18-344 Recitation 10

11/21/2025

Outline

- 1. Logistics
- 2. Lab 3 & 4
- 3. Concurrency, Parallelism, and Synchronization

Logistics

- Homework 9 released, due Nov 24 (Mon) (in 3 days)
- Homework 10 to be released on Nov 24, due Dec 3 (Wed) (in 1 week + 5 days)
- Lab 3
 - Code freeze: November 21 (Friday) (today)
 - Submit (push a commit to your repo) on GitHub Classroom
 - Report: November 24 (Monday) (in 3 days)
 - Submit on Gradescope
- Lab 4
 - Code freeze: December 11 (in 2 weeks + 6 days)
 - Submit (push a commit to your repo) on GitHub Classroom
 - Report: December 14 (in 3 weeks + 2 days)
 - Submit on Gradescope
- Exam 2 on December 3 (Wednesday) (in 1 week + 5 days)
 - Same location and time as regular lecture
 - If you miss no more than 2 lectures, for any reason, <u>after</u> the midterm exam, you may choose to use the homework average from the 2st half in place of the 2st exam.

Lab 3 & 4 Final Tips & Reminders

Lab 3

- TLB configuration is up to you.
 - size, associativity, replacement policy?
 - You'll need to justify your design choice and implementability.
- Evaluate how the hierarchical page table you implement reduces the amount of memory required for page table.
- vm_trace
 - Normal to take a relatively long time to produce a full trace for a microbenchmark.
 e.g. Takes about 10 minutes for void main() {return;} and produces a 800KB full trace.
 - We recommend *against* running vm_trace with SPEC benchmarks.
 Write your own microbenchmarks with *diverse memory access patterns* instead.
 - Trace contains memory accesses to unmapped memory regions?
- Anyone implementing a hashing page table?

Lab 4

- Binning by source or destination? Why?
- What cache performance metrics are useful for evaluation?
 - Evaluate using your cache simulator from lab 2.
 - What configuration would you choose and why?
 - Talk to us if your cache simulator may have correctness issues.
- What runtime metrics to measure and how to measure them?
 - Time (aka wall-clock time) (aka elapsed real time) of:
 The whole program? Part of the program? Which part of the program?
 - o If using <u>time</u> use *real* time. Better options exist but not required (e.g. std::chrono).
 - Consider and do your best to eliminate the influence of external factors.
 e.g. Don't benchmark on a crowded machine where people are running a million processes.
 - Measuring performance in real-world terms will always give varying results.
 Measure multiple times and record variance.

Lab 4 cont'd

- We highly recommend using large, real-world graphs.
 - Makes the effectiveness of propagation blocking more significant and observable.
 - For <u>SNAP</u>, web-Google, and various social media graphs are good starting points.
 - You'll need to write scripts to convert real-world graphs to EL format.
 Make sure to handle unidirectional edges.
 - Real-world graphs are large.
 Please don't turn them in, and make sure to not exceed your ECE AFS disk quota.
- graph.h defines MAX_VTX
 - Need to change it for graphs of different sizes.
 - This is a C macro, so there are multiple ways to change it without needing to modify the code.
 - This affects binning, so *do not* set it to an arbitrarily large number (e.g. INT_MAX).

On reporting results and writing the report

Be comprehensive.

Read the handout (all of it, not just the final sections) carefully to find what's required in your report.

- Be quantitative.
 - e.g. For graph G, using binning by {src, dst}, simulating with a cache with configuration C:
 - Quantitative: Increasing the number of bins from N to M results in a X% increase in cache hit rate.
 - Qualitative: Increasing the number of bins results in an increase in cache hit rate.
 - Quantitative when reporting most evaluation results, qualitative when reporting general trends.
- Lab report writing resources:
 - Lab report writing guide
 - Report writing tips from recitations 1&5
 - Our feedback from recitation 9
 - Your graded lab reports from labs 1&2



Concurrency, Parallelism, and Synchronization

Concurrency & Parallelism

Concurrency

- Executing multiple tasks at once by allowing them to make progress in overlapping time periods.
- Tasks start, run, and complete in an interleaved way, but not necessarily at the exact same instant.
- e.g. A single-core, single-thread system running multiple software threads.
 Only one software thread runs at a time, but the OS switches between them.

Parallelism

- Performing multiple operations at the same instant.
- Many types of parallelism available (non-exhaustive):
 - Data-level parallelism
 - e.g. Using SIMD instructions to add two vectors together.
 - Task-level parallelism
 - e.g. A single-core, multi-thread system running multiple software threads.
 - All hardware threads run at the same time.
 - In this case, the software threads are also executed concurrently.

An awkwardly parallel program

```
1  void *thread(void):
2  for (int i = 0; i < K; i++):
3    size_t ind = rand() % N
4    arr[ind]++</pre>
```

Assuming a global, heap-allocated array of integers, **arr**, is shared across all threads.

Each thread randomly increment an element in **arr** and repeat until K times.

At any instant, multiple threads could be getting the same **ind**. Since **++** is a Read-Modify-Write sequence and **not atomic**, there is a **data race**.

Adding synchronization, **spinlock** edition

```
void *thread(void):
for (int i = 0; i < K; i++):
    size_t ind = rand() % N
    spin_lock(&locks[ind])
    arr[ind]++
    spin_unlock(&locks[ind])</pre>
```

Assuming a global, heap-allocated array of spinlock_ts, **locks**, is shared across all threads and initialized appropriately.

When a thread attempts to acquire a spinlock and finds it already locked by another thread, it continuously checks the lock variable in a tight loop until the lock becomes available.

A spinlock can be implemented like:

```
while(test_and_set(&lock)) {
   // Busy-wait
}
```

Adding synchronization, **__sync_fetch_and_add** edition

```
1  void *thread(void):
2  for (int i = 0; i < K; i++):
3    size_t ind = rand() % N
4    __sync_fetch_and_add(
5    &arr[ind], // ptr
6    1    // value
7  )</pre>
```

This is a real gcc builtin function for x86.

```
type __sync_fetch_and_add
  (type *ptr, type value)
```

As the name suggests,

__sync_fetch_and_add fetches data from
a given address *ptr then adds a given
value to it *in-place and atomically*.

Adding synchronization, __sync_bool_compare_and_swap edition

```
void *thread(void):
     for (int i = 0; i < K; i \leftrightarrow ):
       size t ind = rand() % N
       bool success = false;
       do:
         success =
           sync bool compare and swap(
             &arr[ind], // *ptr
             arr[ind], // oldvar
             arr[ind] + 1 // newval
10
11
       while (!success)
12
```

This is a real gcc builtin function for x86.

As the name suggests,

__sync_fetch_and_add performs an

atomic compare-and-exchange operation:

It compares the value at *ptr with oldval, and if they are equal, it atomically stores newval into *ptr and returns true; otherwise it leaves *ptr unchanged and returns false.

Adding synchronization, **Transactional Memory**, 1st edition

```
void *thread(void):
     for (int i = 0; i < K; i++)
       size t ind = rand() % N
       bool success = false
       do:
         if (tm begin() = TM STARTED):
           arr[ind]++
           tm end()
           success = true
      while (!success)
10
```

The do—while loop retries the same update until tm_begin() succeeds.

On success, the thread increments arr[ind] and commits.

On any abort or failure to start, the transaction is retried immediately.

If a transaction repeatedly aborts on the chosen index, the thread *keeps retrying the same conflicting operation forever*.

Adding synchronization, **Transactional Memory**, 2nd edition

```
void *thread(void):
     for (int i = 0; i < K; i++)
       size t ind = rand() % N
       for (int j = 0; j < LIMIT; j \leftrightarrow ):
          if (tm begin() = TM STARTED):
            arr[ind]++
            tm end()
            goto 12
       spin lock(&locks[ind])
       arr[ind]++
10
       spin unlock(&locks[ind])
11
12
```

Solution: add back-off to tm begin().

If a transaction repeatedly aborts or fails to start on the chosen index, the thread tries up to **LIMIT** times before giving up and falling back to use other synchronization methods.

On a tm begin() success, control needs to skip the fall-back using goto.

Transactions can *inevitably fail* if another thread is in fall-back and about the increment the array element.

Abort becomes more expensive for longer transactions.

Adding synchronization, Transactional Memory, final edition

```
void *thread(void):
     for (int i = 0; i < K; i + +)
       size t ind = rand() % N
       for (int j = 0; j < LIMIT; j \leftrightarrow ):
         if (tm begin() = TM STARTED):
            if (locks[ind] = LOCKED):
6
              tm abort()
            else:
              arr[ind]++
              tm_end()
10
11
              goto 15
       spin lock(&locks[ind])
12
       arr[ind]++
13
14
       spin unlock(&locks[ind])
15
```

Optimization: after beginning a transaction, proactively check for the lock status of all memory addresses participating in the transaction, and tm_abort() early if any memory address' lock has already been acquired.

Transactional memory would have been great if it weren't for the many **security vulnerabilities**

