

2/14/24

# RECITATION 4B

SPECIAL LSI SYSTEMS, SAMPLING,  
CHANGE OF SAMPLING RATE

## DOWN SAMPLING BY $M$

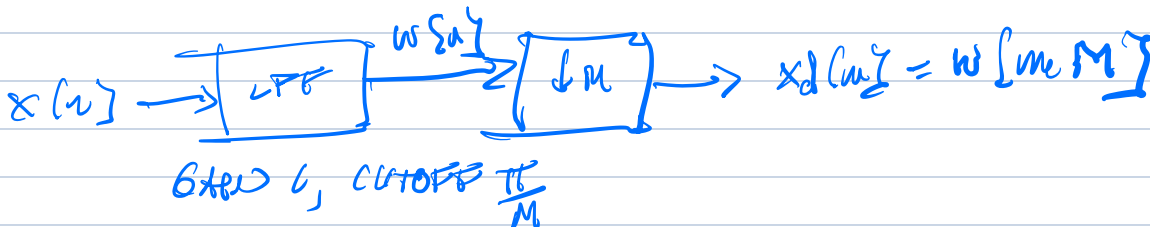


$$s_s[n] = \begin{cases} 1, & n \in \mathbb{Z}M \\ 0, & \text{ELSE} \end{cases}$$

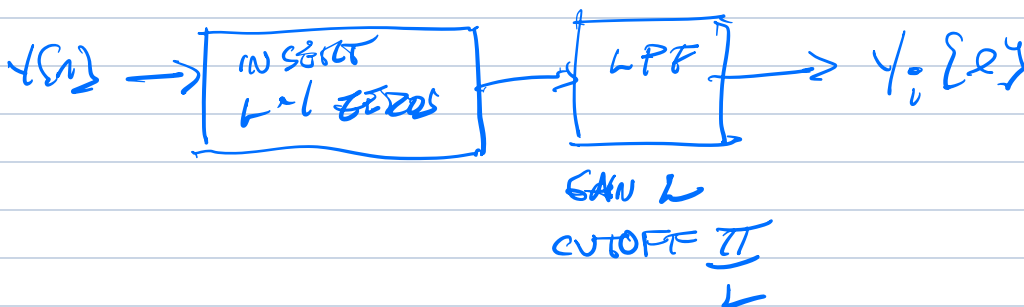
TO AVOID ALIASING  
REGIONS  $X_c(j\omega) = 0$

$$\frac{\pi}{M} < |\omega| < \pi$$

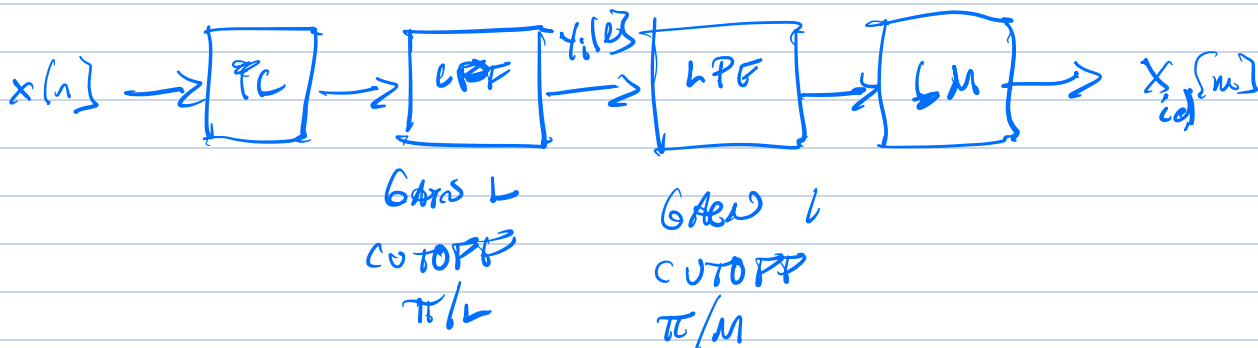
## PRACTICAL IMPLEMENTATION



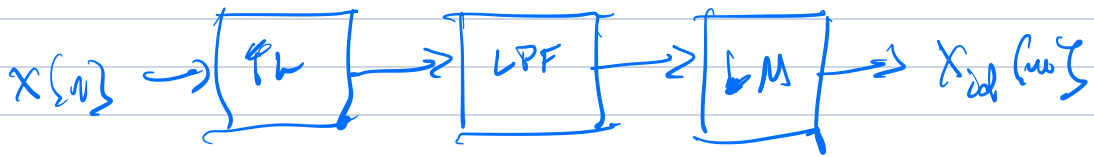
## INTERPOLATION BY $L$



## CHANGING RATE BY $L/M$



# MORE EFFICIENT IMPLEMENTATION



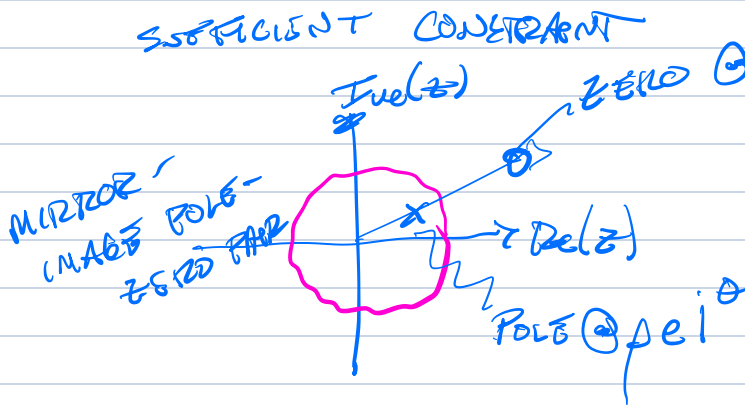
GAIN  $L$   
CUTOFF  $\omega_c \in (\frac{\pi}{L}, \frac{\pi}{M})$

## SPECIAL LTI SYSTEMS

ALL PASS SYSTEM

$$|H(e^{j\omega})| = \text{CONST.}$$

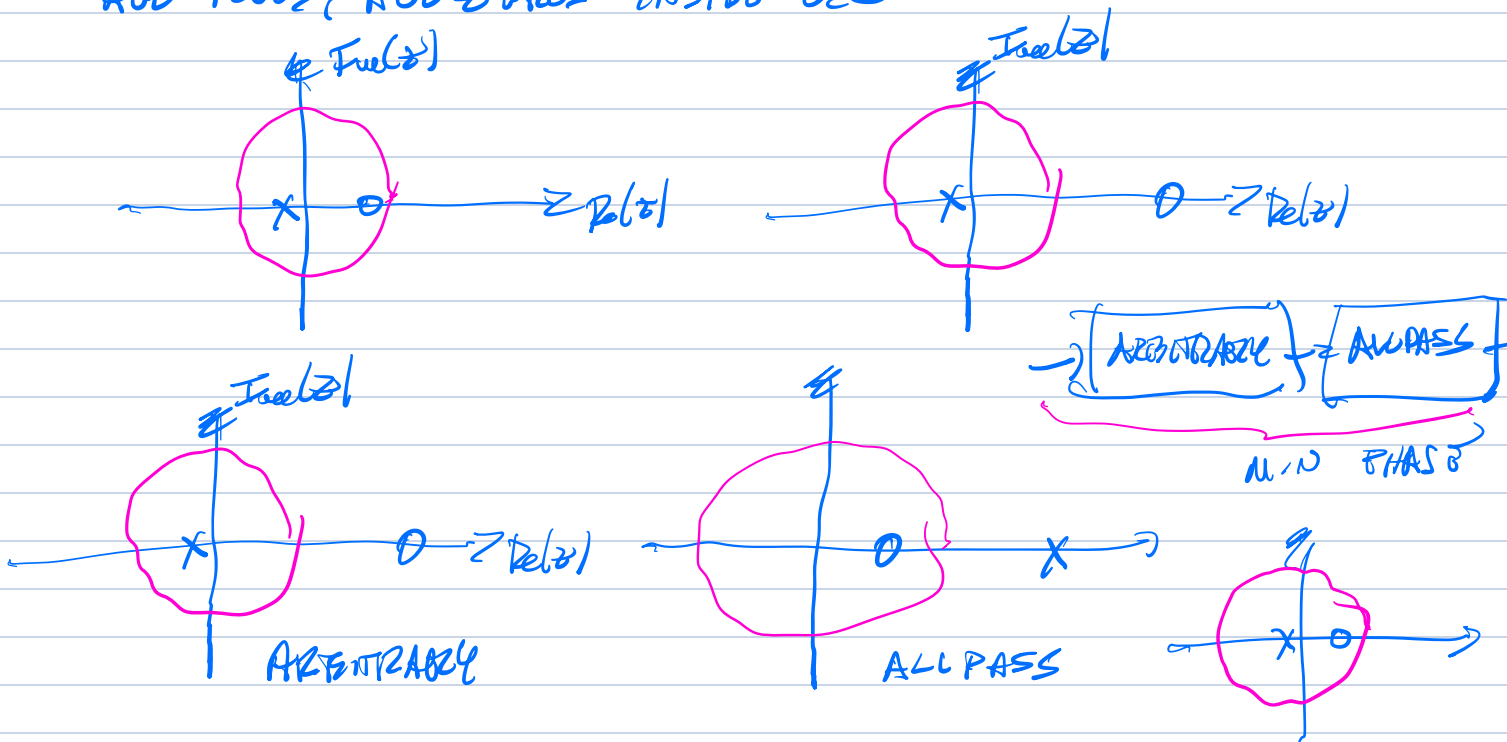
SUFFICIENT CONSTRAINT



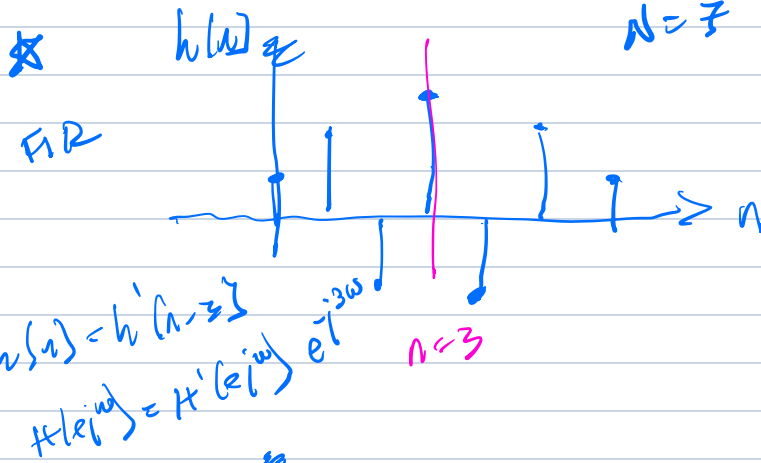
$$H(z) = \frac{z^{-L} p e^{j\theta}}{z^{-1} p e^{j\theta}}$$

## MINIMUM PHASE SYSTEM

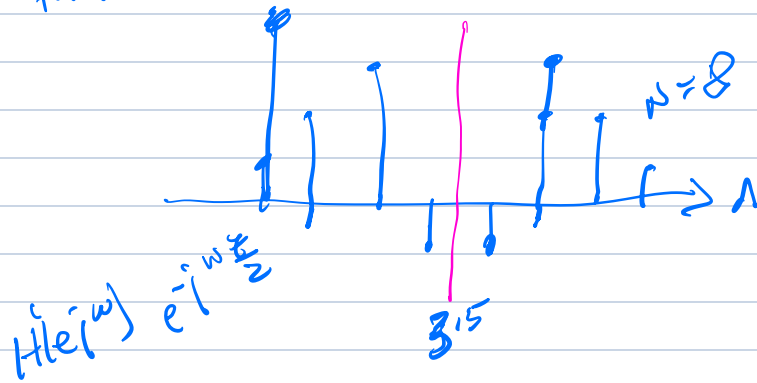
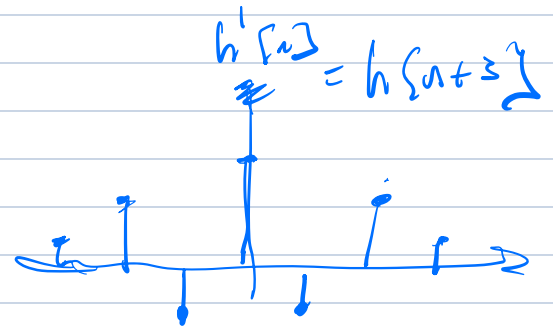
ALL POLES, ALL ZEROS INSIDE U.C.



# LINEAR PHASE SYSTEM



SYMMETRIC ABOUT  $\frac{N-1}{2} = 3$



SYMMETRIC ABOUT  $\frac{N-1}{2} = \frac{7}{2}$

("GENERALIZED LINEAR PHASE")

$$H(z) = 1 + 2z^{-1} - \frac{3}{2}z^{-2} + \frac{5}{2}z^{-3} - \frac{3}{2}z^{-4} + 2z^{-5} + z^{-6}$$

ZEROS

$$1 + 2z^{-1} - \frac{3}{2}z^{-2} + \frac{5}{2}z^{-3} - \frac{3}{2}z^{-4} + 2z^{-5} + z^{-6} = 0$$

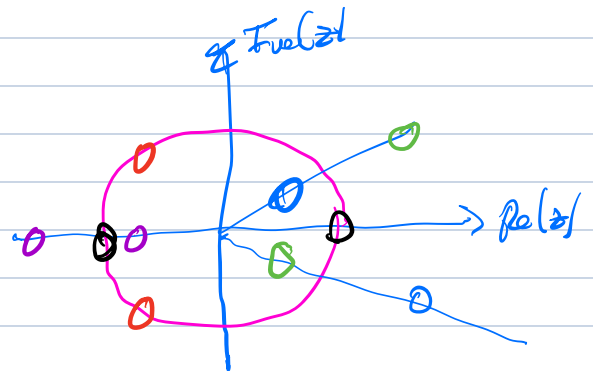
$$z^6 + 2z^5 - \frac{3}{2}z^4 + \frac{5}{2}z^3 - \frac{3}{2}z^2 + 2z + 1 = 0$$

IF  $z_0$  IS A ZERO OF  $H(z)$

$1/z_0$  WILL BE ZERO AS WELL

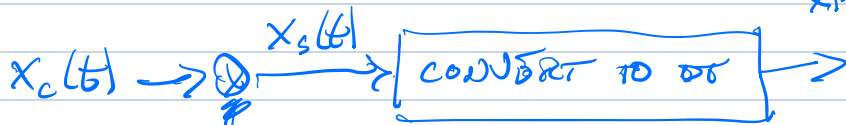
$$z_0 = \rho e^{j\theta}$$

$$\frac{1}{z_0} = \frac{1}{\rho e^{j\theta}} = \frac{1}{\rho} e^{-j\theta}$$

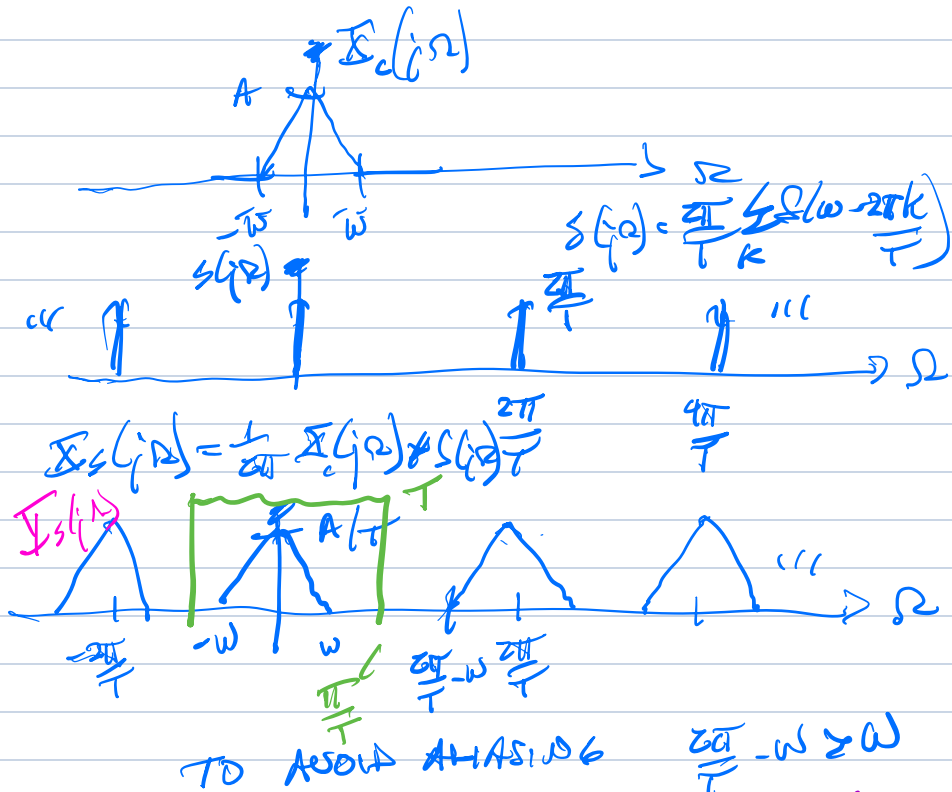
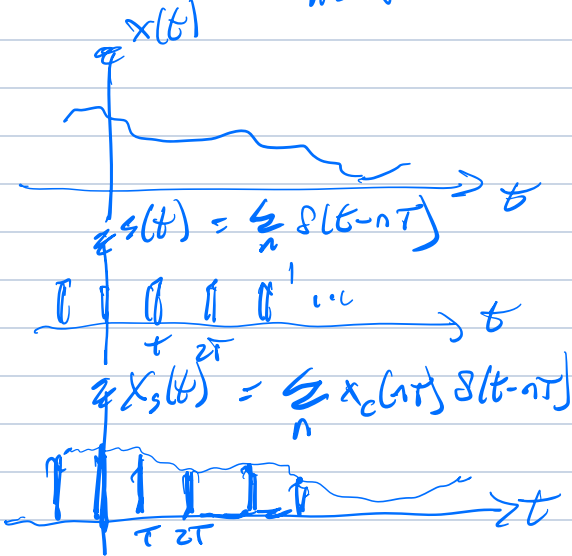
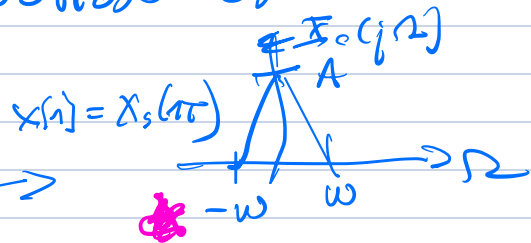


# SAMPLING + RECONSTRUCTION OF CT SIGNALS

C/D CONVERSION

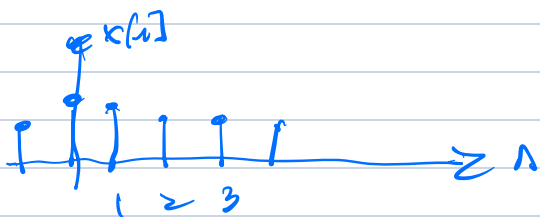


$$s(t) = \sum_{n=-\infty}^{\infty} \delta(t-nT)$$



TO AVOID ALIASING  $\frac{2\pi}{T} - \omega \geq \omega$

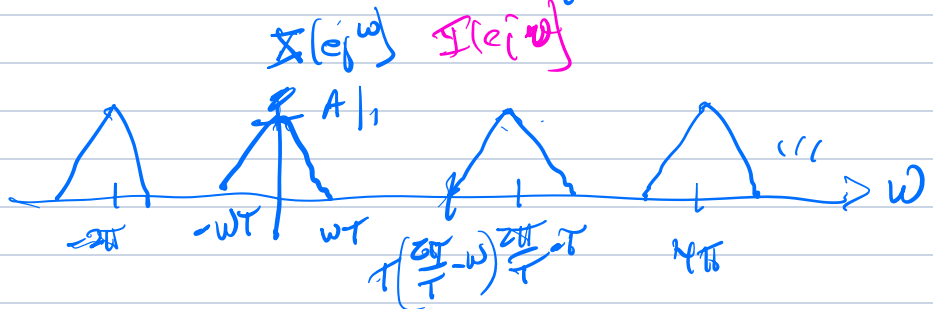
$\omega < \frac{\pi}{T}$



$$\omega = \Omega T$$

$$\Omega = \frac{\omega}{T}$$

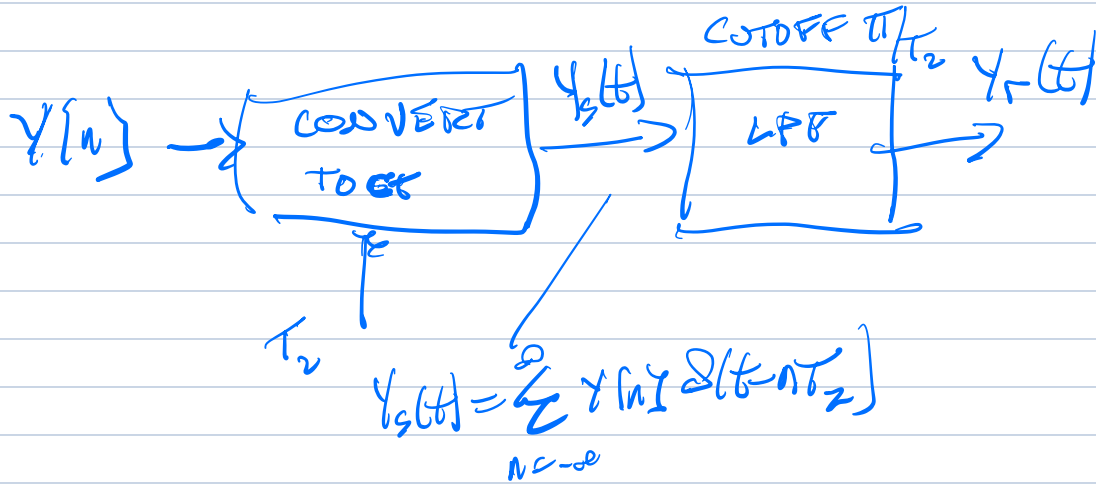
$$X(e^{j\omega}) = X_s(j\Omega) \Big|_{\Omega = \frac{\omega}{T}}$$



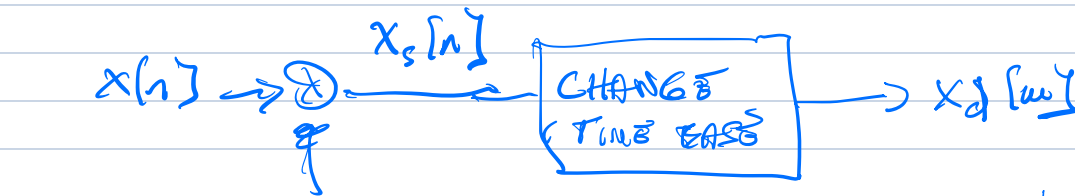
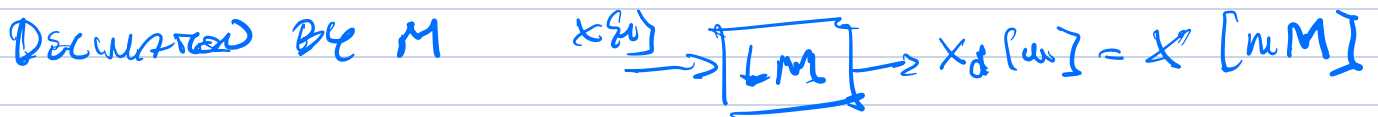
$$X_s(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - \frac{2\pi k}{T}))$$

$$X(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\frac{\omega}{T} - \frac{2\pi k}{T}))$$

# D/C CONVERSION



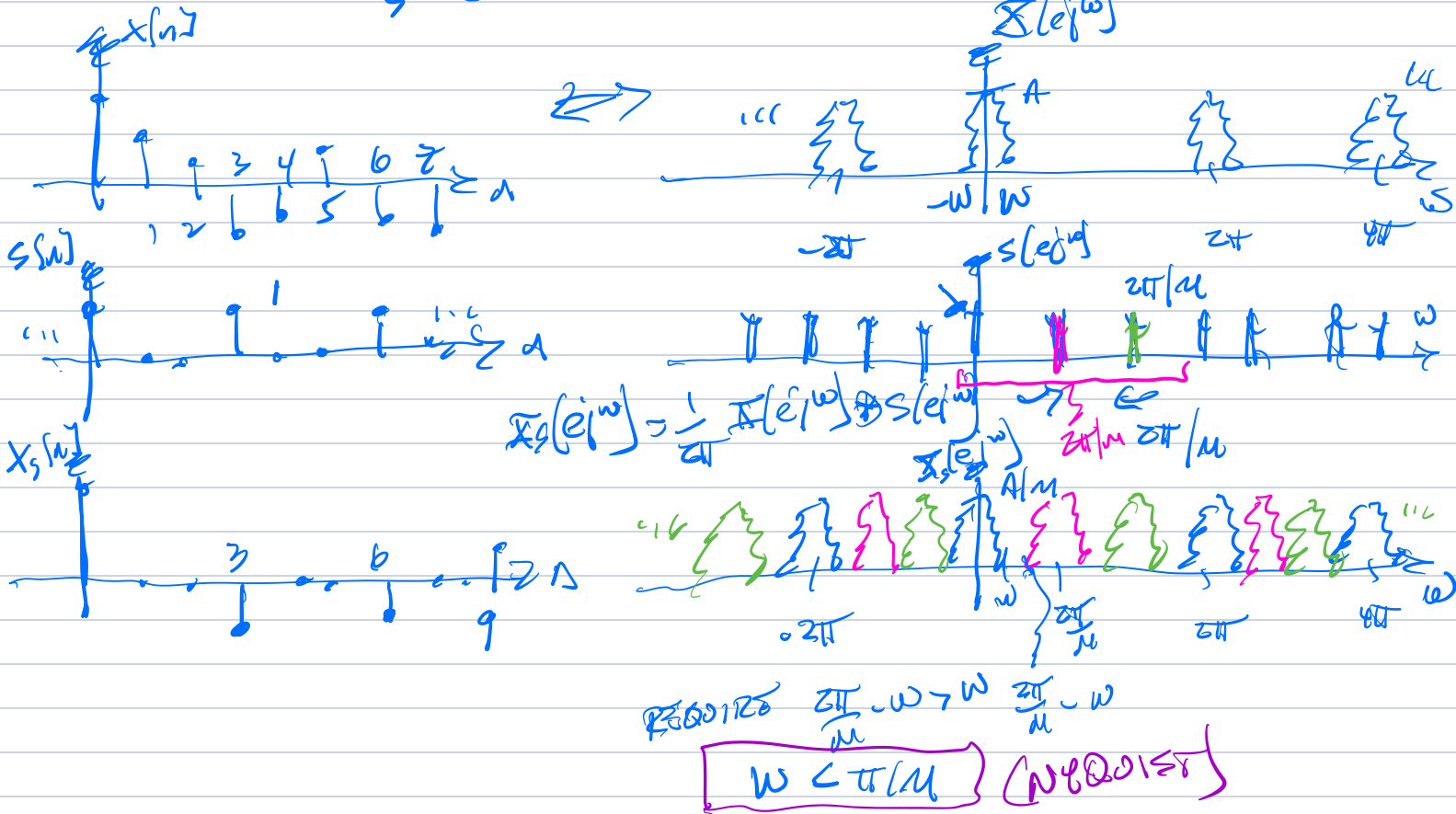
# DECIMATION & INTERPOLATION

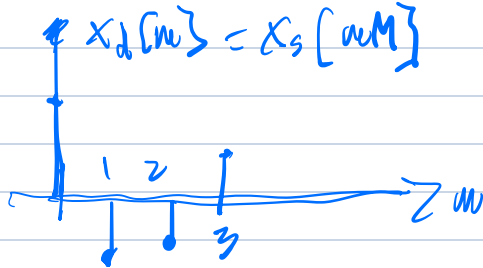


$M=3$

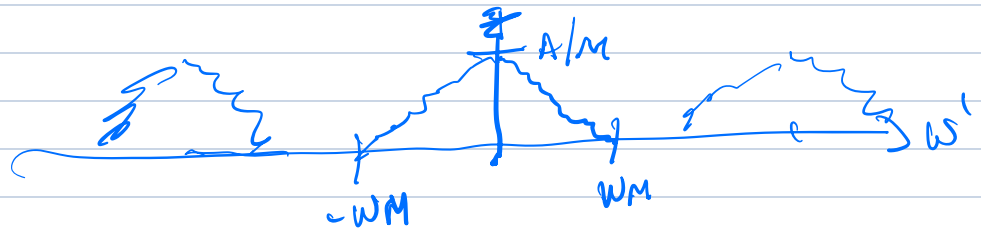
$$s[n] = \begin{cases} 1, & n = 0, M \\ 0, & \text{else} \end{cases}$$

$$|S(e^{j\omega})| = 0, \quad \omega < -\pi \text{ or } \omega > \pi$$

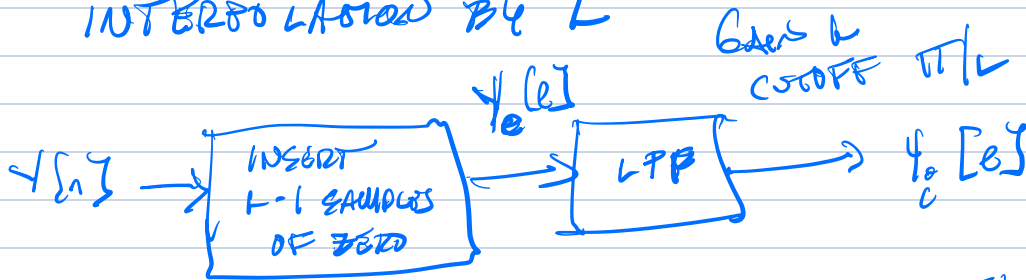




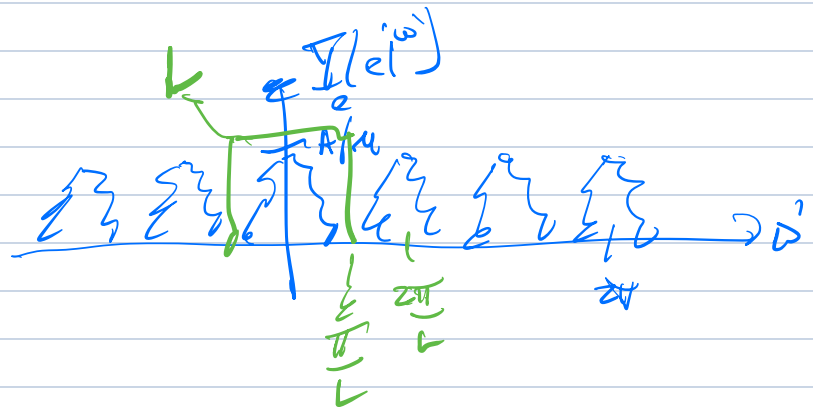
$X_d(e^{j\omega}) = X_s(e^{j\frac{\omega}{M}})$



INTERPOLATION BY L



$Y(e^{j\omega}) = Y(e^{j\omega'L})$



CONSIDER  $x(n) = \cos(0.4\pi n)$

DECIMATION BY  $M=4$

