

B2: Smart Wardrobe

Problem Area:

- Picking the right outfit can be a difficult task
 - Difficult and time consuming to test outfit combinations manually
 - Hard to visualize how new articles of clothing will add to a wardrobe
 - Outfits need to account for day to day situations
- As wardrobes get bigger, they become more difficult to manage
 - Difficult and time consuming to find articles manually

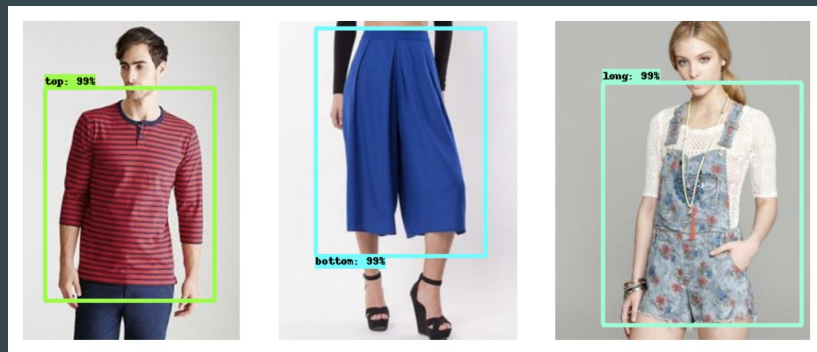
Use case

- **Outfit Visualizer (software)**
 - Recognizes client's clothing articles and finds matching/similar outfits online
 - Client can pick specific clothing articles (pants, shirt, or jacket) for the visualizer to search on
 - Other basic filters like color, type, temperature, etc.
- **iButler (hardware)**
 - Can automatically retrieve clothing articles specified via simple user interface
 - Can automatically store clothing articles



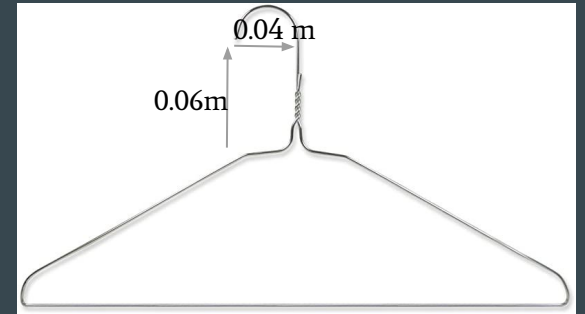
Software Requirements

- Clothing Matching
 - S1. Can find x amount of trending outfit photos that match user-given specifications
 - S2. Continuously adds new outfit photos as new ones are posted online
- Clothing Recognition
 - S3. Using the photos of outfits it can determine pants, shirts, and jackets
 - S4. Identifies color and variation of clothing, like jeans or shorts
 - S5. Maintain a minimum of x% accuracy in identifying clothes
- Runtime
 - S6. Software should be able to execute operations within a few seconds



Hardware Requirements

- Horizontal Movement
 - H1. Move to the designated coordinates within $\pm 0.02\text{m}$
- Vertical Movement (grabbing and placing the clothes)
 - H2. Vertical Margin of error within $\pm 0.03\text{m}$
- Retrieval Speed
 - H3. Retrieve/store clothing articles within 10 seconds
- Clothing Requirements
 - C4. Clothing articles are placed 10 cm apart
 - C5. Clothes weigh less than 2 kg



Technical Challenges (Software)

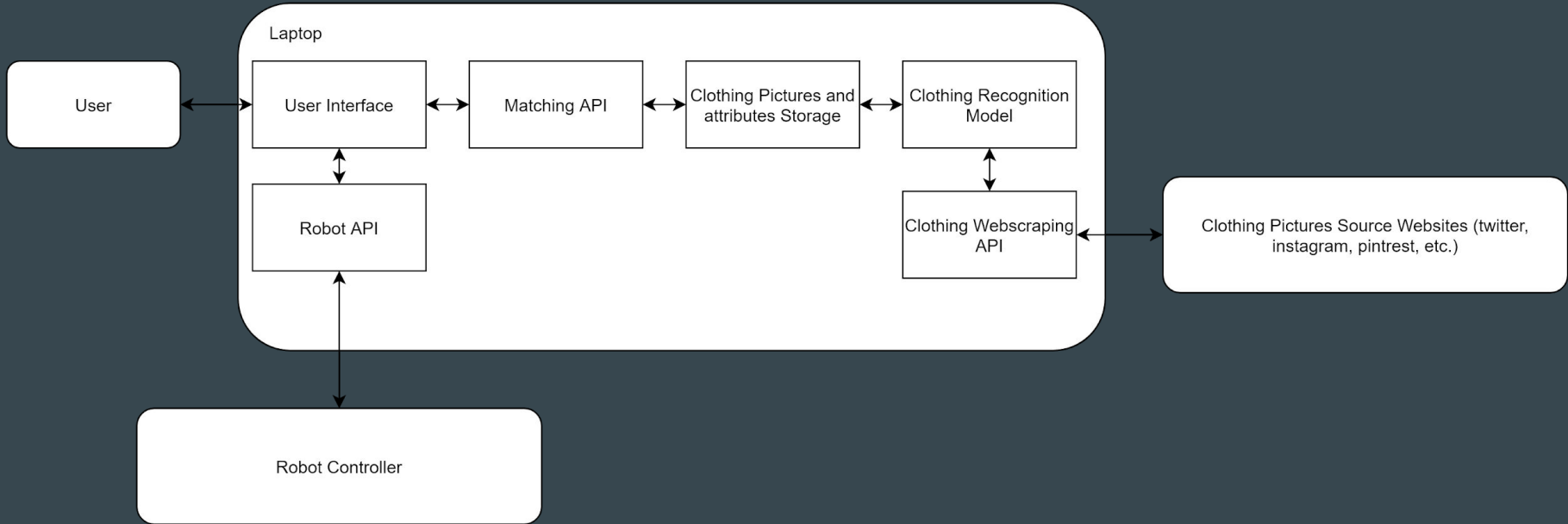
- Clothing Matching
 - Runtime: Could be difficult to find the amount requirement within runtime requirement if outfit is difficult to find online
 - RM: mitigate latency with good caching and precomputing
- Clothing Recognition
 - Model must correctly label outfits with high precision
 - Many varying attributes like lighting, pose, and occlusion could be a challenge for the model
 - RM: use a predefined dataset with outliers removed if necessary

RM == Risk Mitigation

Technical Challenges (Hardware)

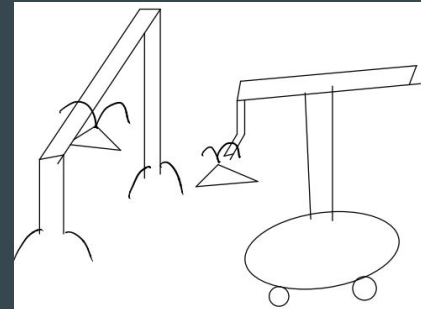
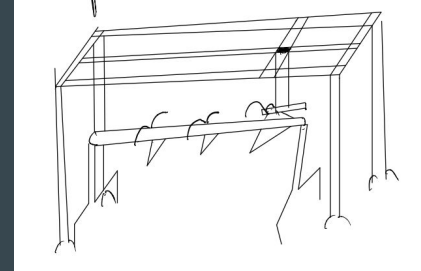
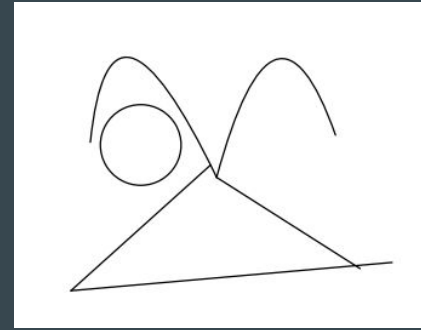
- Accuracy
 - The clothing hanger hook has a small surface area so we have to be accurate
 - RM: good hardware design with minimal margins of error
 - Have to ensure the right clothing article is chosen
 - RM: Correct calibration and error correction in software
- Weight
 - Robot arm should be able to handle weight up to 2kg
 - RM: sturdy motors/actuators that won't malfunction when its carrying clothes
 - Consistency in movement speed and precision regardless of having clothes or not
 - RM: Not too sure what this will be

Solution Approach (Software)



Solution Approach (Hardware)

- Fixed rail device (Claw Machine)
 - Sliding claw machine with 3 degrees of motion (x, y, z)
 - Smaller margin of error compared to modular approach
 - Requires building rail system that could be difficult to implement
- Modular device (Roomba)
 - Roomba provides 2 degrees of motion (x, y)
 - Third degree of motion from linear actuator
 - Easier to implement in terms of hardware
 - Requires error correction software
 - Higher margin of error



Testing, Verification, and Metrics (Software)

- Clothing Matching
 - S1. Automated test cases that uses exercises matching API to reach targeted amount of outfit photos
 - S2. Ensure photos are from online source (attach URL)
- Clothing Recognition
 - S3/4/5. DeepFashion dataset contains over 800,000 labeled fashion images that we can use for both training and testing
 - Because it already has the labels we want, we can use it to run validation testing
- Runtime
 - Benchmark tests for varying predefined and random test cases

Testing, Verification, and Metrics (Hardware)

- Horizontal Movement
 - Can move on the x and y axis consistently to .02 m of the location
 - If we can maintain this accuracy in 19 out of 20 trials
 - Test specifications:
 - Designated locations are randomly selected out of a fixed grid system
 - Tape defining the margin of error can be used to quickly identify if a test passes or not
- Vertical Movement
 - Can move on the vertical axis to within .03 m of the location
 - If we can maintain this accuracy in 19 out of 20 trials
 - Similar test specifications to horizontal movement
- Load Testing
 - Adding load to our horizontal and vertical movement tests
 - Testing with 0 kg load, 1 kg load, and 2 kg load

Tasks and Division of Labor

- Hardware
 - HT1. Finalize design of our hardware + controller (3 days, Team)
 - HT2. Order necessary parts online (1 day, Team)
 - HT3. 3D Printing / laser cutting (depending on our method) (3 weeks, Fred)
 - HT4. Assembling the hardware (1 week, Sung Hyun)
 - HT5. Hardware drivers (4 weeks, Henry, Sung Hyun)
 - HT6. Hardware debugging and testing (3 weeks, Sung Hyun)
- Software
 - ST1. Web scraping for pictures (1 week, Fred)
 - ST2. Model to identify clothes (3 weeks, Henry)
 - ST3. Hardware integration (1 week, Henry)
 - ST4. Matching API (1 week, Sung Hyun)
 - ST5. User interface (1 week, Sung Hyun)
 - ST6. Software debugging and testing (2 weeks, Fred)

