system

◆ What makes embedded systems different?

- Many sets of constraints on designs
- Four general types:
 - General Purpose
 - Signal Processing
 - Communications
 - Control (*distributed control is focus of this course*)

◆ What embedded system designers need to know

- **Multi-objective:** cost, dependability, performance, *etc.*
- **Multi-discipline:** hardware, software, electromechanical, *etc.*
- **Life cycle:** specification, design, prototyping, deployment, support, retirement
- **Critical systems:** would you trust your own life to your product?

◆ Next Lecture: Embedded/Real Time Fundamentals