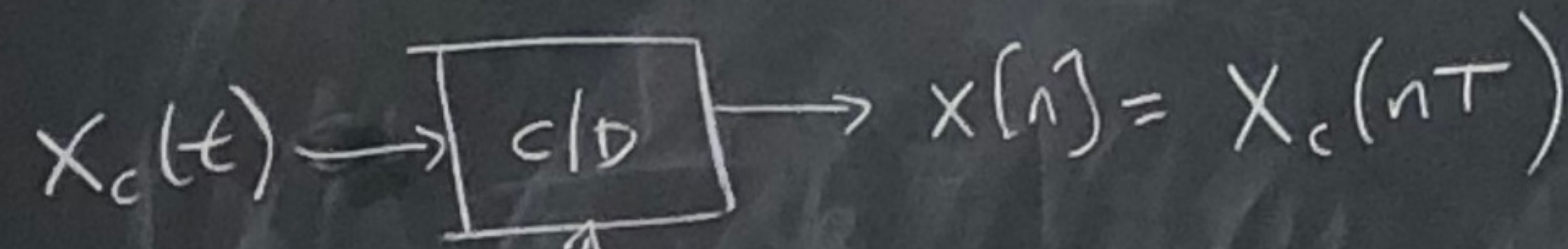
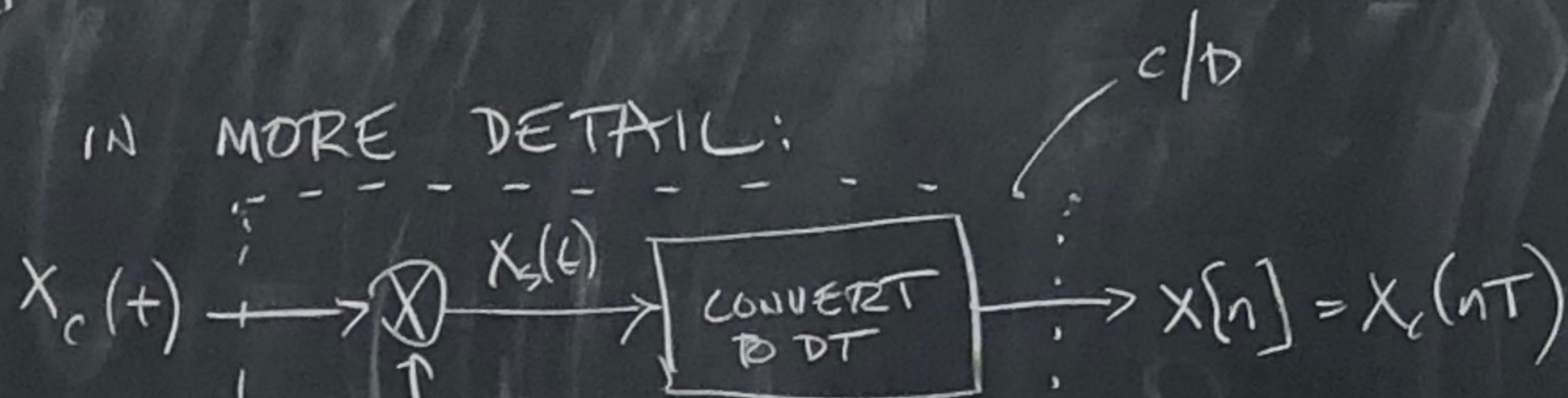


IDEAL
C/D CONVERSION



IN MORE DETAIL:



$$s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

$$X_s(t) = s(t) \cdot X_c(t)$$

$$X_s(j\Omega) = \frac{1}{2\pi} X_c(j\Omega) * S(j\Omega)$$

SAMPLING CT
SIGNALS

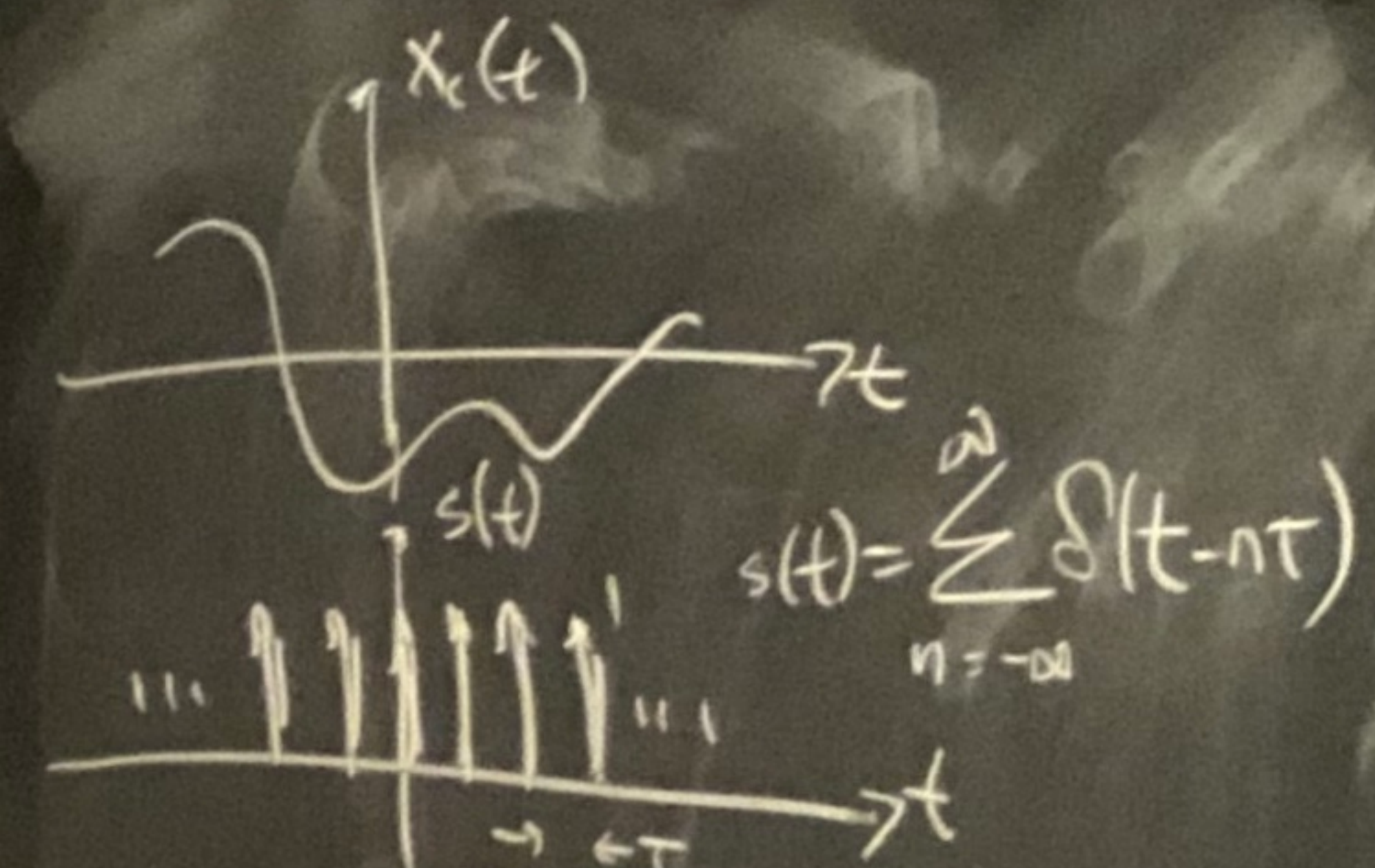
OS4P 4.0-4.5

CTFT $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\Omega) e^{j\Omega t} d\Omega$

$$X(j\Omega) = \int_{-\infty}^{\infty} x(t) e^{-j\Omega t} dt$$

DTFT $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega$

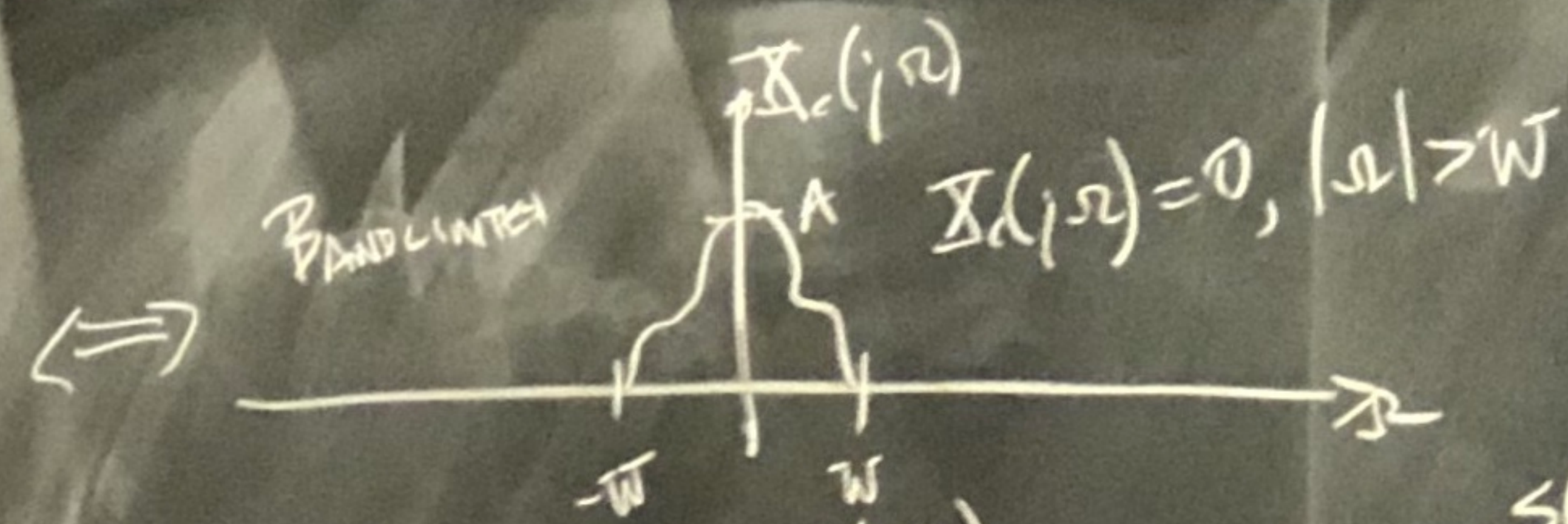
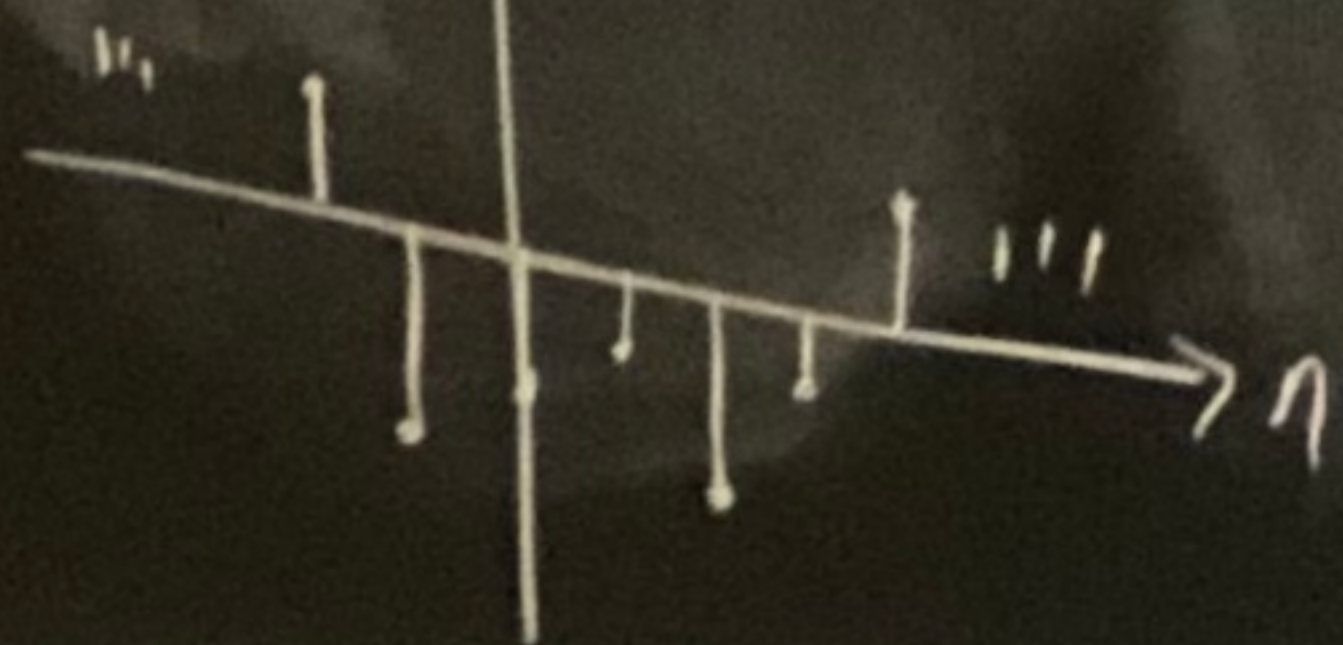
$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$



$$s(t) = \sum_{n=-\infty}^{\infty} \delta(t-nT)$$

$$x_s(t) = \sum_{n=-\infty}^{\infty} x_c(nT) \delta(t-nT)$$

$$x[n] = \sum_{l=-\infty}^{\infty} x_c(lT) \delta[n-l]$$



$$s(j\Omega) = \sum_{k=-\infty}^{\infty} \frac{2\pi}{T} \delta(\Omega - k \frac{2\pi}{T})$$

$$X_s(j\Omega) = \frac{1}{T} X_c(j\Omega) * S(j\Omega) = \sum_{k=-\infty}^{\infty} \frac{1}{T} X_c(j\Omega - k \frac{2\pi}{T})$$

$$\omega = \Omega T$$

$$X(e^{j\omega}) = \sum_{k=-\infty}^{\infty} \frac{1}{T} X_c(j\frac{\omega}{T} - k 2\pi)$$

$$\frac{2\pi}{T} = \Omega_0$$

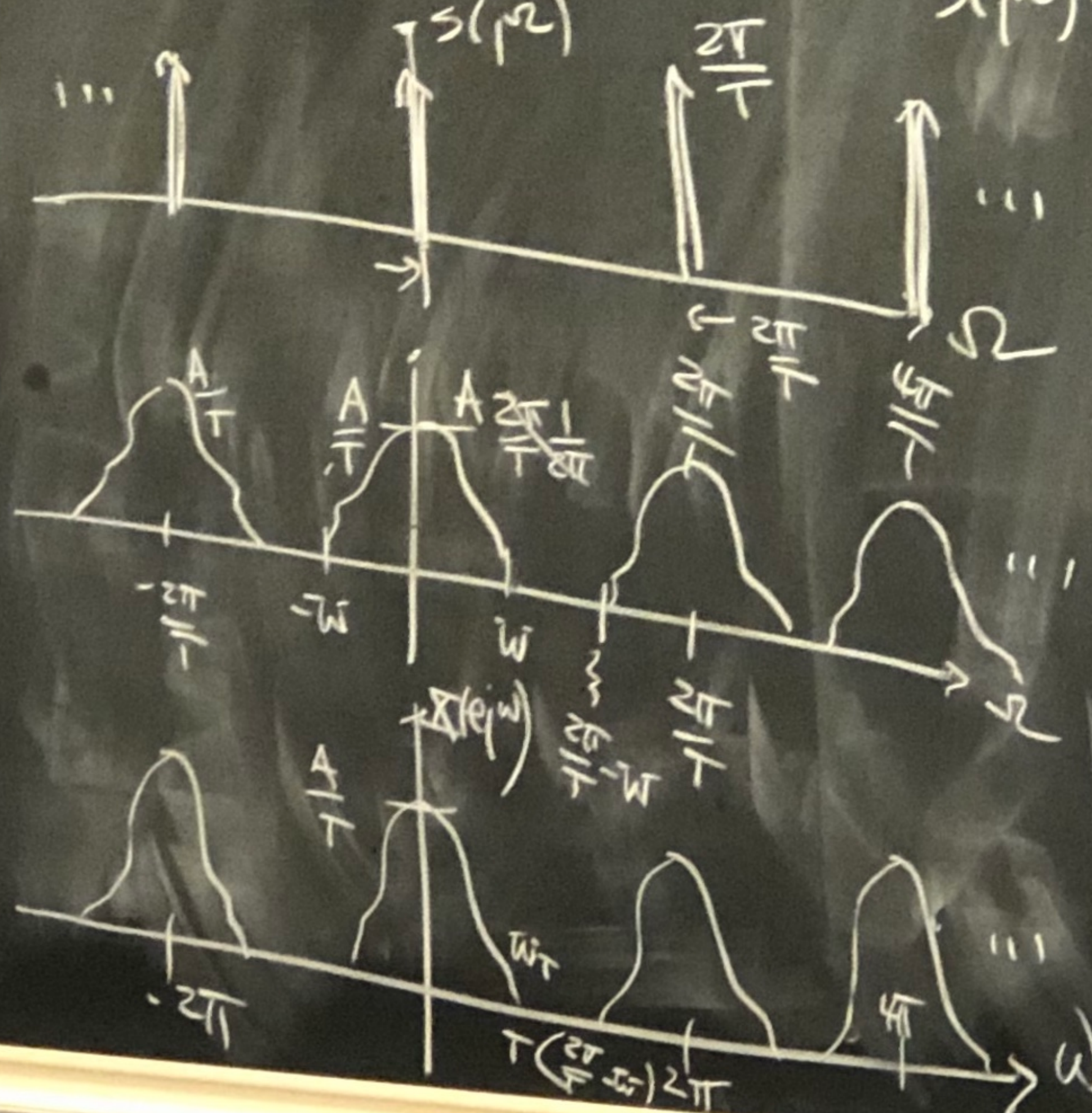
TO AVOID OVERLAP
NEED

$$W < \frac{2\pi}{T} - W$$

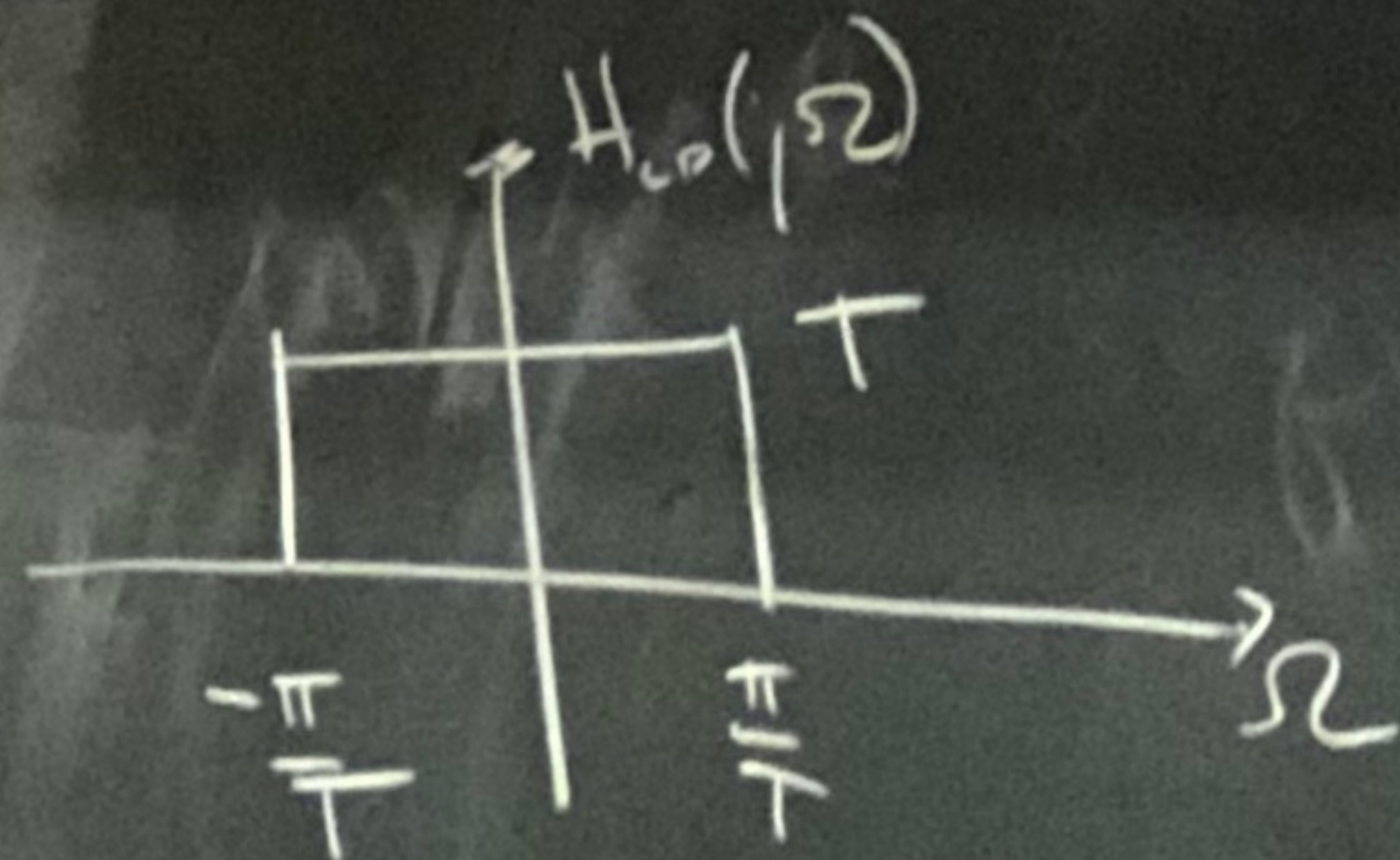
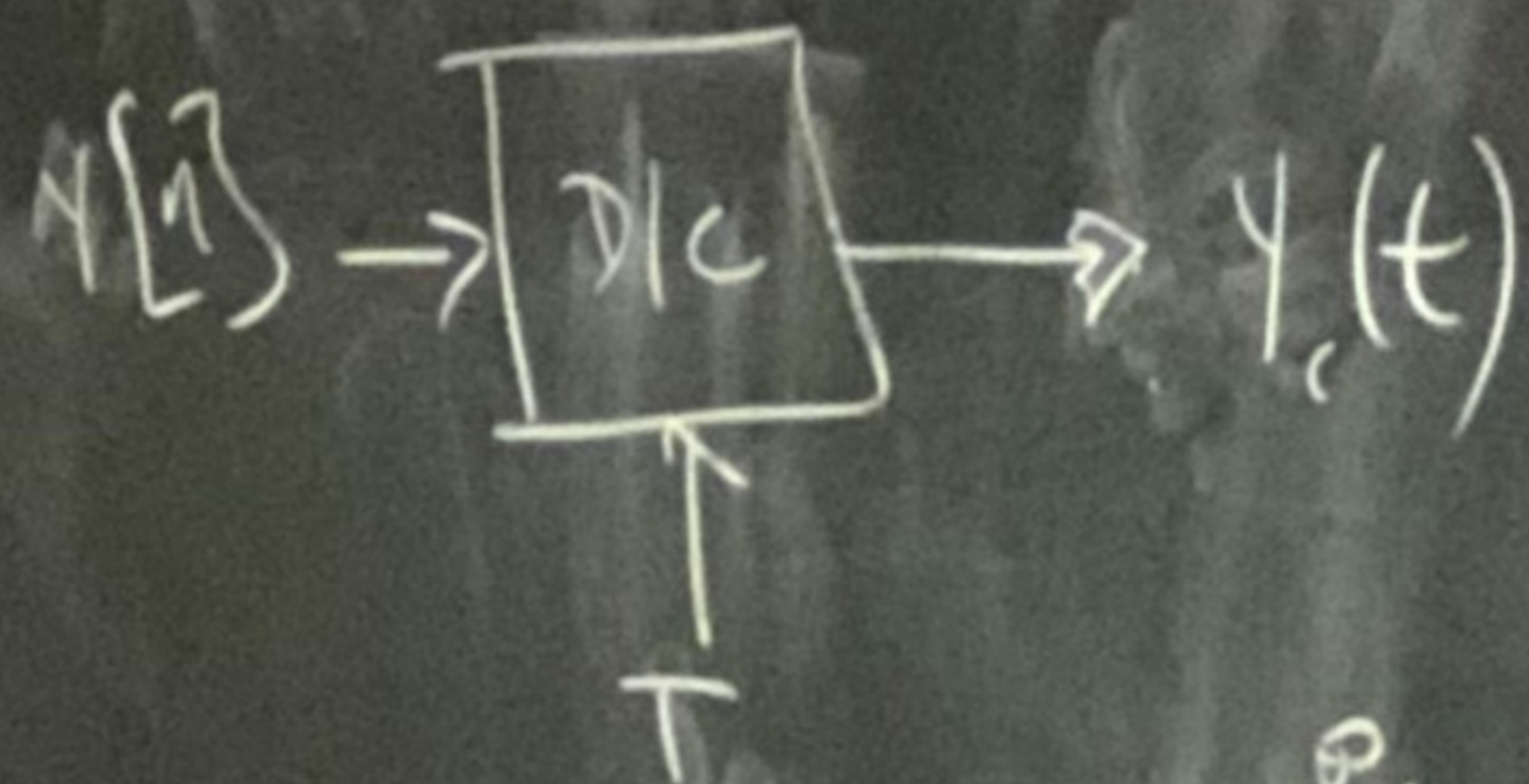
$$2W < \frac{2\pi}{T}$$

$$W < \frac{\pi}{T} = \frac{1}{2} \frac{2\pi}{T}$$

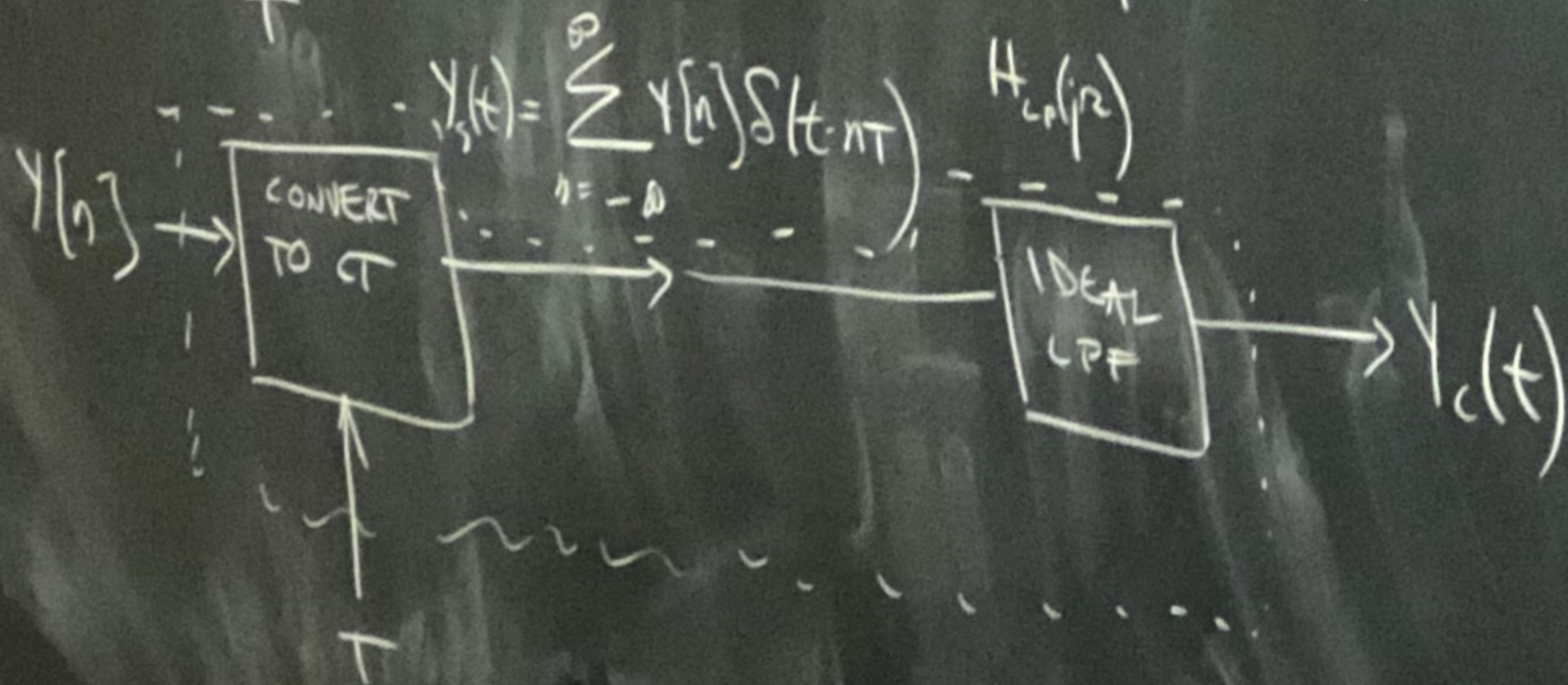
NYQUIST
CONSTRAINT



IDEAL D/C CONVERSION



$$H_{LP}(\omega) = \begin{cases} 1, & |\omega| \leq \pi \\ 0, & \text{ELSE} \end{cases}$$



COMPARING $X_s(j\Omega)$ with $X(e^{j\omega})$

$$X_s(j\Omega) = \int_{-\infty}^{\infty} x_s(t) e^{-j\Omega t} dt = \int_{-\infty}^{\infty} \underbrace{\sum_{n=-\infty}^{\infty} x_c(nT) \delta(t-nT)}_{x_s(t)} e^{-j\Omega t} dt$$

$$= \sum_{n=-\infty}^{\infty} x_c(nT) \underbrace{\int_{-\infty}^{\infty} \delta(t-nT) e^{-j\Omega t} dt}_{e^{-j\Omega nT}} = \sum_{n=-\infty}^{\infty} x_c(nT) e^{-j\Omega nT} = X_s(j\Omega)$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} \quad e^{j\Omega nT}$$

$$= \sum_{n=-\infty}^{\infty} x_c(nT) e^{-j\omega n} = X(e^{j\omega}) = X_s(j\Omega)$$

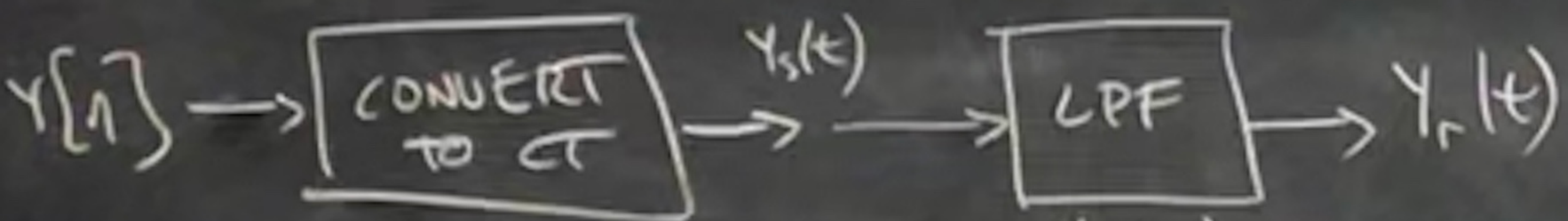
$$\boxed{\omega = \Omega T}$$

$$\Omega = \frac{\omega}{T}$$

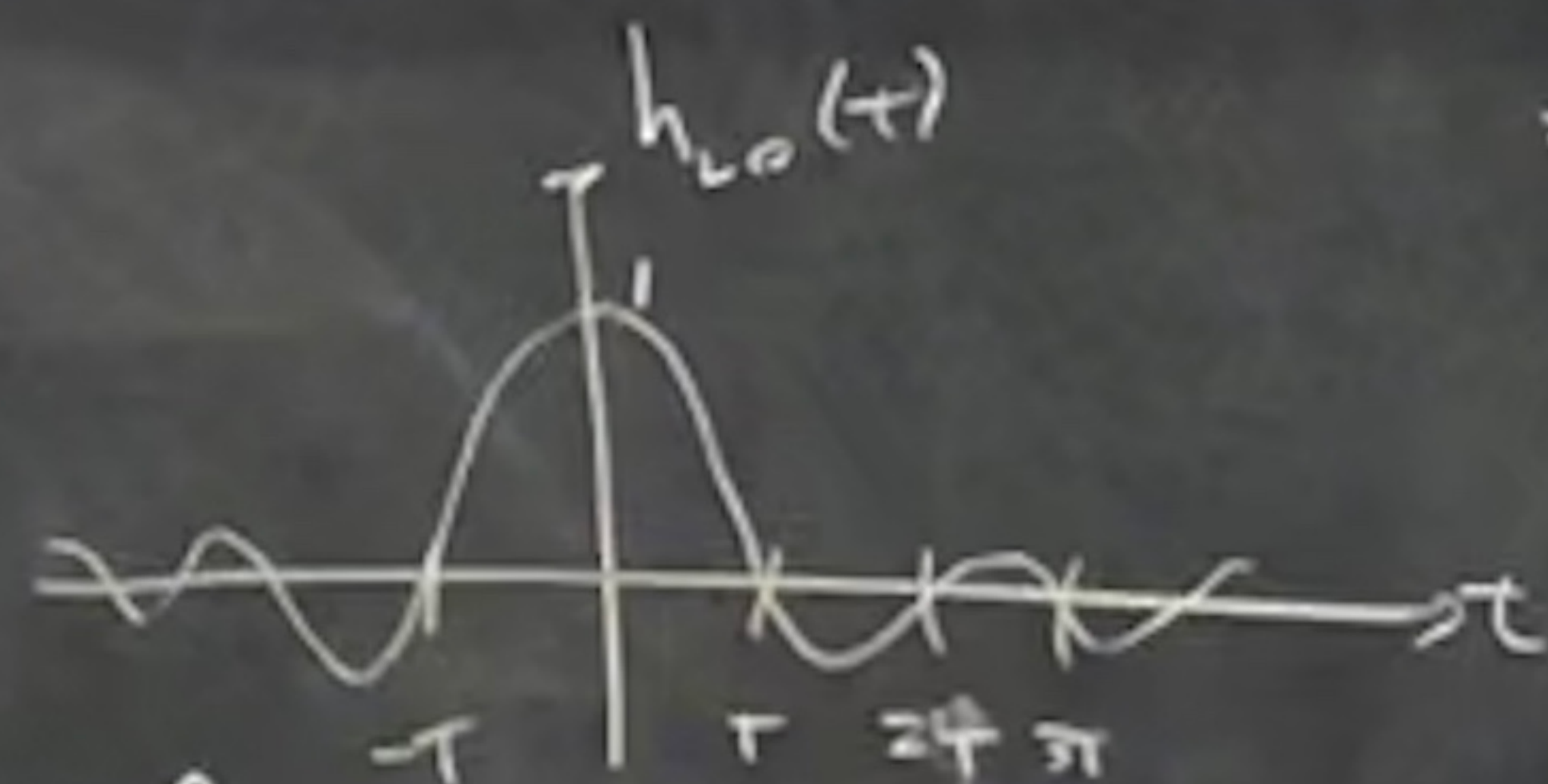
$$\text{RAD} = \frac{\text{RAD}}{\text{SEC}} \quad \text{SEC}$$

$$\Omega = \frac{\omega}{T}$$

RECONSTRUCTION IN THE TIME DOMAIN



$$y_s(t) = \sum_{n=-\infty}^{\infty} y[n] \delta(t - nT)$$



$$y_r(t) = \sum_{n=-\infty}^{\infty} y[n] \cdot h_{LP}(t - nT)$$

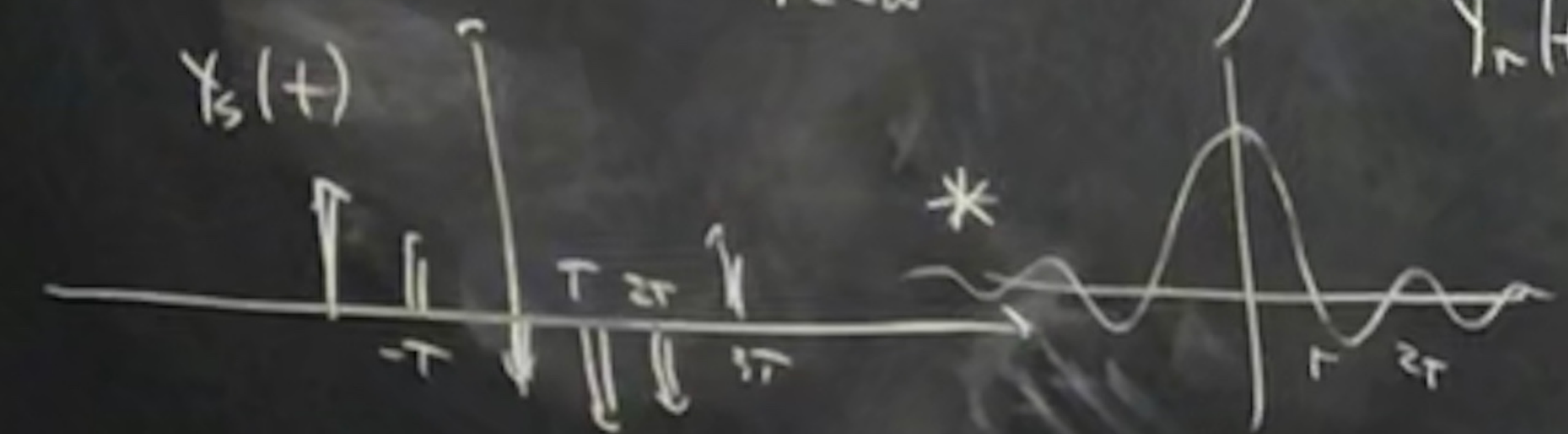
$$y_r(t) = \sum_{n=-\infty}^{\infty} y[n] \frac{\sin\left(\frac{\pi(t-nT)}{T}\right)}{\frac{\pi(t-nT)}{T}}$$

$$h_{LP}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H_{LP}(j\Omega) e^{j\Omega t} d\Omega$$

$$= \frac{1}{2\pi} \int_{-\frac{\pi}{T}}^{\frac{\pi}{T}} T e^{j\Omega t} d\Omega = \frac{T}{2\pi} \left. \frac{e^{j\Omega t}}{jt} \right|_{-\frac{\pi}{T}}^{\frac{\pi}{T}} = \frac{\sin\left(\frac{\pi t}{T}\right)}{\frac{\pi t}{T}} = \lim_{t \rightarrow 0} \frac{\frac{\pi}{T} \cos\left(\frac{\pi t}{T}\right)}{\frac{\pi}{T}} = 1$$

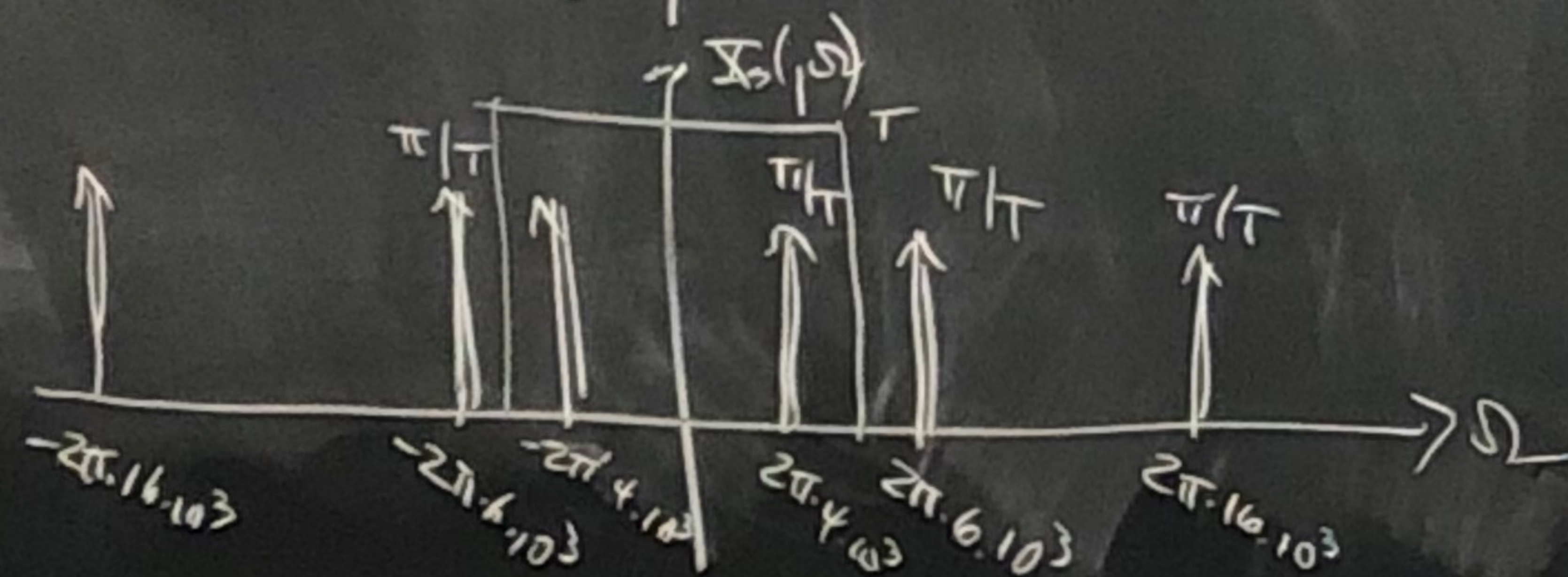
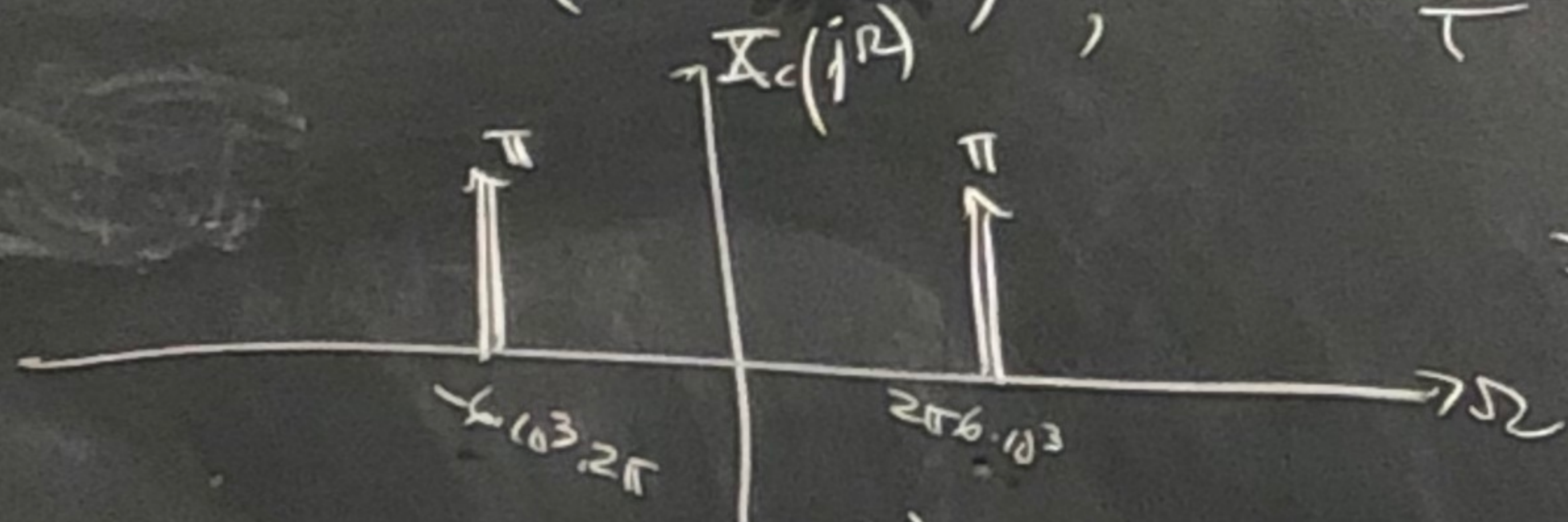
$$= \frac{T}{2\pi} \cdot \left(\frac{e^{j\frac{\pi}{T}t} - e^{-j\frac{\pi}{T}t}}{j\left(\frac{\pi t}{T}\right)} \right) = \frac{\sin\left(\frac{\pi t}{T}\right)}{\frac{\pi t}{T}}$$

$$\frac{\pi t}{T} = k\pi; t = kT$$

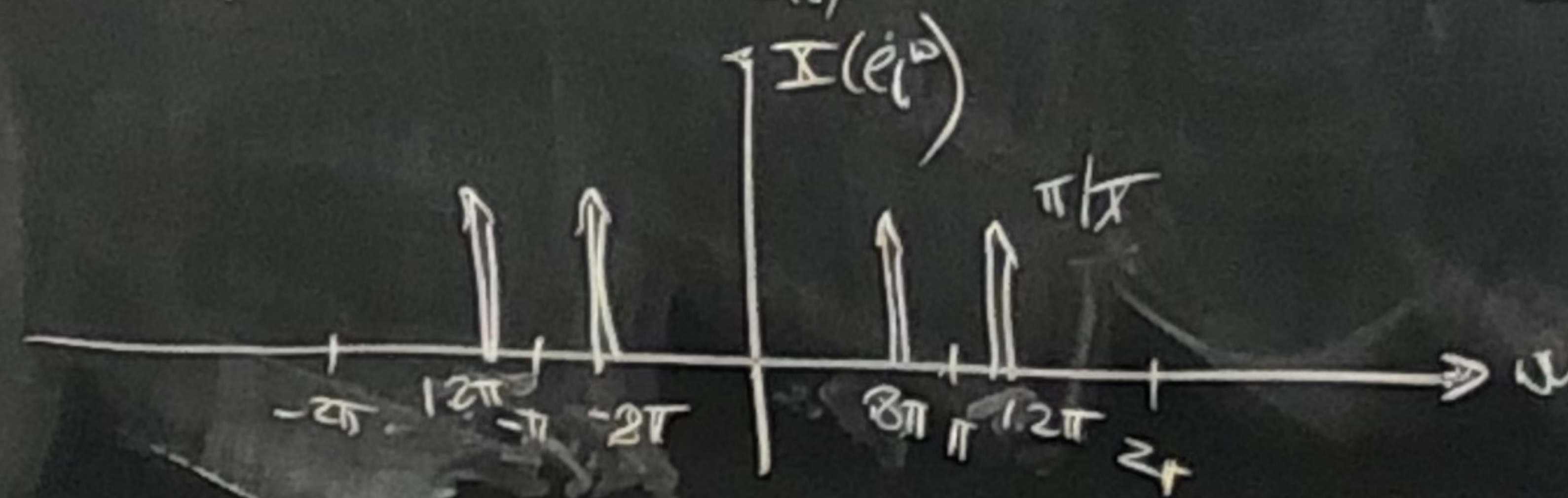
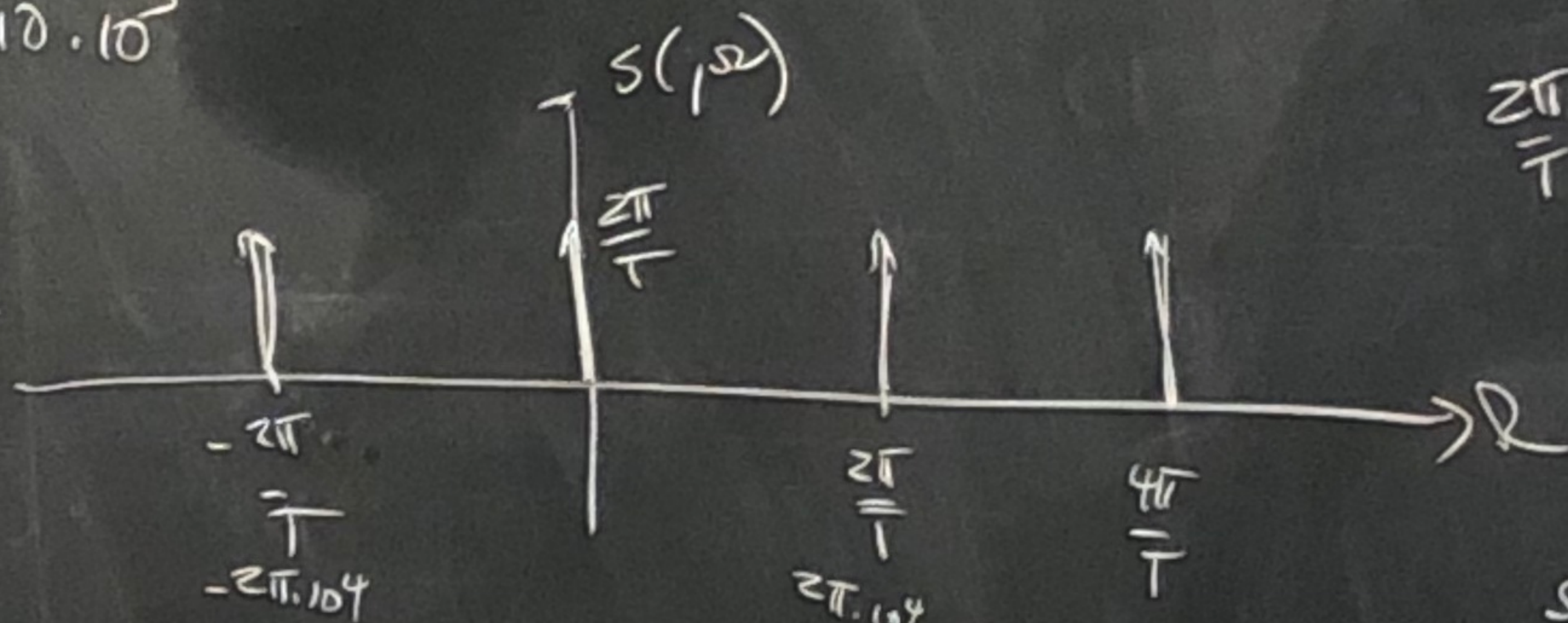


RECONSTRUCTION IN THE
TIME DOMAIN

$$x_c(t) = \cos(2\pi \cdot 6 \cdot 10^3 t), \quad \Omega_s = \frac{2\pi}{T} = 2\pi \cdot 10 \cdot 10^3$$



$$* \frac{1}{2\pi}$$



$$S(at) = \frac{1}{|a|} S(t)$$

$$\frac{2\pi}{T} = \Omega_s = 2\pi \cdot 10^4$$

$$S(\omega) = S\left(\frac{\Omega}{T}\right)$$

$$\Omega = 2\pi \cdot 4 \cdot 10^3$$

$$\omega = \Omega T = 2\pi \cdot 4 \cdot 10^3 \cdot 10^{-4} = 2\pi(0.4) \text{ rad}$$