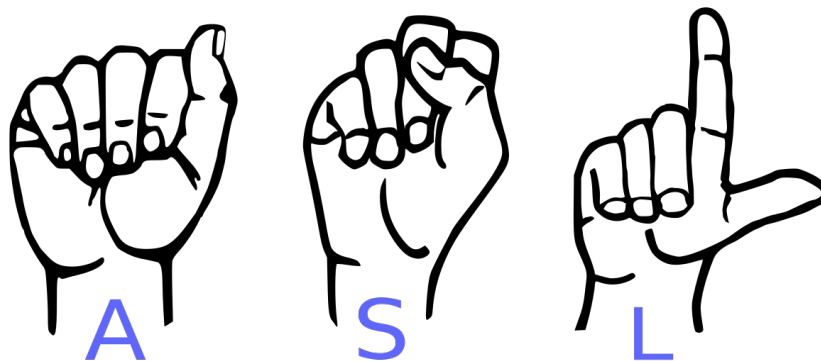


# Gesture Glove

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# Overview

- Motivation: to help people who sign ASL communicate with others who do not understand ASL
- Gesture-sensing gloves
  - Thumbs up
  - Thumbs down
  - Love
  - Peace
  - Stop



# Use Case

- Recognizes motion and gesture
- Applications & problem areas
  - sign languages
  - VR/AR experience
  - HCI
  - Assess rehabilitation
- Area: circuits, software systems



# Requirements

- Accuracy - 90%
- Latency - 100 ms
- Frequency - 0.5 s per gesture
- How long should users hold each gesture? - 250 ms
- Craftsmanship - <250g



# Technical Challenges

- High variance in data from sensors
- Data collection
- Circuit design
- Trade-offs



# High Variance From Data Sensors + Data Collection

- Calibrate sensors
  - Ensure all sensors are working accurately
- Combining streams of different data

```
Adafruit LSM6DSOX test!
```

```
LSM6DSOX Found!
```

```
Accelerometer range set to: +-2G
```

```
Gyro range set to: 250 degrees/s
```

```
Accelerometer data rate set to: 104 Hz
```

```
Gyro data rate set to: 104 Hz
```

```
Temperature 23.87 deg C
```

```
Accel X: 0.57 Y: -0.38
```

```
Gyro X: 3.16 Y: -5.15
```

```
Z: 39.52 m/s^2
```

```
Z: -27.93 degrees/s
```

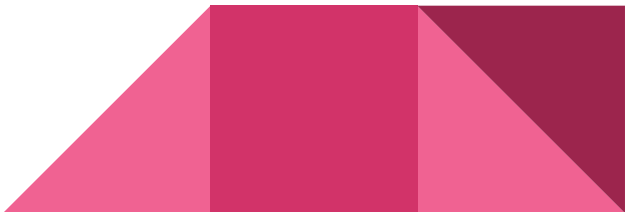
```
Temperature 23.07 deg C
```

```
Accel X: 0.15 Y: -0.10
```

```
Gyro X: 1.23 Y: 0.11
```

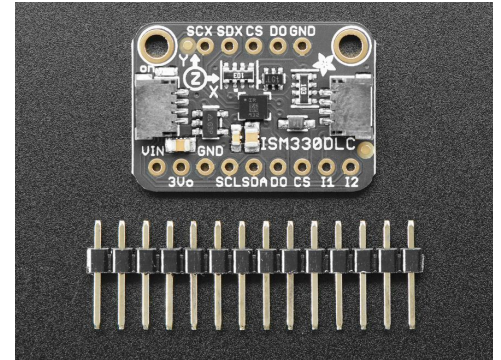
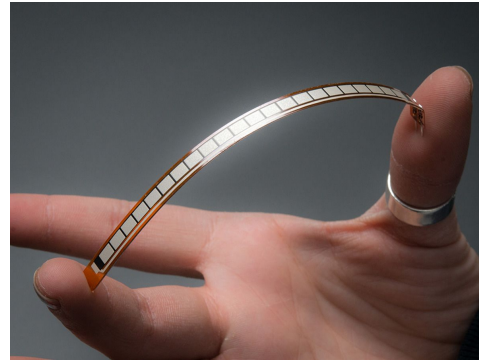
```
Z: 9.89 m/s^2
```

```
Z: -0.51 degrees/s
```



# Circuit Design

- Need to minimize wiring and create a compact circuit
  - The glove should be lightweight
  - Movements should be unhindered by wiring



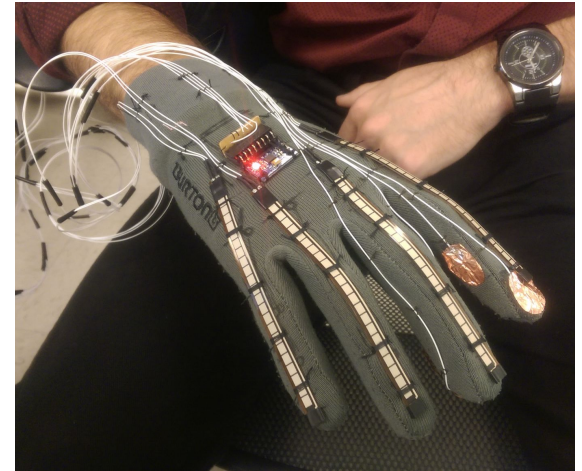
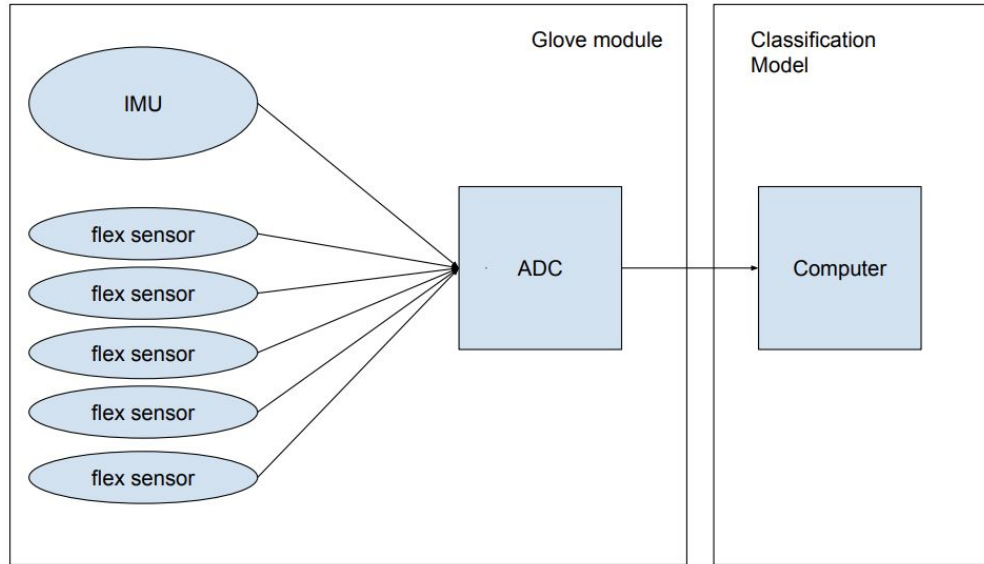
# Trade-offs

- Number of classes vs. accuracy
- Number of sensors (usability) vs. accuracy
- Sampling rate vs. latency





# Solution Approach



# Testing, Verification and Metrics

- Accuracy
- Latency
- Frequency
- How long should users hold each gesture?
- Craftsmanship



# Tasks and Division of Labor

- **Glove**
  - Research and buy flex sensors and IMU
  - Fit glove with sensors
  - Test sensor data collection
- **Classification Model**
  - Testing out different models
  - Collect data from glove sensors
  - Train model
  - Test model
  - Make necessary adjustments



# Schedule

	9/13	9/20	9/27	10/4	10/11	10/18	10/25	11/1	11/8	11/15	11/22	11/28
Make proposal presentation + website												
Order parts (arrive by 9/27 - expedite shipping if necessary)												
Do proposal presentation												
Attach flex sensors												
Test that we get consistent data from flex sensors with each gester												
Prepare design review												
Do design presentation												
Design report												
Attach IMU												
Test that we get consistent data from IMU with each gesture												
Determine ML Model												
Collect data (for training and testing)												
Train model												
Test model ourselves												
Get other people to test (gather survey data)												
Make adjustments as needed from feedback												
Make final presentation												
Final presentation												
Final report												

everyone
sophia
stephanie
rachel

