### 18-344: Computer Systems and the Hardware-Software Interface Fall 2023



### **Course Description**

**Lecture 7: Caches and the Memory Hierarchy** 

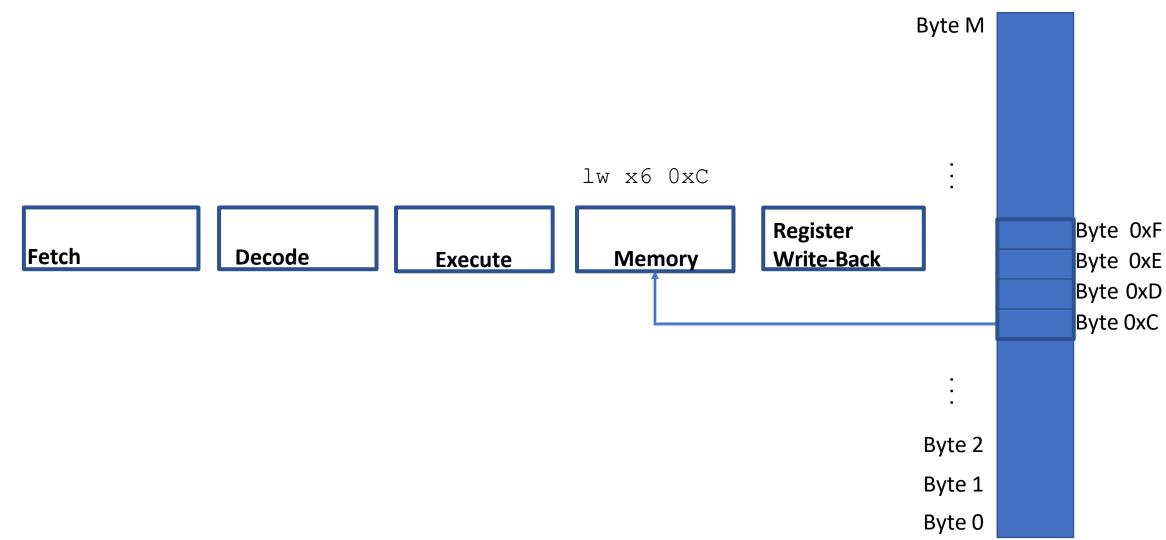
This course covers the design and implementation of computer systems from the perspective of the hardware software interface. The purpose of this course is for students to understand the relationship between the operating system, software, and computer architecture. Students that complete the course will have learned operating system fundamentals, computer architecture fundamentals, compilation to hardware abstractions, and how software actually executes from the perspective of the hardware software/boundary. The course will focus especially on understanding the relationships between software and hardware, and how those relationships influence the design of a computer system's software and hardware. The course will convey these topics through a series of practical, implementation-oriented lab assignments.

Credit: Brandon Lucia

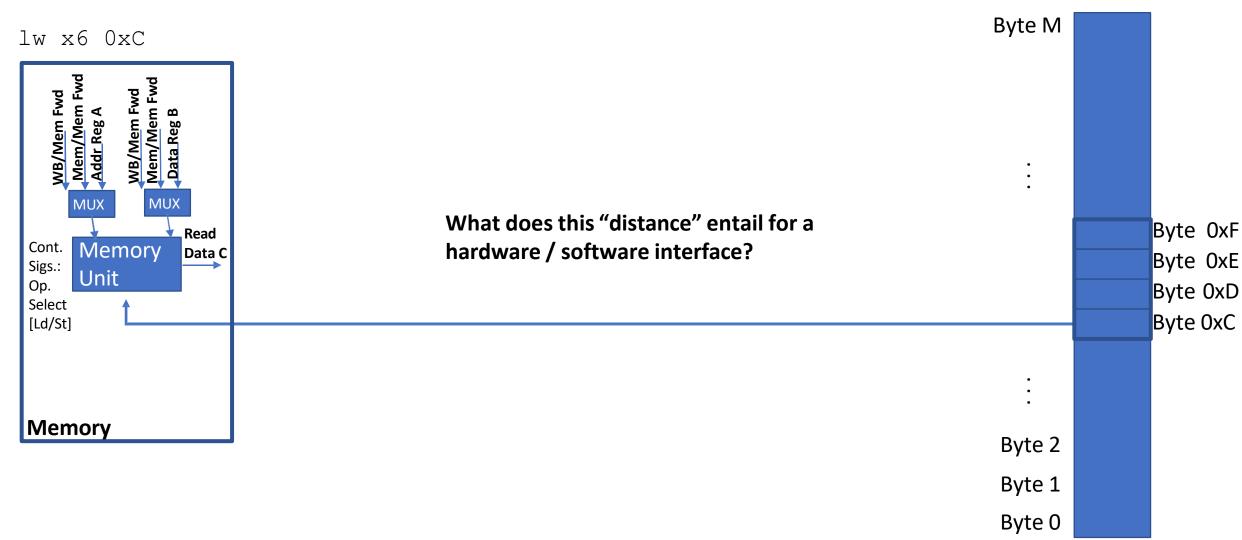
# Today: Caches and the Memory Hierarchy

- Introduction to caches and cache organization
- Caches in the memory hierarchy
- Cache implementation choices
- Cache hardware optimizations
- Software-managed caches & scratchpad memories

# Memory is a big list of M bytes

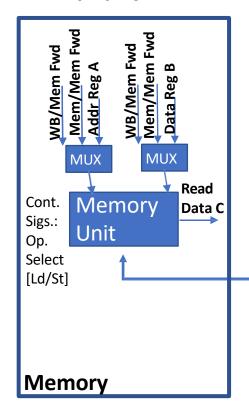


# Memory is conceptually far away from CPU



# Memory is conceptually far away from CPU

lw x6 0xC



What does this "distance" entail for a hardware / software interface?

- Need to be judicious with lw & sw
- Compiler & programmer must carefully lay out memory
- Worth spending hardware resources to optimize
- Need hardware and software to co-optimize data re-use
- Data movement is a fundamental limit on speed & energy

Byte M

Byte 0xF Byte 0xE

Byte 0xD

Byte 0xC

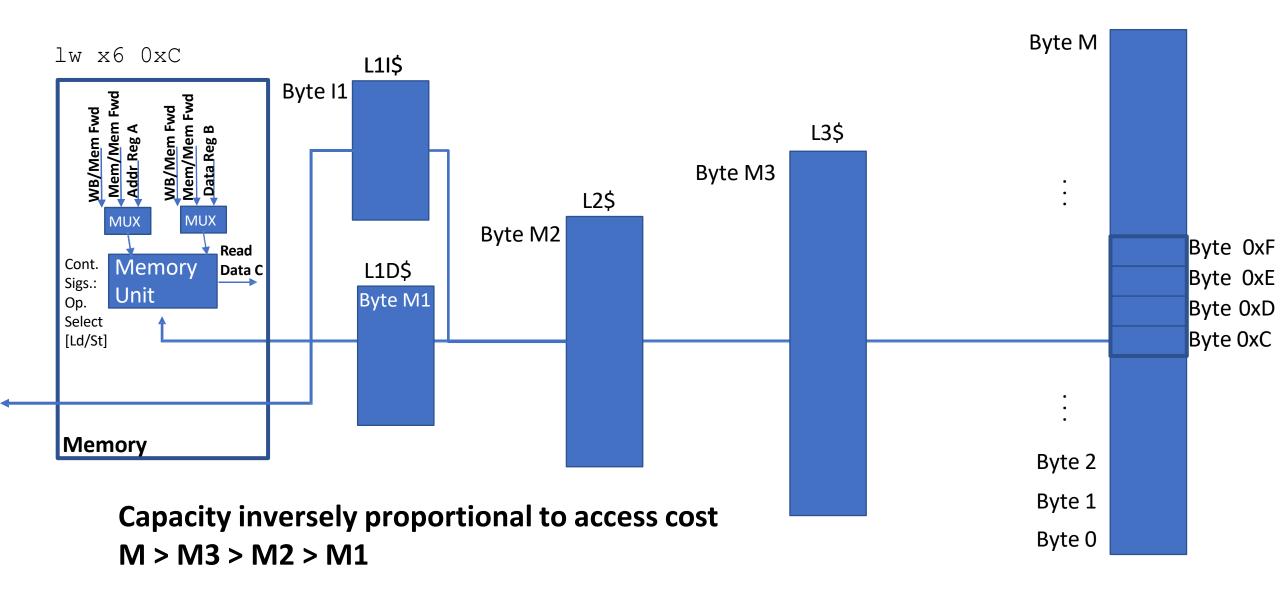
:

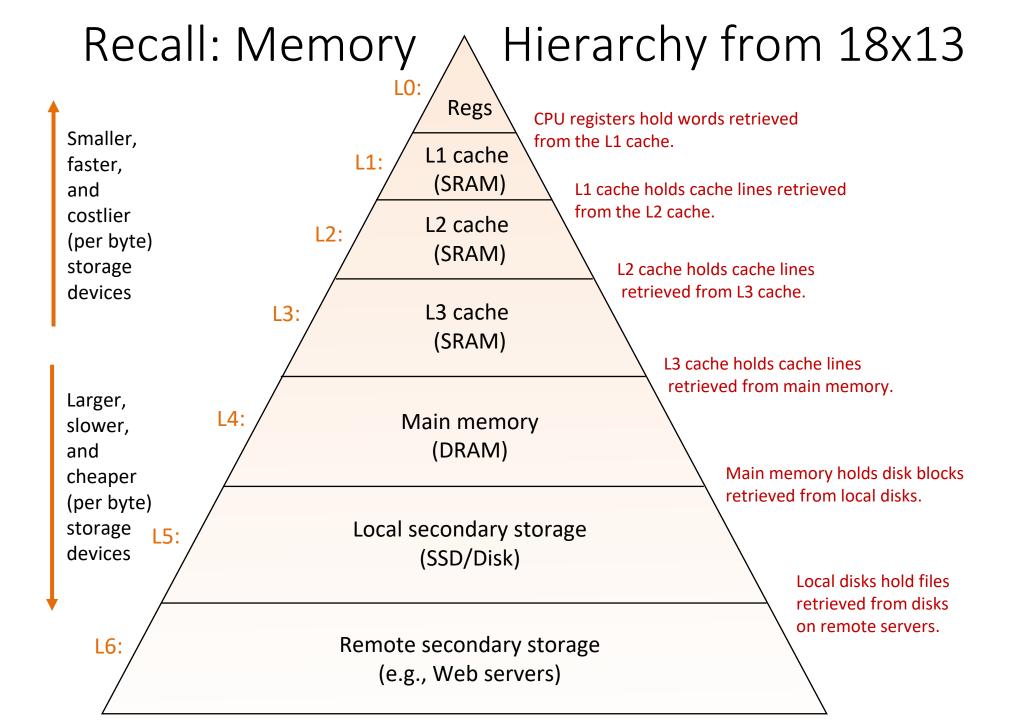
Byte 2

Byte 1

Byte 0

## Memory hierarchy: large & slow vs. small & fast





## Recall from 18x13: The Working Set

- The data that is presently being use is called the Working Set.
- Imagine you are working on 18x13. Your working set might include:
  - The lab handout
  - A terminal window for editing
  - A terminal window for debugging
  - A browser window for looking up man pages
- If you changed tasks, you'd probably hide those windows and open new ones
- The data computer programs use works the same way.

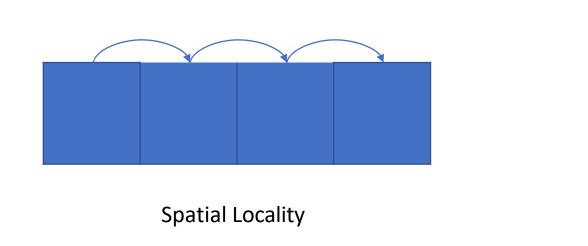
## Recall from 18x13: Guesstimating the Working Set

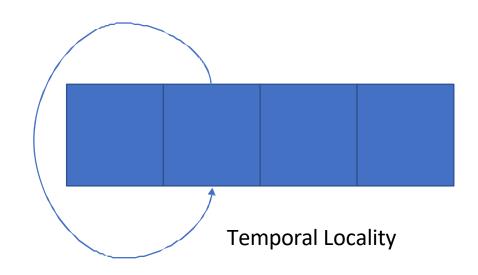
- How does the memory system (cache logic) know the working set?
  - This is tricky. There is no way it can really know what data the program needs or will need soon.
  - It could even be totally dynamic, based upon input.
- It approximates it using a simple heuristic called locality:
  - Temporal locality: Data used recently is likely to be used again in the near future (local in time).
  - Spatial locality: Data near the data used recently is likely to be used soon (local in space, e.g. address space).
- The memory system will bring and keep the Most Recently Used (MRU) data and data near it in memory to the higher layers while evicting the Least Recently Used (LRU) data to the lower layers.

### What's New Since 18x13?

- We want to think about a cache built natively in real hardware vs a software simulation of a cache
- The 18x13 cache was a software simulation of a somewhat ideal LRU cache
- Consider how you built an LRU cache simulator in 18x13:
  - A linked list- based queue?
  - A copy-to-shift array-based queue?
- Time for the "18-240 Thinking Cap": Consider the implementation of LRU in hardware
  - Can the 18x13 approach be translated to real hardware in a practical way?

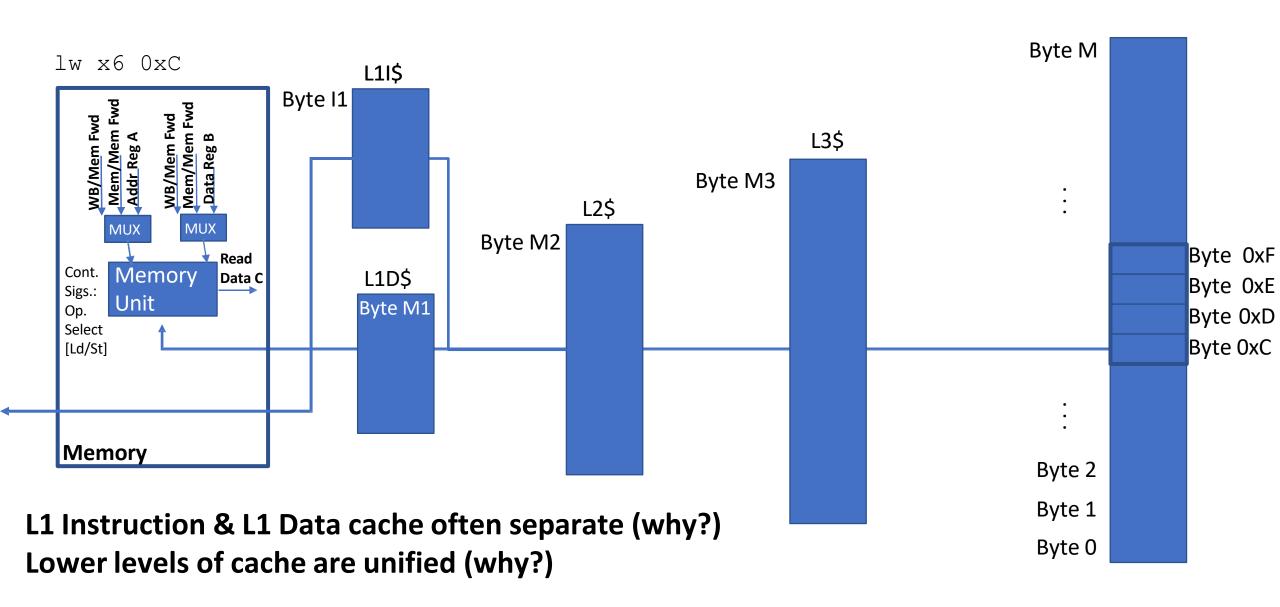
## Locality is the key to cache performance



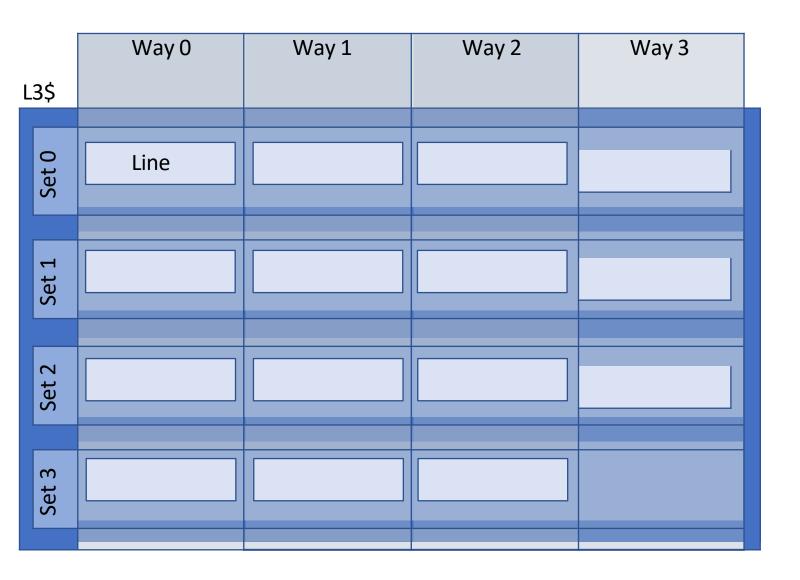


Why do we see locality? What are some examples of each?

## Memory hierarchy: Unified vs. Split ICache & DCache



# Review: Anatomy of a set-associative cache



#### **Typical Parameters**

Line contains 16-64 bytes of data

1-8 number of sets

1 set contains all lines?

All sets contain 1 line?

Total size varies by level:

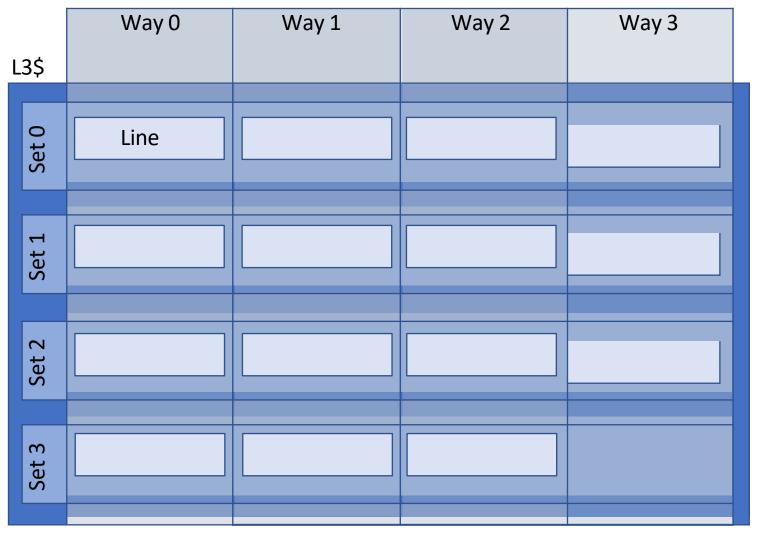
L1: 1kB - 32kB

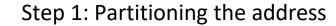
L3: a few kB - 48MB

	Valid	Dirty	Tag	B bytes data
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Anatomy of a Line

## Review: Accessing the cache





lb x6 0x7fff0053



set index

0x0111111111111111000000001010011

tag bits

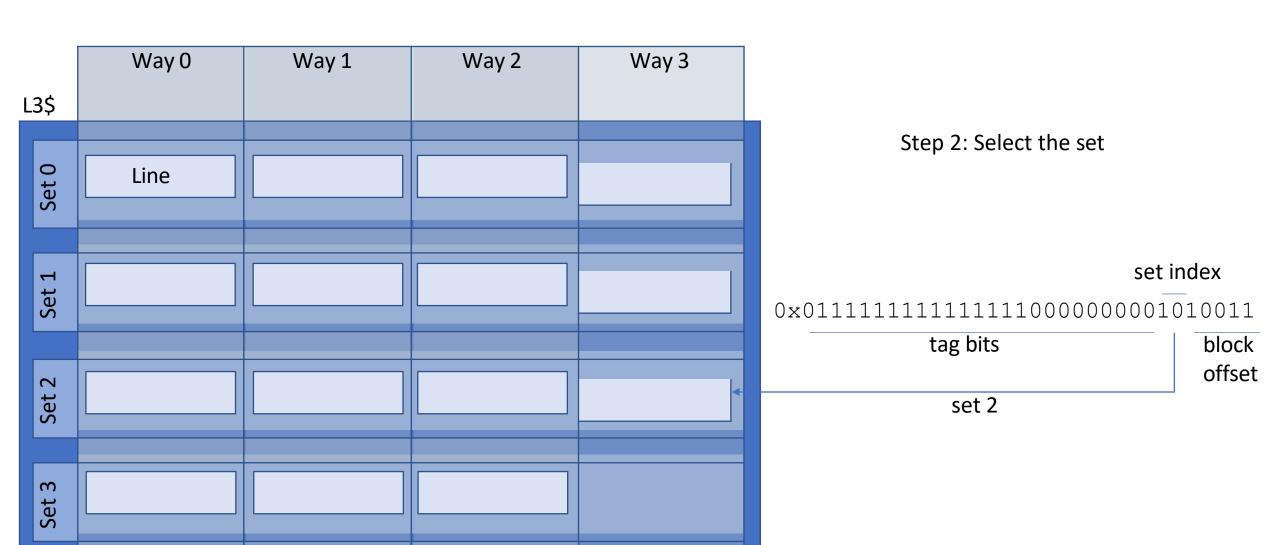
block offset

Valid   Dirty   Tag   32 bytes data
-------------------------------------

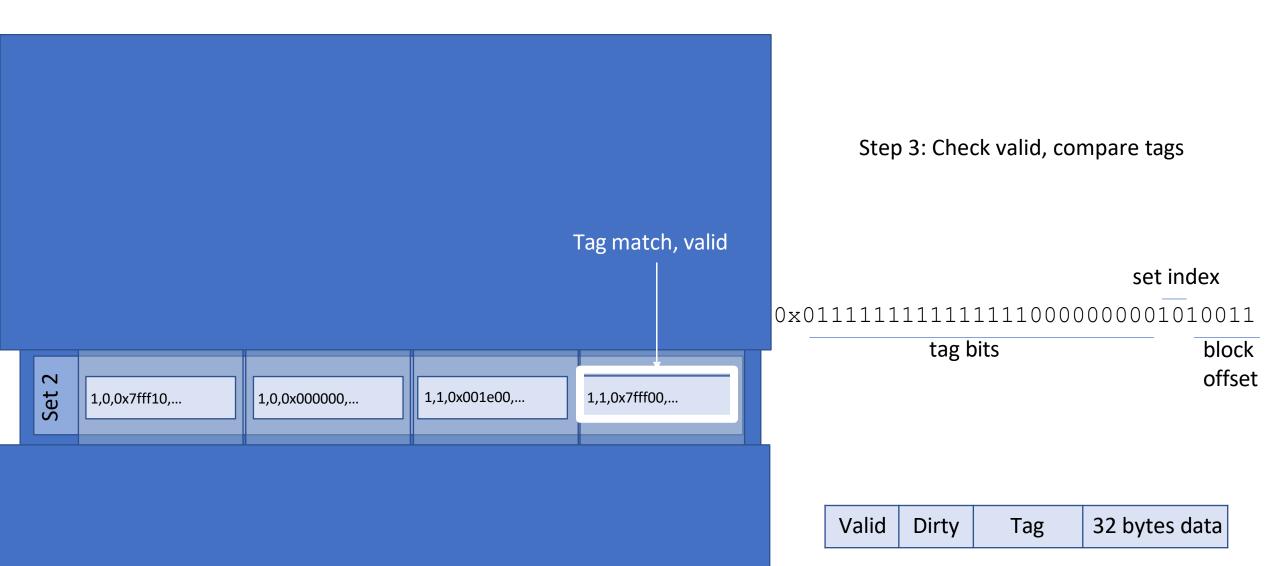
Total cache size = 32B x 4 sets x 4 ways = 512B

#### lb x6 0x7fff0053

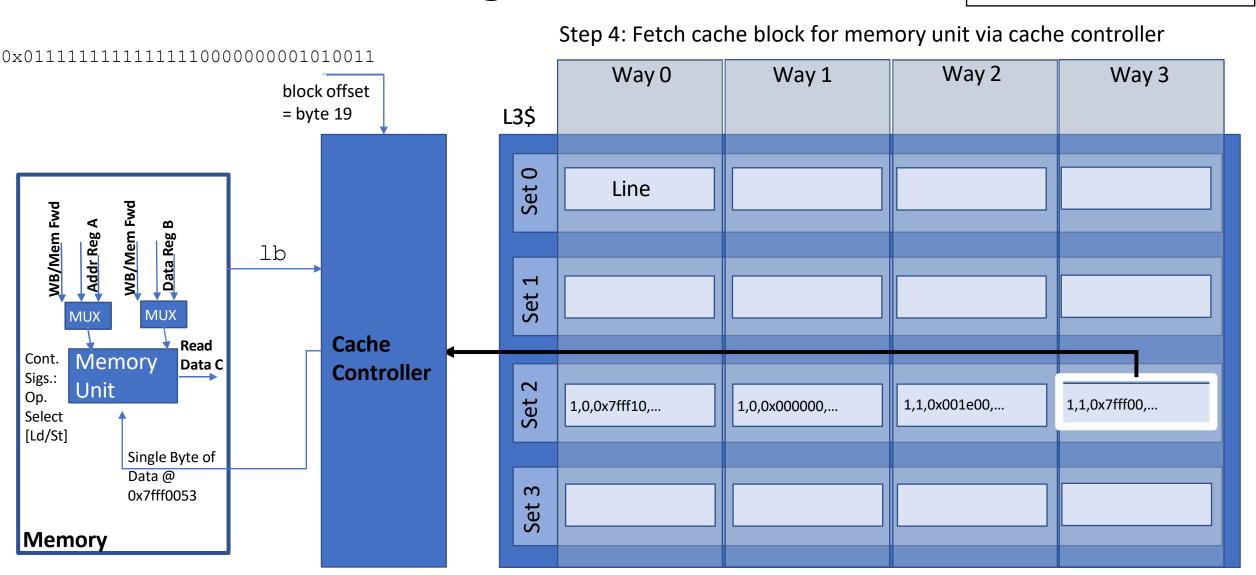
## Review: Accessing the cache



# Review: Accessing the cache - Hit

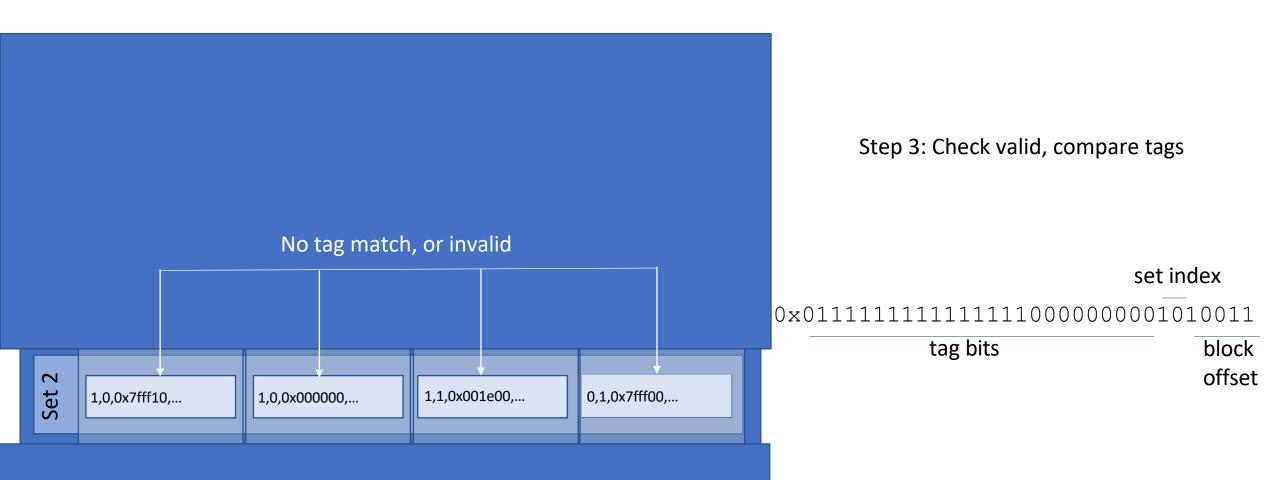


## Review: Accessing the cache - Hit



32 bytes data

# Review: Accessing the cache - Miss



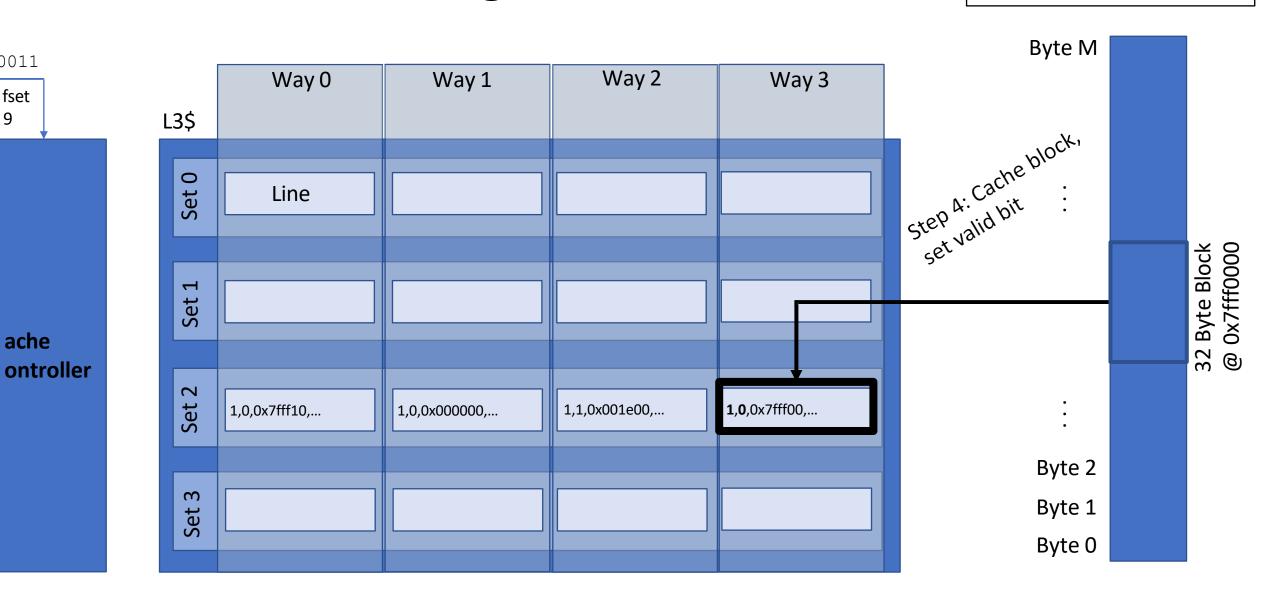
Valid

Dirty

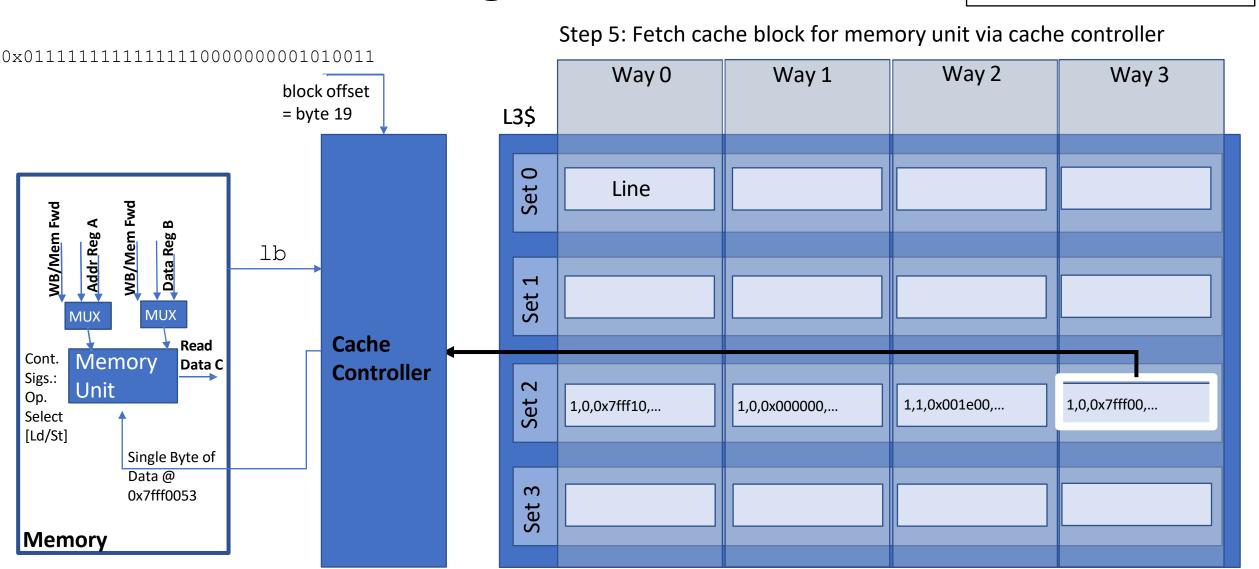
Tag

# Review: Accessing the cache - Miss

lb x6 0x7fff0053



# Review: Accessing the cache - Miss



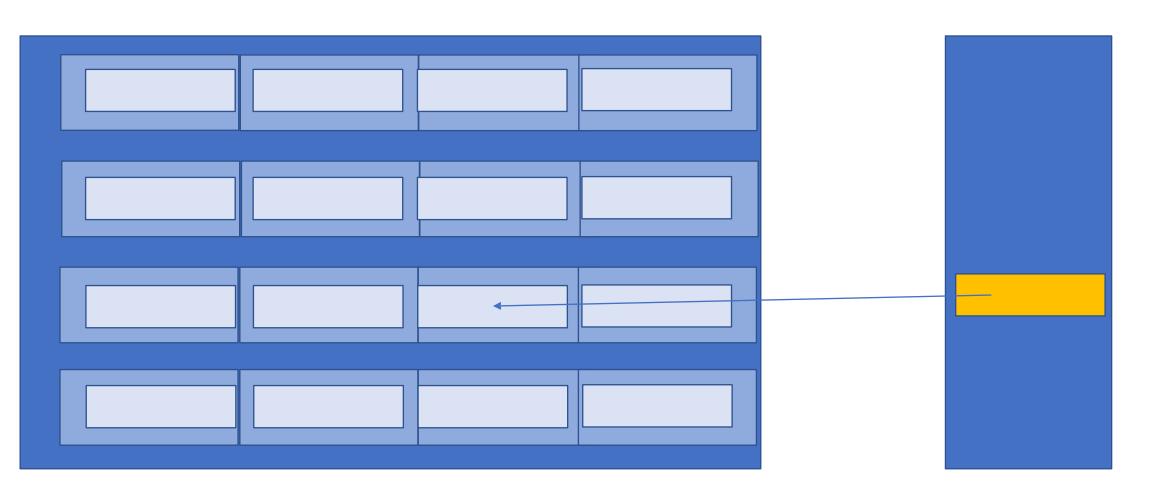
Why do we miss in the cache?

# Why do we miss in the cache?

- The 3 C's of misses
  - Compulsory
  - Conflict
  - Capacity

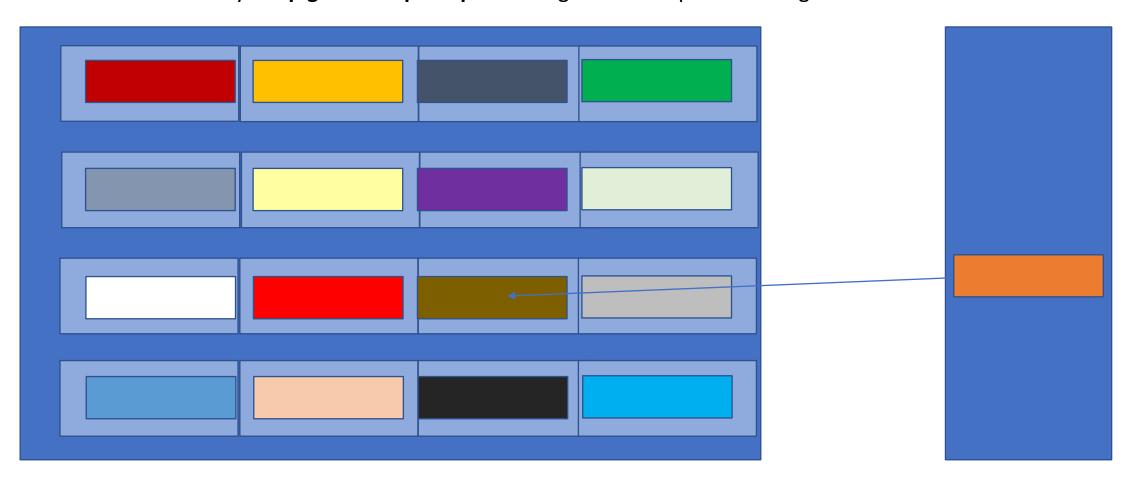
# Why miss? Compulsory misses

First access to any block of memory is always a miss; these misses are **compulsory** 



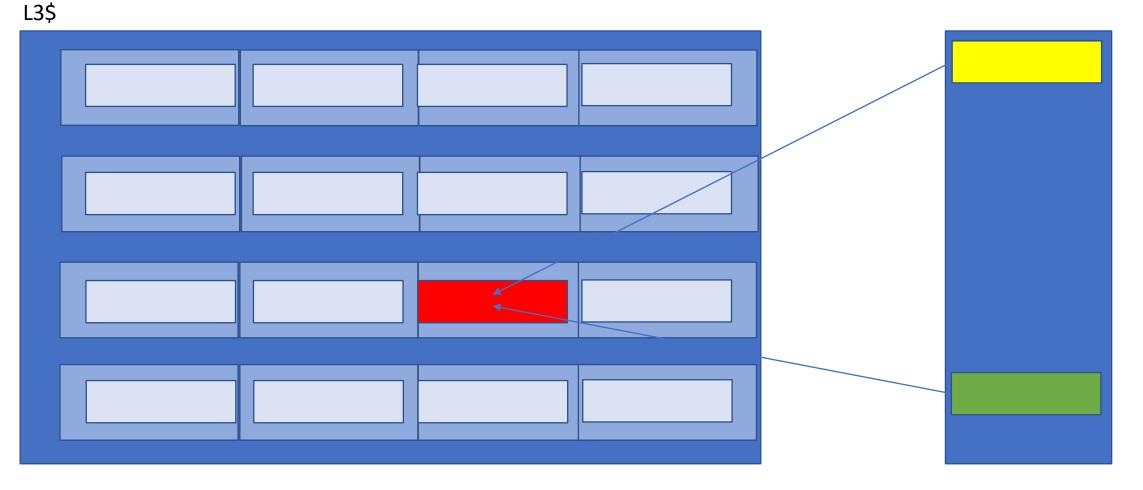
## Why miss? Capacity misses

**Working set** of program contains more data than can be cached at one time. By the **pigeonhole principle** caching all data requires missing at least once

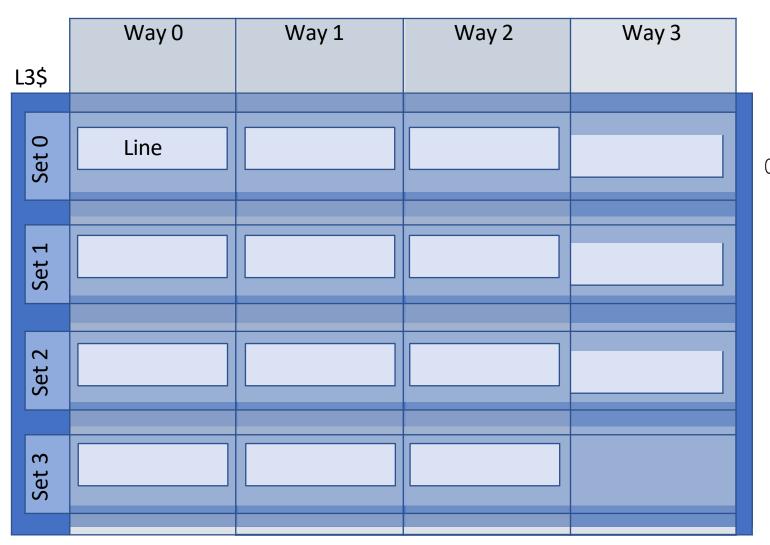


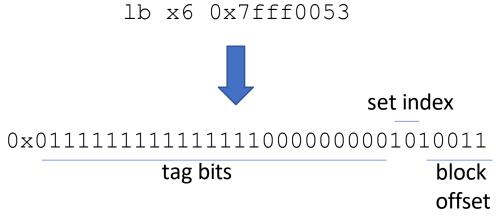
# Why miss? Conflict misses

Multiple blocks of memory map to the same location in the cache and **conflict**, even if there is still some empty space in the cache



# How many bits in tag/index/offset?



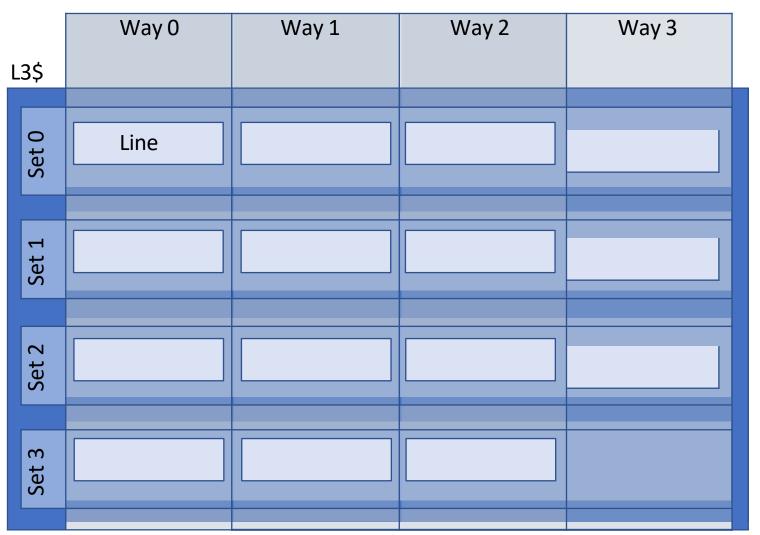


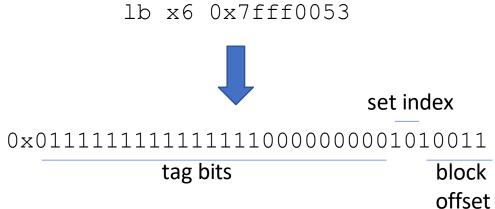
#### Why these numbers of bits?

Valid Dirty	Tag	32 bytes data
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Total cache size =  $32B \times 4$  sets  $\times 4$  ways = 512B

# How many bits in tag/index/offset?



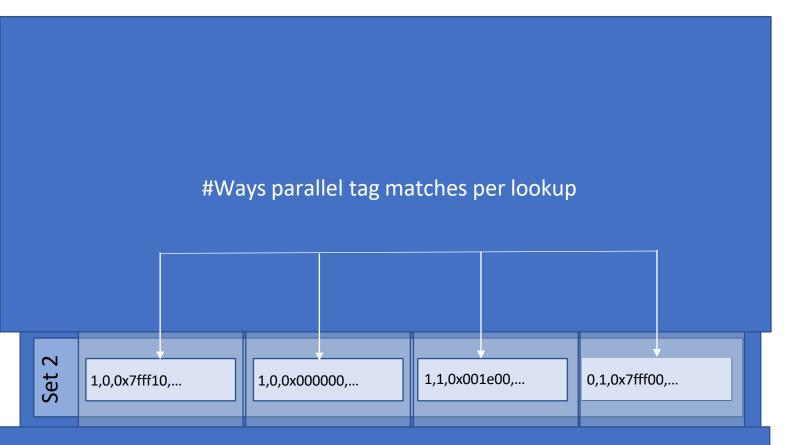


Enough **block offset** bits to count block bytes Enough **set index** bits to count the sets All left-over bits are **tag** bits **Question: what do tag bits mean?** 

Valid	Dirty	Tag	32 bytes data
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Total cache size =  $32B \times 4 \text{ sets } \times 4 \text{ ways} = 512B$ 

## How many sets should your cache have?

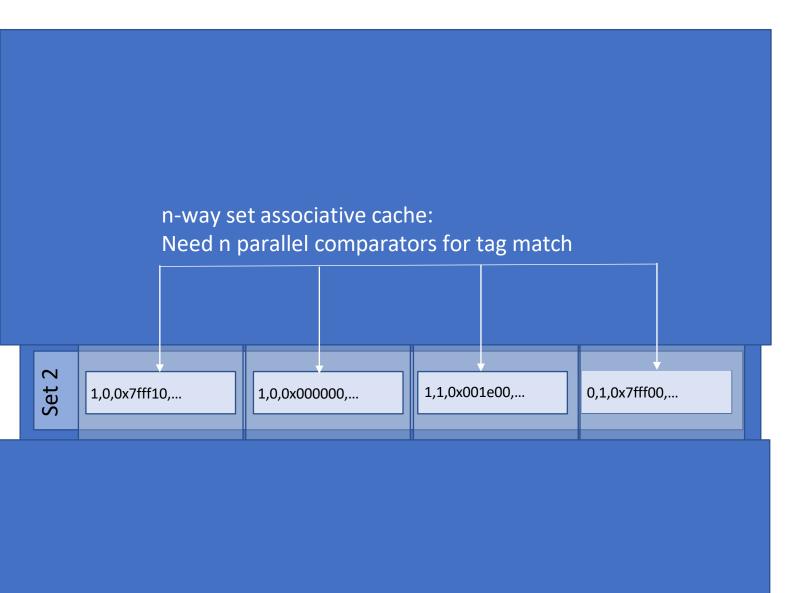


#### **Set Associative Cache Design Procedure**

- 1. Select total cache size
- 2. Select implementable #ways
- 3.cache size = #sets x #ways x #block\_bytes
- 4.#sets = cache size / (#ways x #block\_bytes)

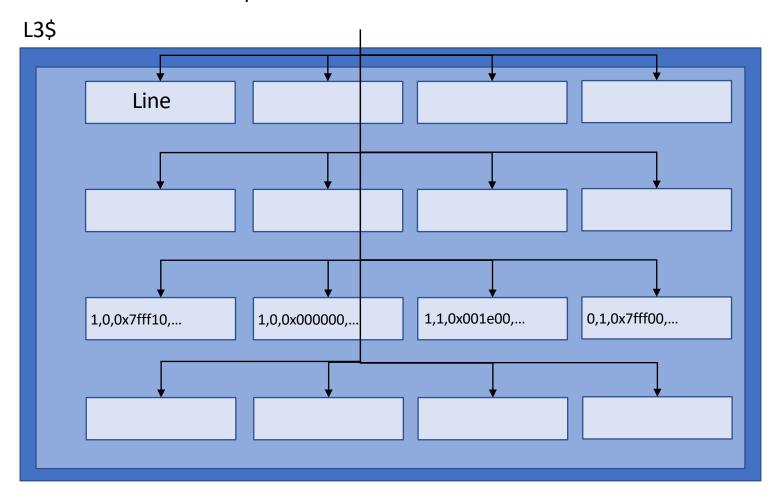
What is an implementable # of ways?

# What is an implementable # ways?

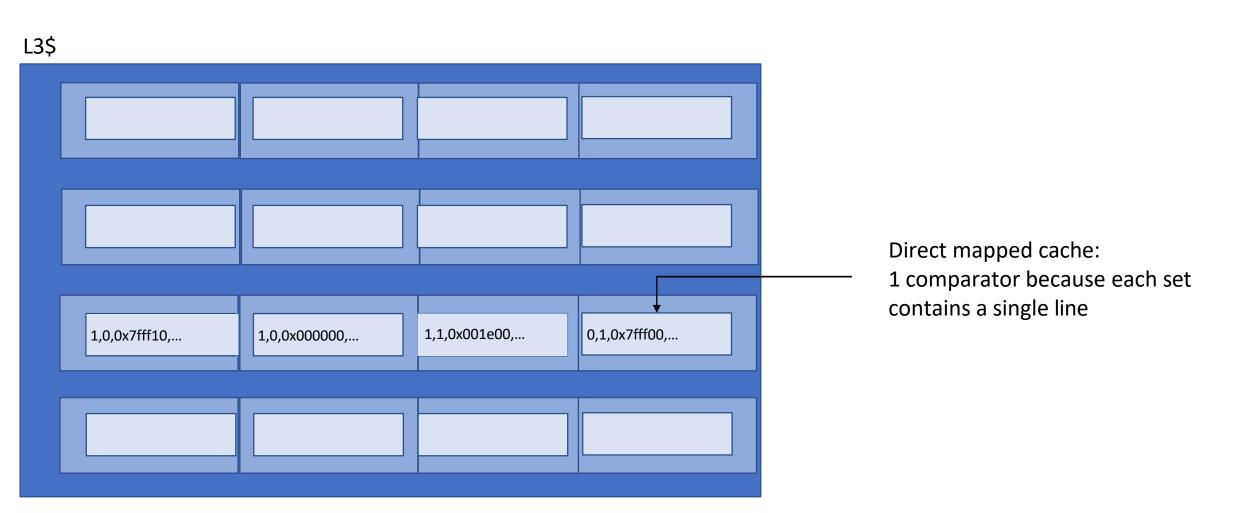


# What is an implementable # ways?

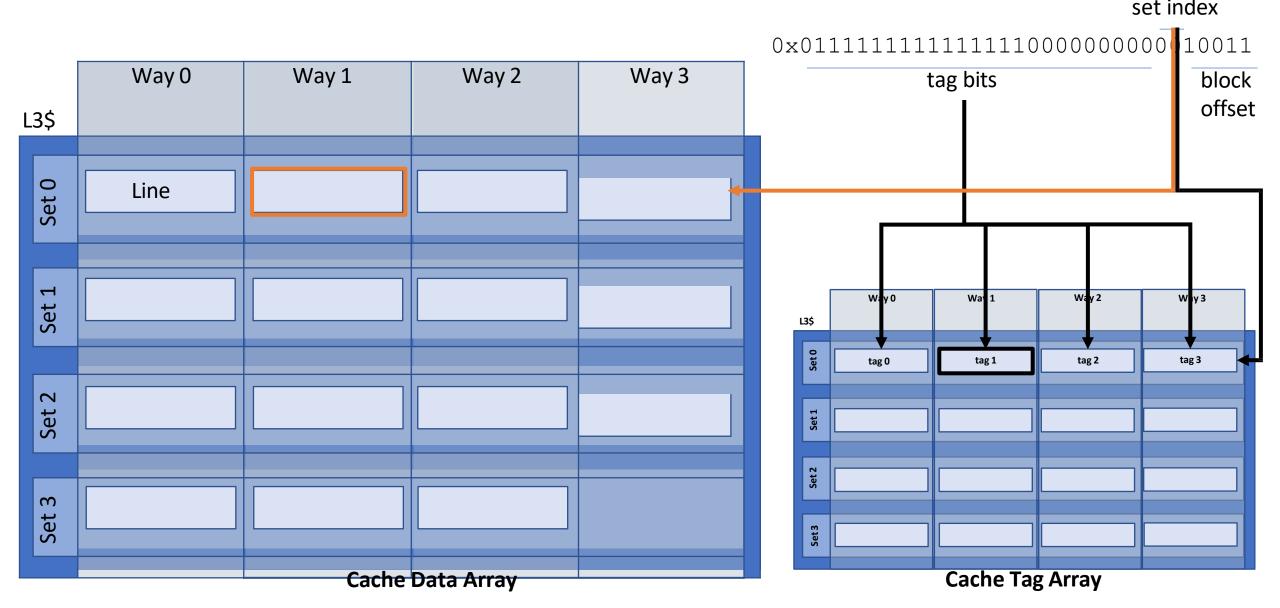
Fully-associative cache: # comparators = # lines in entire cache



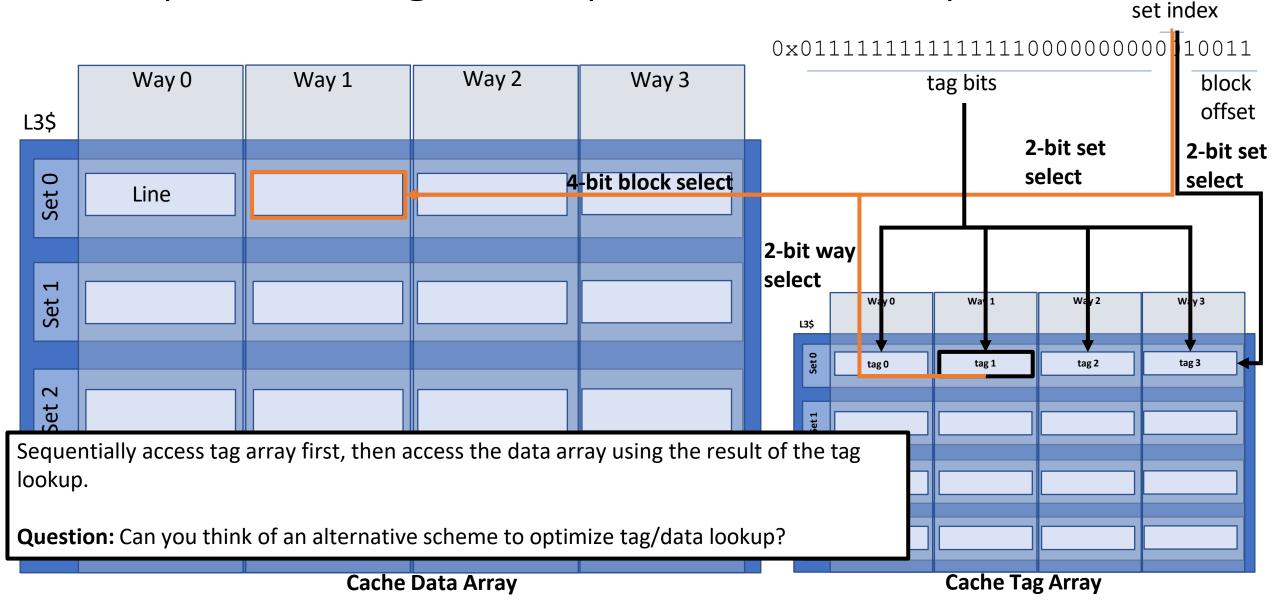
# What is an implementable # ways?



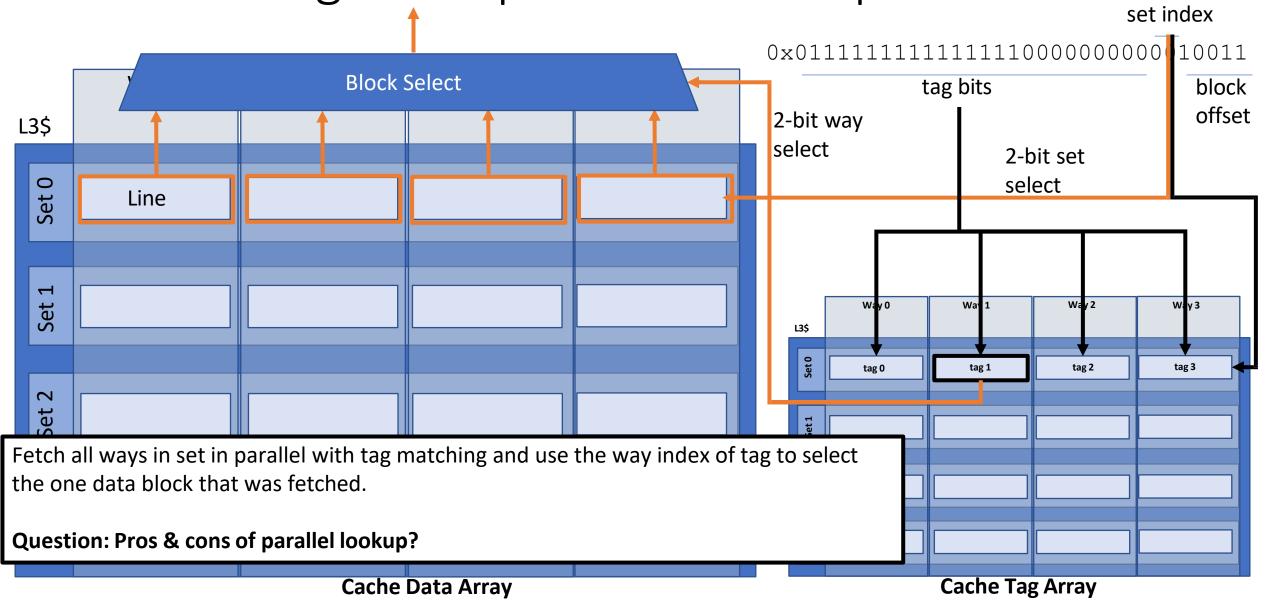
# Physical implementation separates data & tags



## Sequential Tag Lookup & Data Lookup



# Parallel Tag Lookup & Data Lookup



Way Prediction: Cost Like Sequential, Performance Like Parallel Tag Lookup Prediction set index validator Way 0 Way 2 Way 3 tag bits block offset L3\$ way 2-bit set 2-bit set predictor select select 0 4-bit block select Line  $\vdash$ Wav 2 Way 1 2-bit way tag 2 tag 0 tag 3 select 2 Send some tag bits and set index bits to fast way predictor, output of which is 4-bit block select, like in sequential. Fetch way of matched tag and send to prediction validation logic. If correct predict: use block. If incorrect predict: discard block and refetch. **Cache Tag Array** 

Moritz Lipp, Vedad Hadžić, Michael Schwarz, Arthur Perais, Clémentine Maurice, and Daniel Gruss. 2020. Take A Way: Exploring the Security Implications of AMD's Cache Way Predictors. In Proceedings of the 15th ACM Asia Conference on Computer and Communications Security (ASIA CCS '20). Association for Computing Machinery, New York, NY, USA, 813–825. https://doi.org/10.1145/3320269.3384746

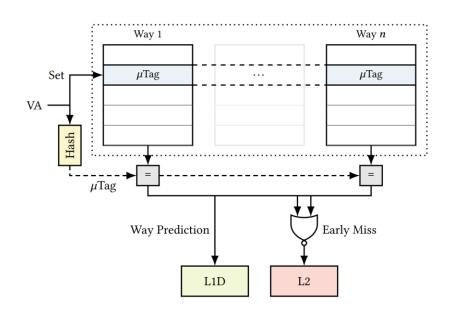


Figure 1: Simplified illustration of AMD's way predictor.

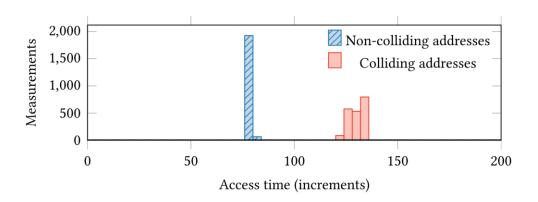


Figure 2: Measured duration of 250 alternating accesses to addresses with and without the same  $\mu$ Tag.

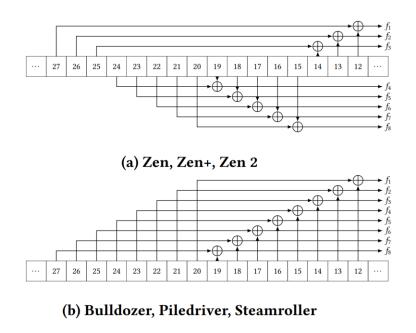


Figure 3: The recovered hash functions use bits 12 to 27 of the virtual address to compute the  $\mu$ Tag.

### Cost of Associativity

512 Bytes, 256-bit (32B) lines, 1-way

512 Bytes, 256-bit (32B) lines, 4-way

#### \$ ./destiny config/SRAM\_512\_1\_256.cfg

Read Latency = 55.4943ps

Tag Read Latency = 277.84ps

Write Latency = 54.7831ps

Tag Write Latency = 212.575ps

Read Bandwidth = 674.493GB/s

Write Bandwidth = 633.944GB/s

Tag Read Dynamic Energy = 0.281324pJ

Tag Write Dynamic Energy = 0.222833pJ

#### \$ ./destiny config/SRAM\_512\_4\_256.cfg

Read Latency = 83.4307ps

Tag Read Latency = 293.516ps

Write Latency = 83.1343ps

Tag Write Latency = 226.518ps

Read Bandwidth = 480.942GB/s

Write Bandwidth = 500.715GB/s

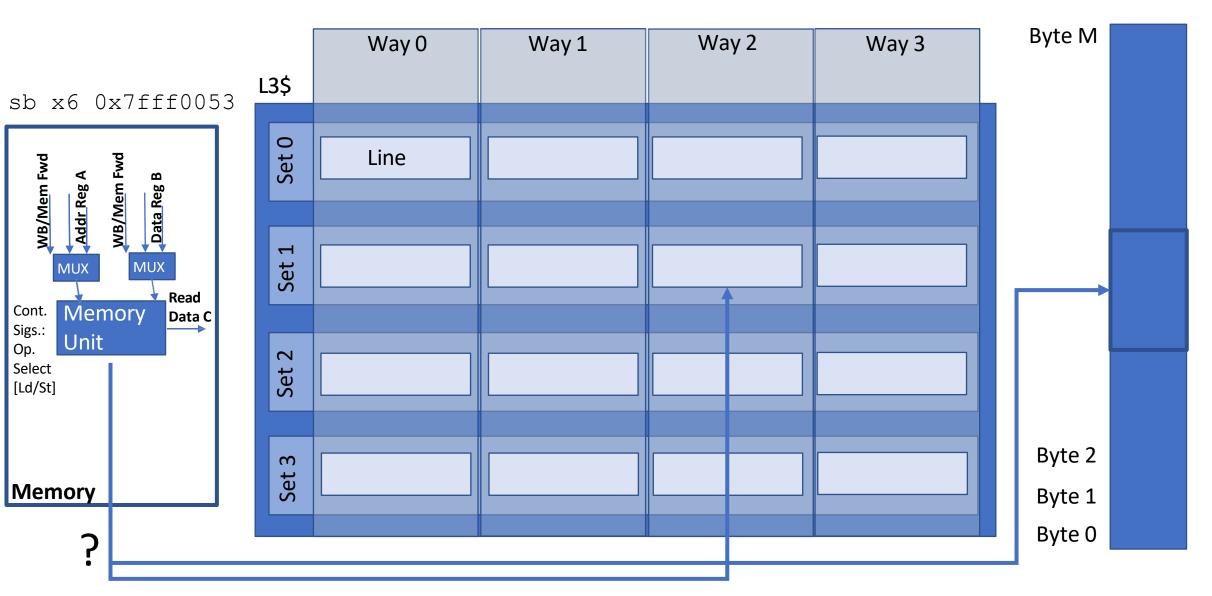
Tag Read Dynamic Energy = 1.01651pJ

Tag Write Dynamic Energy = 0.758075pJ

Higher associativity avoids conflict misses at an additional cost in hit latency & energy

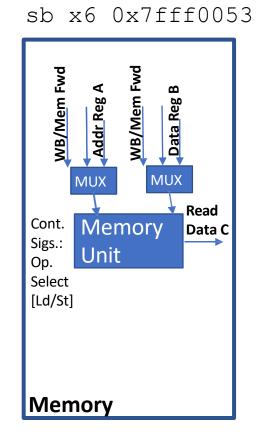
Write-Allocate: Stores go to cache Write-No-Allocate: Stores do not go to cache

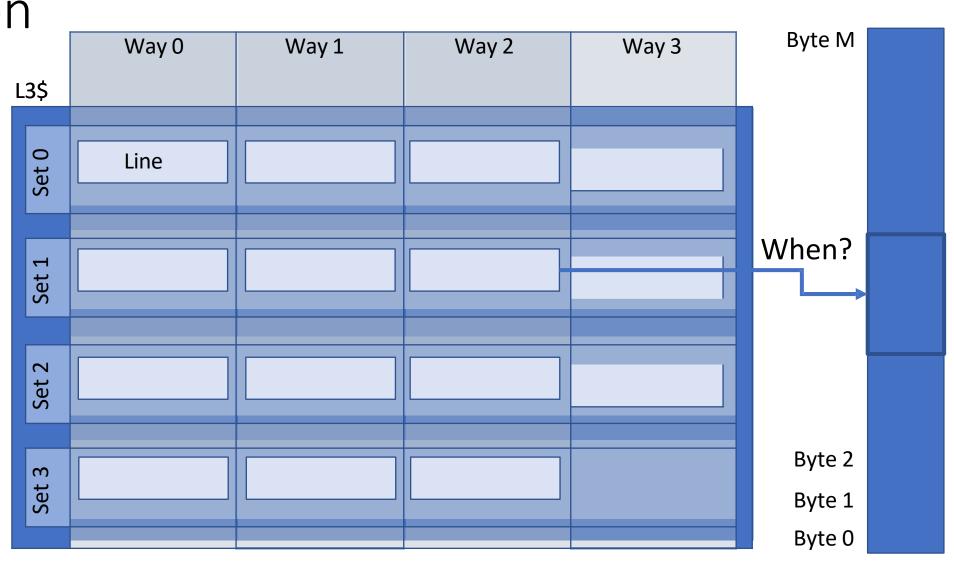
#### Write Policies - Allocation



Write Policies - Propagation \_\_

Write-Back: Wait until line evicted to writeback Write-Through: Writeback immediately on store





#### Recall 18x13: Snoopy Caches

#### Tag each cache block with state

Invalid Cannot use value Shared Readable copy

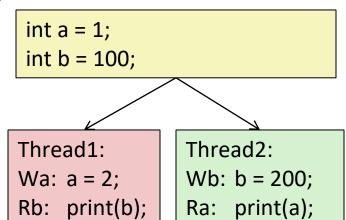
Exclusive Writeable copy

Thread1 Cache

E a: 2

| E b:200 |

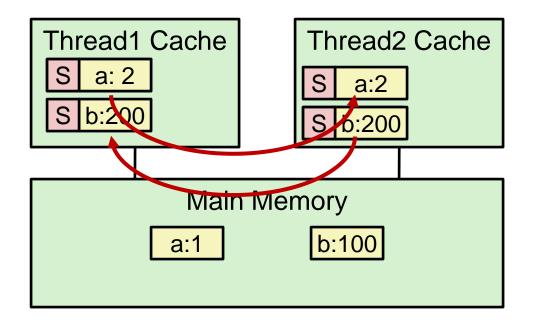
| Main Memory |
| a:1 |
| b:100 |

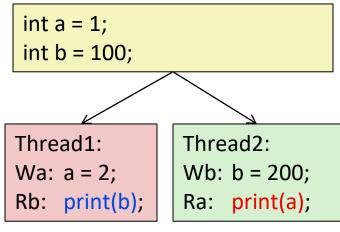


#### Recall 18x13: Snoopy Caches

#### Tag each cache block with state

Invalid Cannot use value
Shared Readable copy
Exclusive Writeable copy



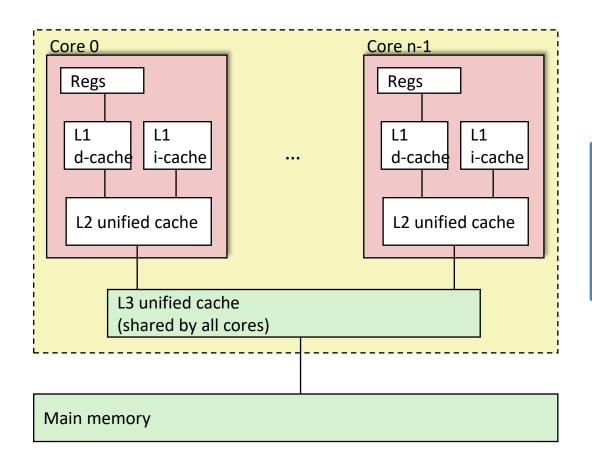


print 2

print 200

- When cache sees request for one of its E-tagged blocks
  - Supply value from cache (Note: value in memory may be stale)
  - Set tag to S

## Recall 18x13: Typical Multicore Processor

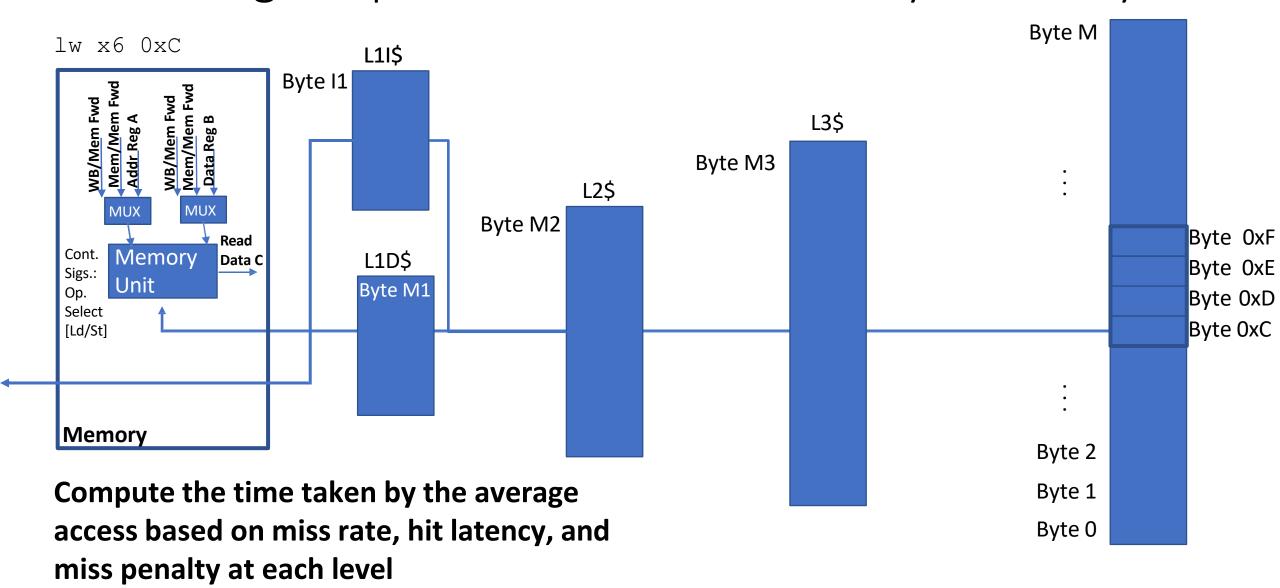


Propagation Policy v. Multicore Cache Coherency

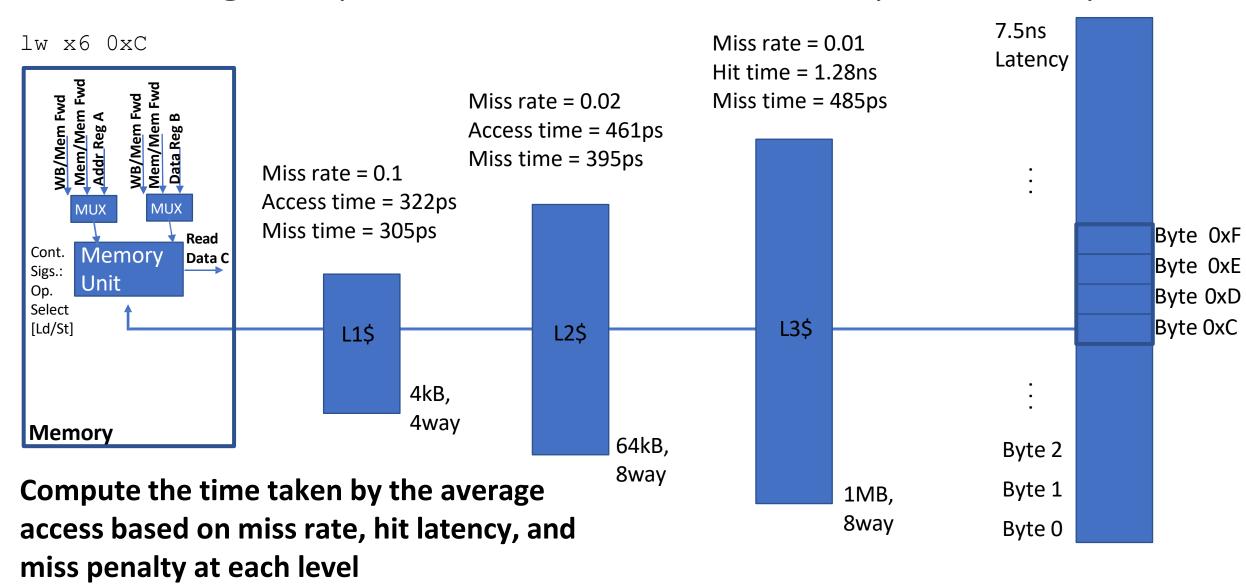
- What is required for a snooping?
- How does propagation policy facilitate or impede this?
- What does this suggest about cache policy by level?

Cache Hierarchy Performance Measurement

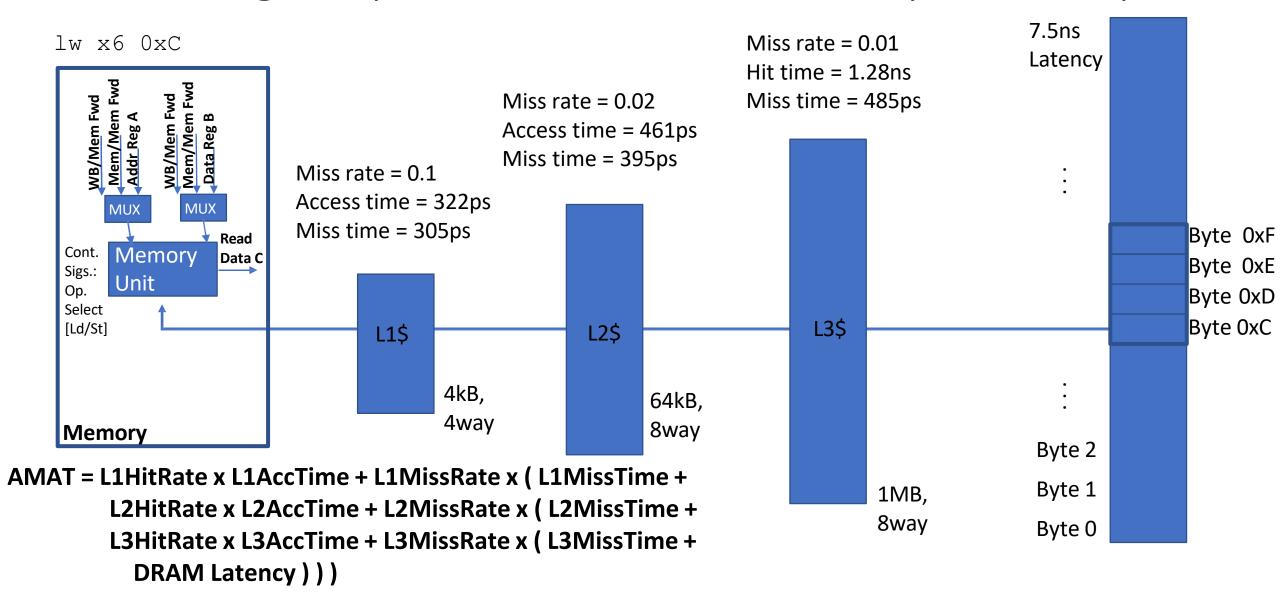
## Average Memory Access Time (AMAT): Measuring the performance of a memory hierarchy



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#### Computing the AMAT 1/2/4/23 90% hits

Miss rate = 0.1 Access time = 322ps (1 cycle @ 3GHz) Miss time = 305ps Miss rate = 0.02 Access time = 461ps (2 cycles @ 3GHz) Miss time = 395ps Miss rate = 0.01 Hit time = 1.28ns (4 cycles @ 3GHz) Miss time = 485ps

DRAM Latency 7.5ns (CAS latency) (23 cycles @ 3GHz)

$$1 \times 0.9 + 0.1 \times (1 + 2 \times 0.98 + 0.02 \times (2 + 4 \times 0.99 + 0.01 \times (2 + 23)))$$
 AMAT in Cycles

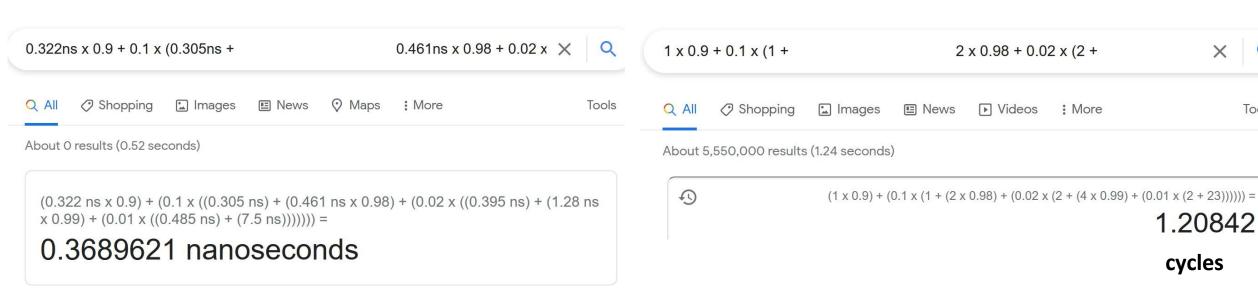
#### Computing the AMAT

Miss rate = 0.1Access time = 322ps Miss time = 305ps

Miss rate = 0.02Access time = 461ps Miss time = 395ps

Miss rate = 0.01Hit time = 1.28ns Miss time = 485ps **DRAM Latency** 7.5ns (CAS latency)

Tools



### Computing the AMAT – 2/5/10/30 90% hits

Miss rate = 0.1 Access time = 2 cycles Miss time = 2 cycles Miss rate = 0.02 Access time = 5 cycles Miss time = 5 cycles Miss rate = 0.01 Hit time = 10 cycles Miss time = 10 cycles

DRAM Latency 30 cycles

 $2 \times 0.9 + 0.1 \times (2 +$ 

$$5 \times 0.98 + 0.02 \times (5 +$$

**AMAT** in cycles

## Computing the AMAT $- \frac{2}{5}/\frac{10}{30} 80\%$ hits

Miss rate = 0.2 Access time = 2 cycles Miss time = 2 cycles Miss rate = 0.02 Access time = 5 cycles Miss time = 5 cycles Miss rate = 0.01 Hit time = 10 cycles Miss time = 10 cycles

DRAM Latency 30 cycles

 $2 \times 0.8 + 0.2 \times (2 +$ 

**AMAT** in cycles

$$10 \times 0.99 + 0.01 \times (10 +$$

The ABCs of Optimizing a Cache

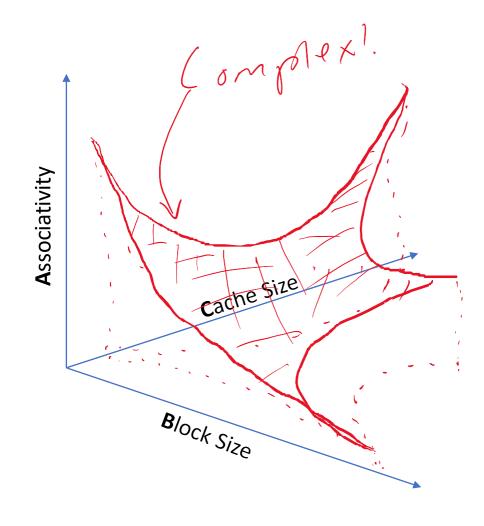
#### Associativity vs. Block Size vs Cache Size

## Many complex inter-dependent factors determine cache performance

- Associativity
- Block Size
- Cache Size
- Replacement Policy
- Write allocation policy
- Write propagation policy

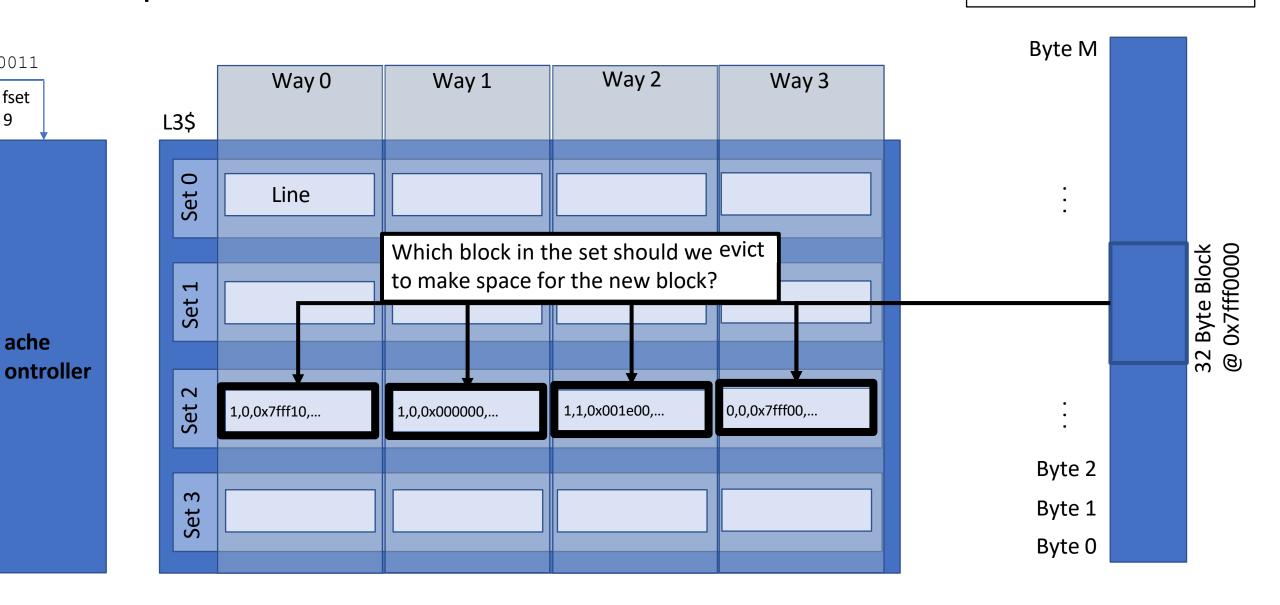
#### Best option depends on workload!

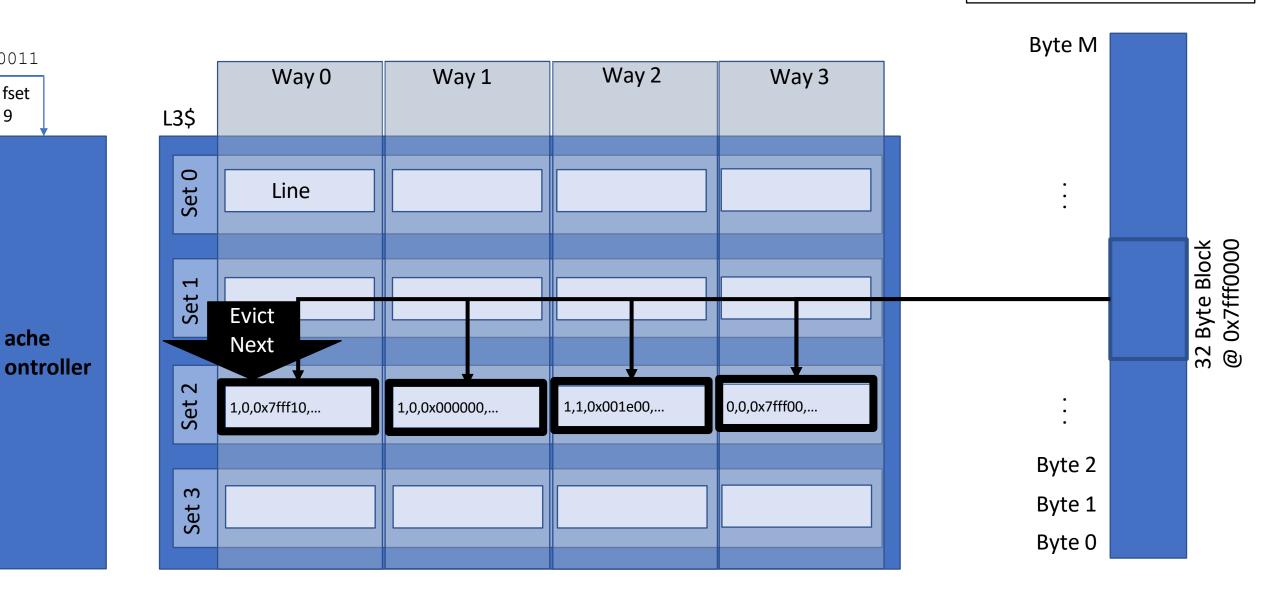
 Factors will sometimes work against one another, where improving degrades another. (we will study this next week)

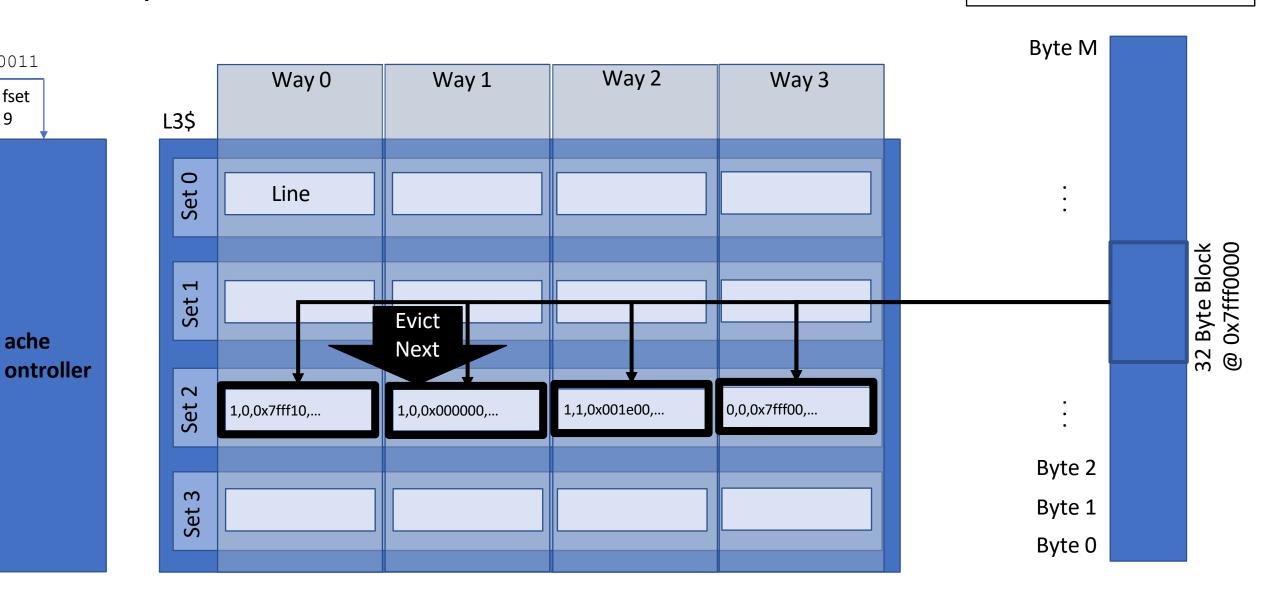


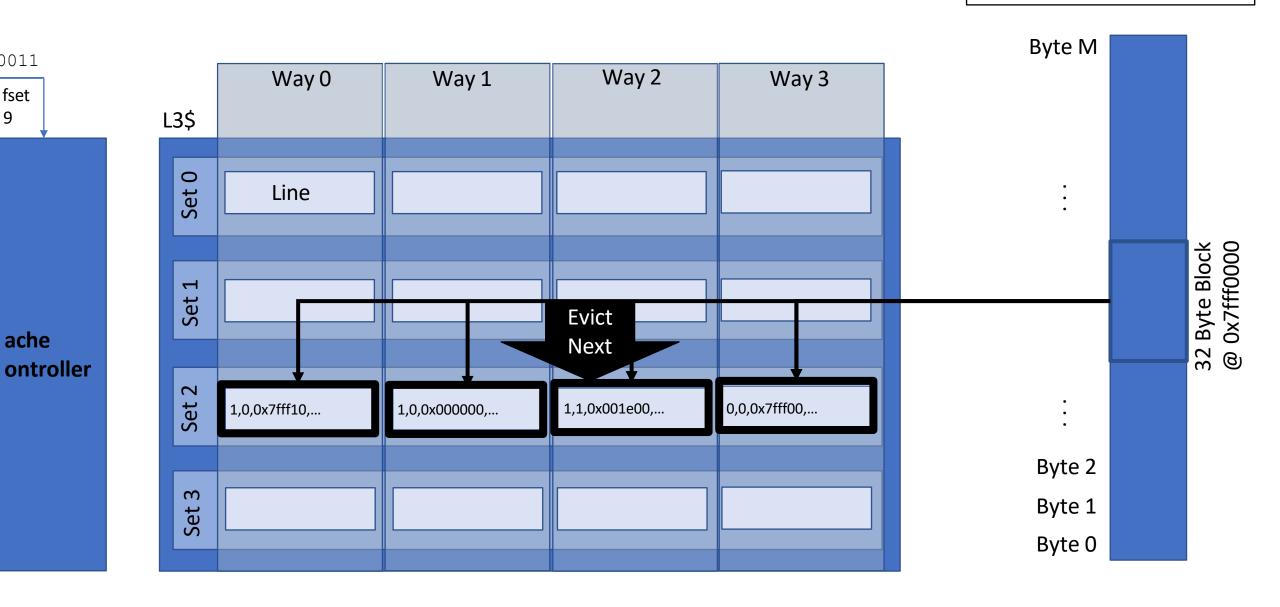
Replacement Policies

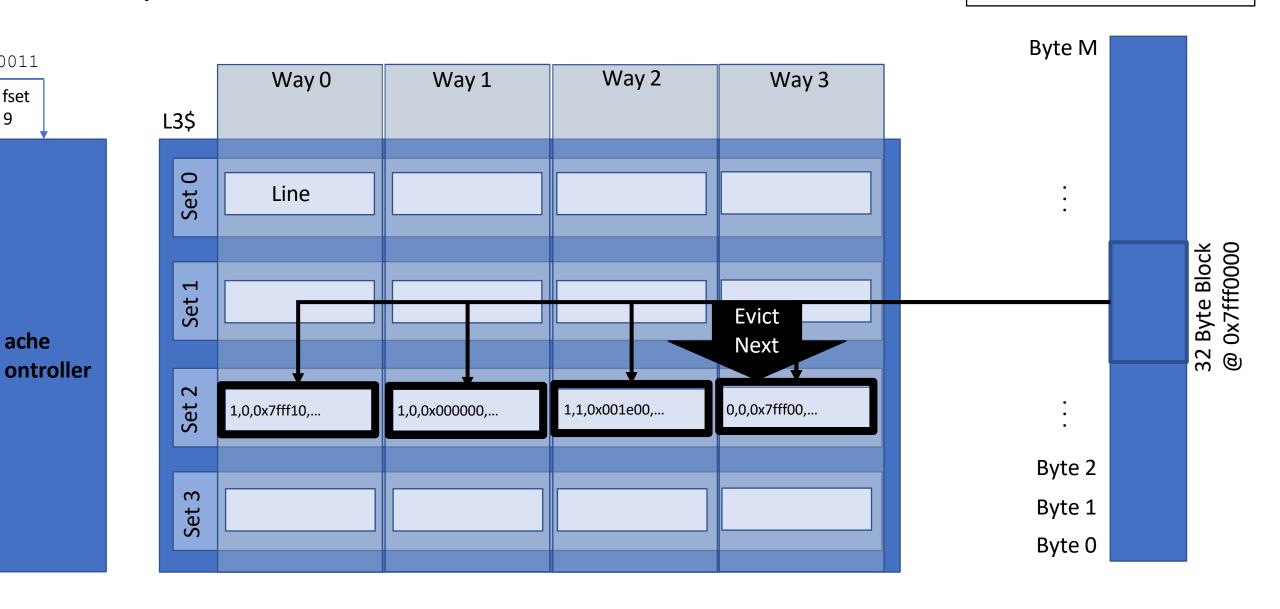
#### Replacement Policies

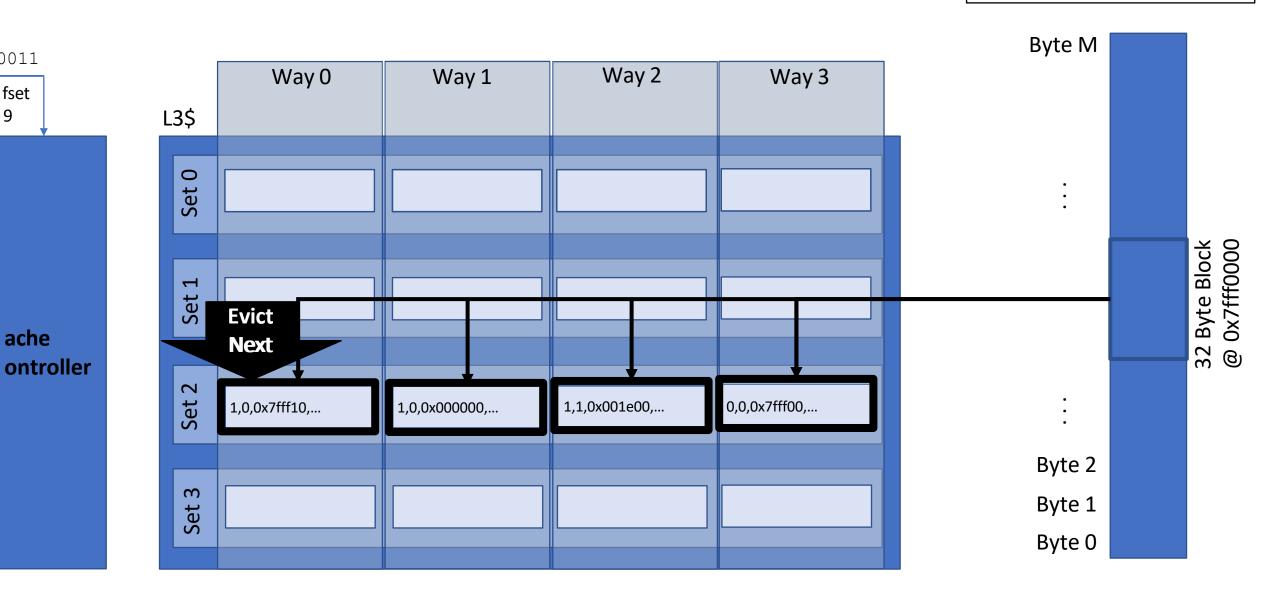


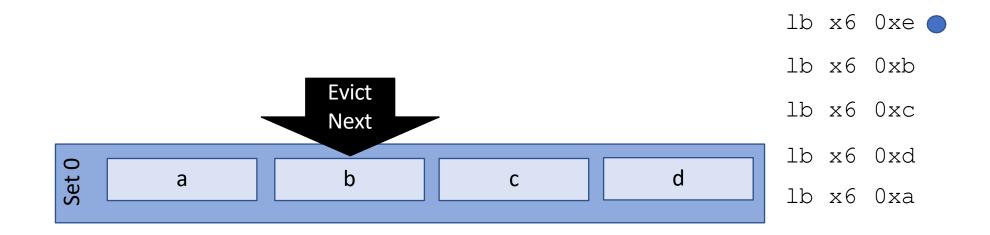




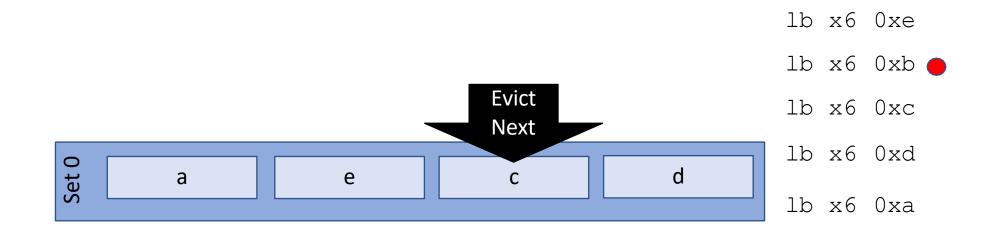




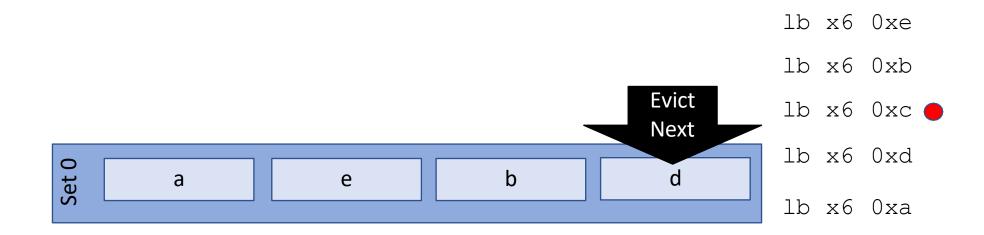




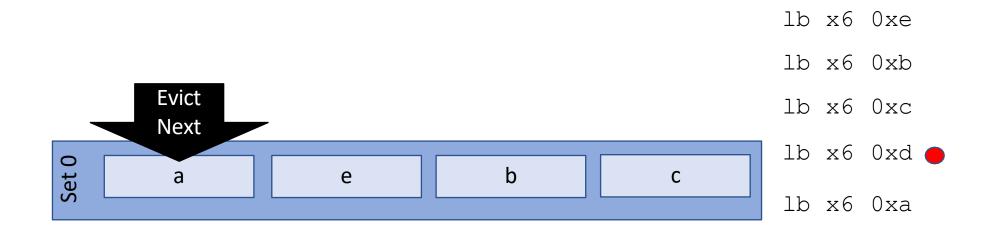
Advantage: Simple to implement and understand



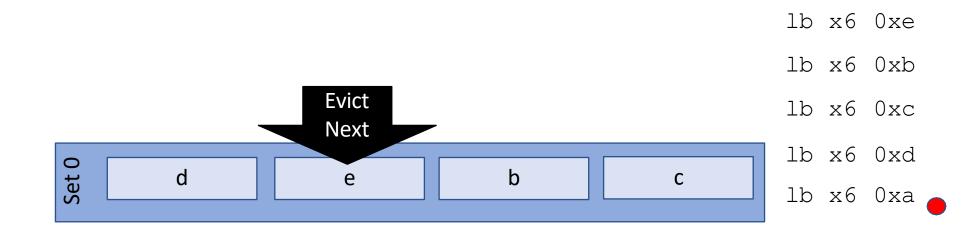
Advantage: Simple to implement and understand



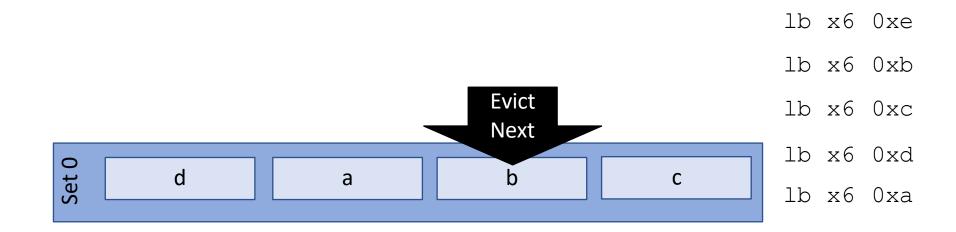
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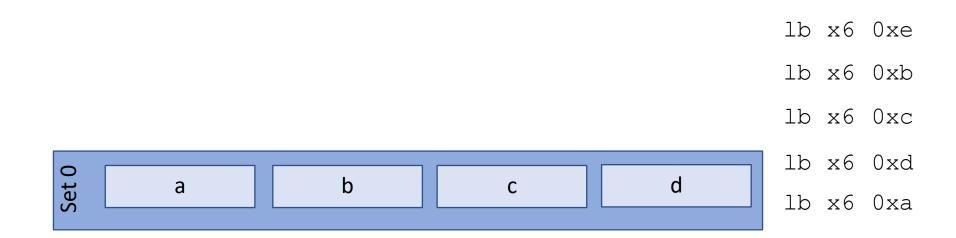


Advantage: Simple to implement and understand



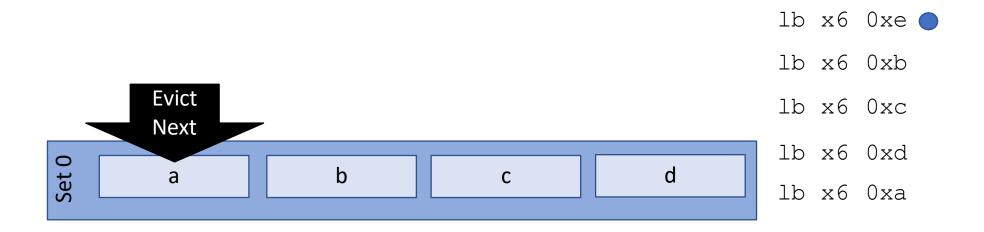
Advantage: Simple to implement and understand

#### Minimum Number of Misses?

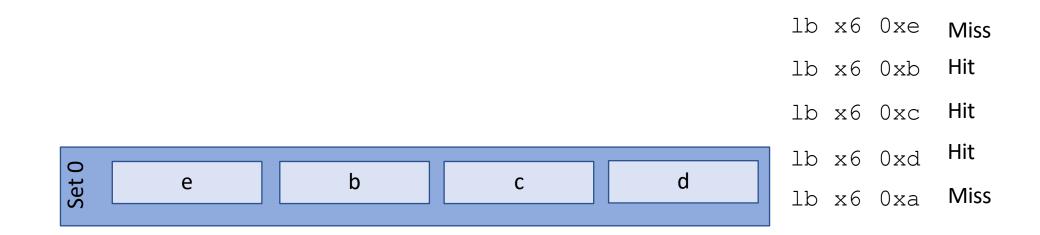


What is the best replacement strategy to minimize misses & why?

#### Minimum Number of Misses?



#### When are we going to re-use cached data?



Replacement decisions must be informed by the next reuse of a block of data.

Think: what is an optimal policy? How far in the future is something going to be used again?

#### What did we just learn?

- Memory has a high access cost; memory hierarchy mitigates that cost
- Caches make locality exploitable to optimize for data reuse
- Review of the basics of cache operation, address decomposition, set associative caches
- Miss types
- The costs of associativity & tag storage arrays
- What to do about writes?
- The replacement problem

#### What to think about next?

- More caches (next time)
  - Replacement from the ground up
  - Caching optimizations: victim caches, write buffers & lockup-free caches, prefetching, way partitioning, banking & bank conflicts
  - Scratchpads vs. Caches & their relation to the HW/SW interface
- Performance Evaluation (next next time)
  - Design spaces, Pareto Frontiers, and design space exploration
- Miscellaneous (micro)architectural tricks & optimizations (future)
  - Vector processors, SIMD/SIMT, dataflow

Replacement Policies – Not Most Recently Used

### Replacement Policies - PLRU

# Replacement Policies - SRRIP

### Replacement Policies – Belady Optimal

### Replacement Policies – Hawkeye

### Victim Caches

# Banking & Bank Conflicts

# Bank Mapping Function

#### NUCA, SNUCA, DNUCA, RNUCA

# Cache Partitioning

# Prefetching

# Non-temporal Stores

# Scratchpads

#### What to think about next?

- Caches as a microarchitectural optimization (next time)
  - Implementation of cache hierarchies
  - Cache design tradeoffs
- Performance Evaluation (next next time)
  - Design spaces, Pareto Frontiers, and design space exploration
- Miscellaneous (micro)architectural tricks & optimizations (future)
  - Vector processors, SIMD/SIMT, dataflow