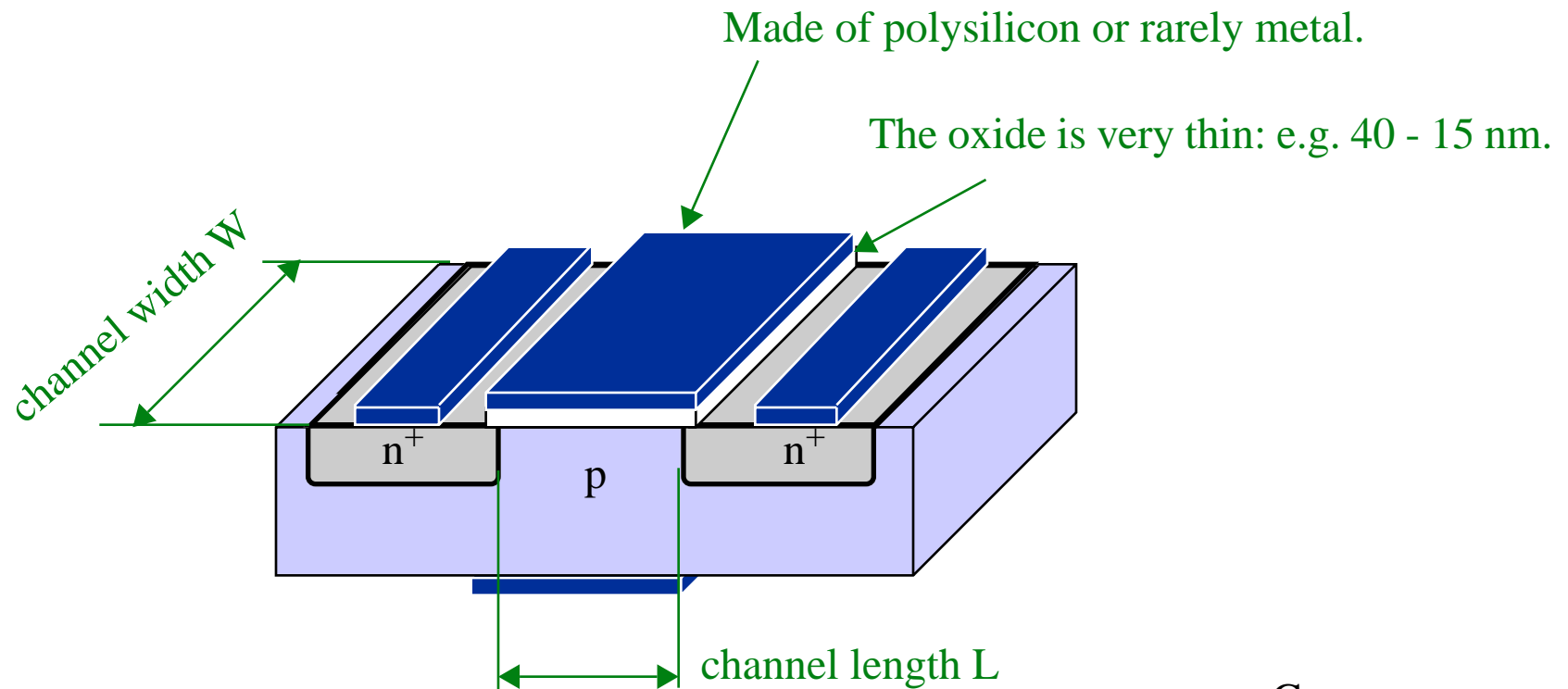


# FETs: Field Effect Transistors

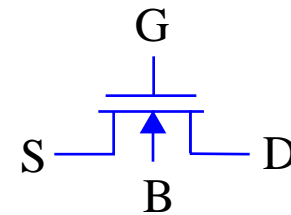
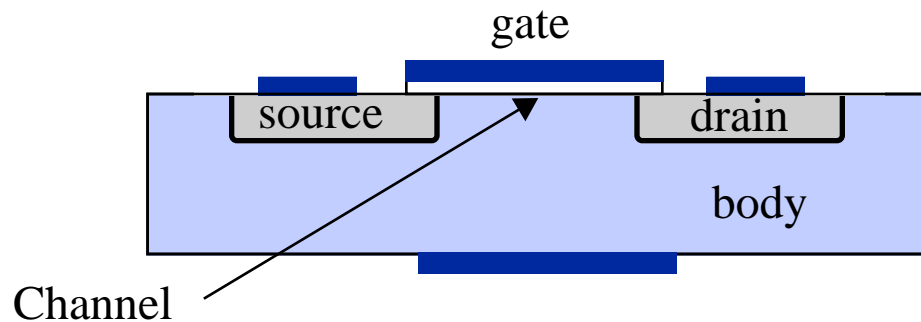
- **MOSFETs:** Metal-Oxide Semiconductor Field Effect Transistors
  - gates are really polysilicon, not metal
  - extremely large input resistance
  - four terminal devices
  - occupy less area than BJTs --- predominant technology for digital
  - but do not provide the same gain as BJTs for analog
- Used for analog mainly due to the need mixed-signal designs
- **JFETs:** Junction Field Effect Transistors
  - not as popular as MOSFETs, but behave very similarly

# Enhancement Mode MOSFETs

- The basic structure of an enhancement mode mosfet

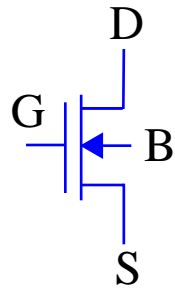


- Cross-section view

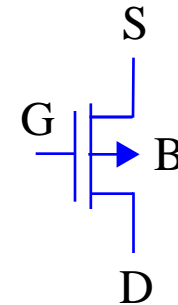


# Enhancement Mode MOSFETs

- NOTE: 4 terminals!!!



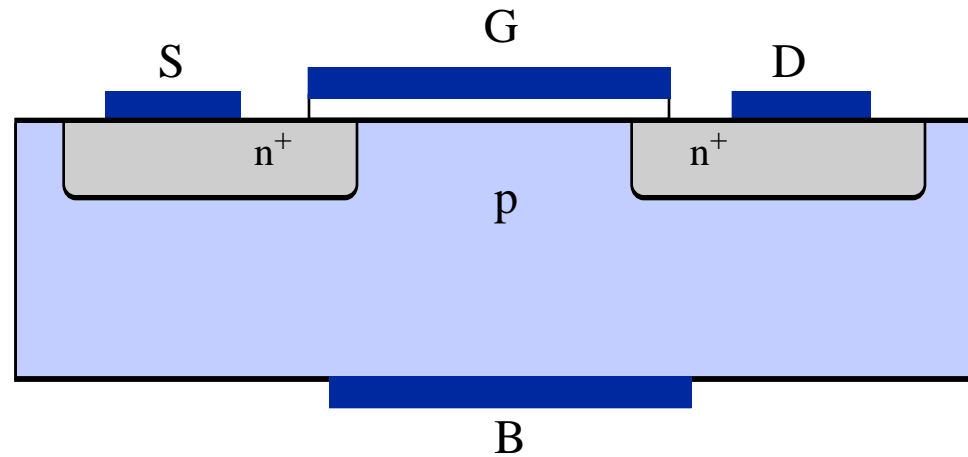
n-channel transistor  
or N-MOSFET  
(p-type substrate)



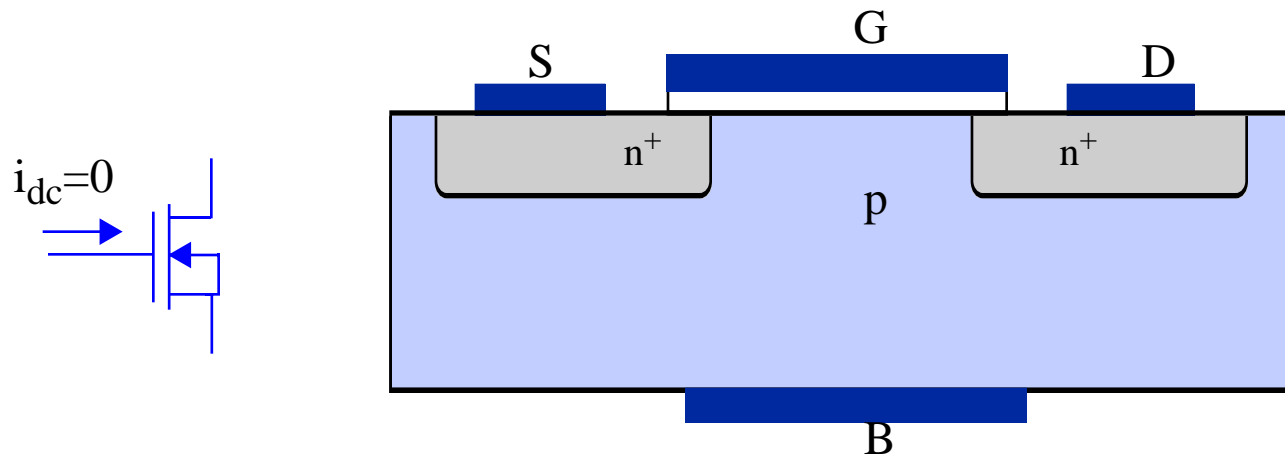
p-channel transistor  
or P-MOSFET  
(n-type substrate)

## Enhancement Mode MOSFETs

- We keep the source and drain p-n junctions off at all times
- They contribute small leakage currents, and some nonlinear capacitance

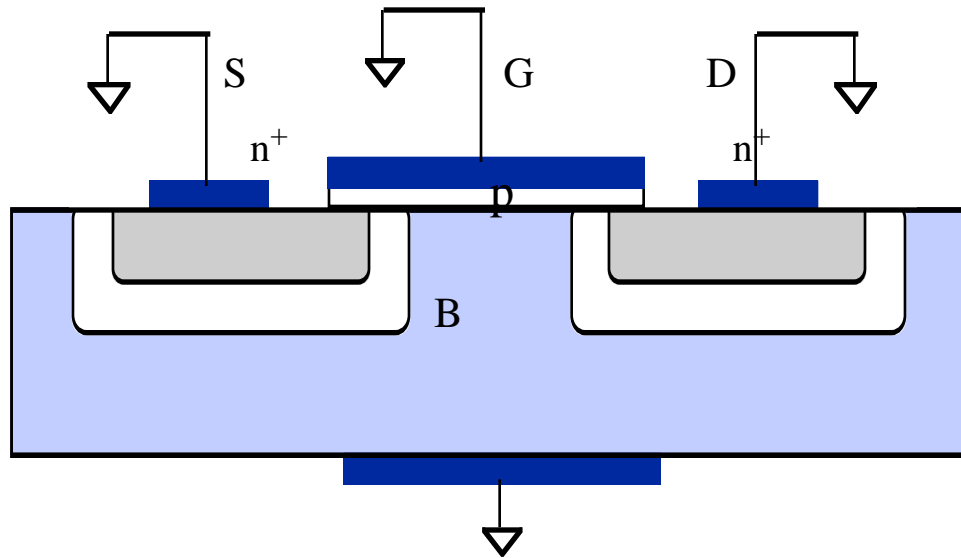


- The gate input has practically infinite resistance, and behaves like a capacitor

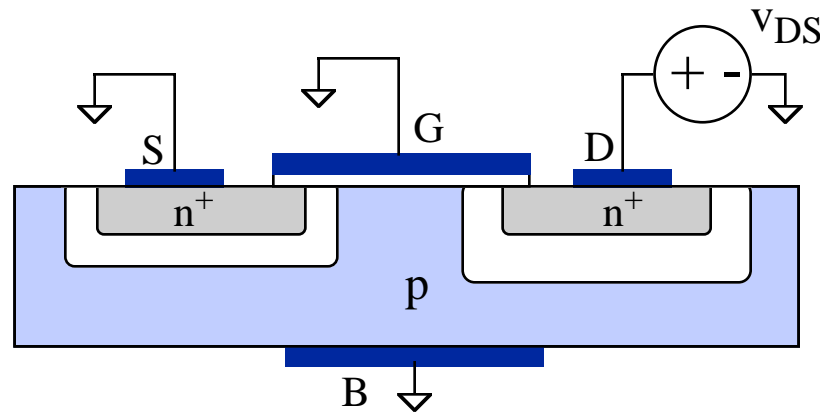


## Enhancement Mode MOSFETs

- Depletion regions around the p-n junctions due to the built-in voltages
- With all of the voltages set to zero, the S-B-D connections form an NPN

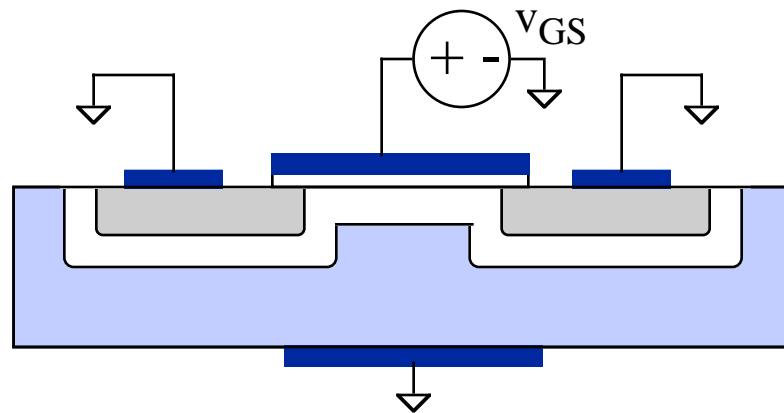


- Even with a positive drain voltage, there is no significant current flow



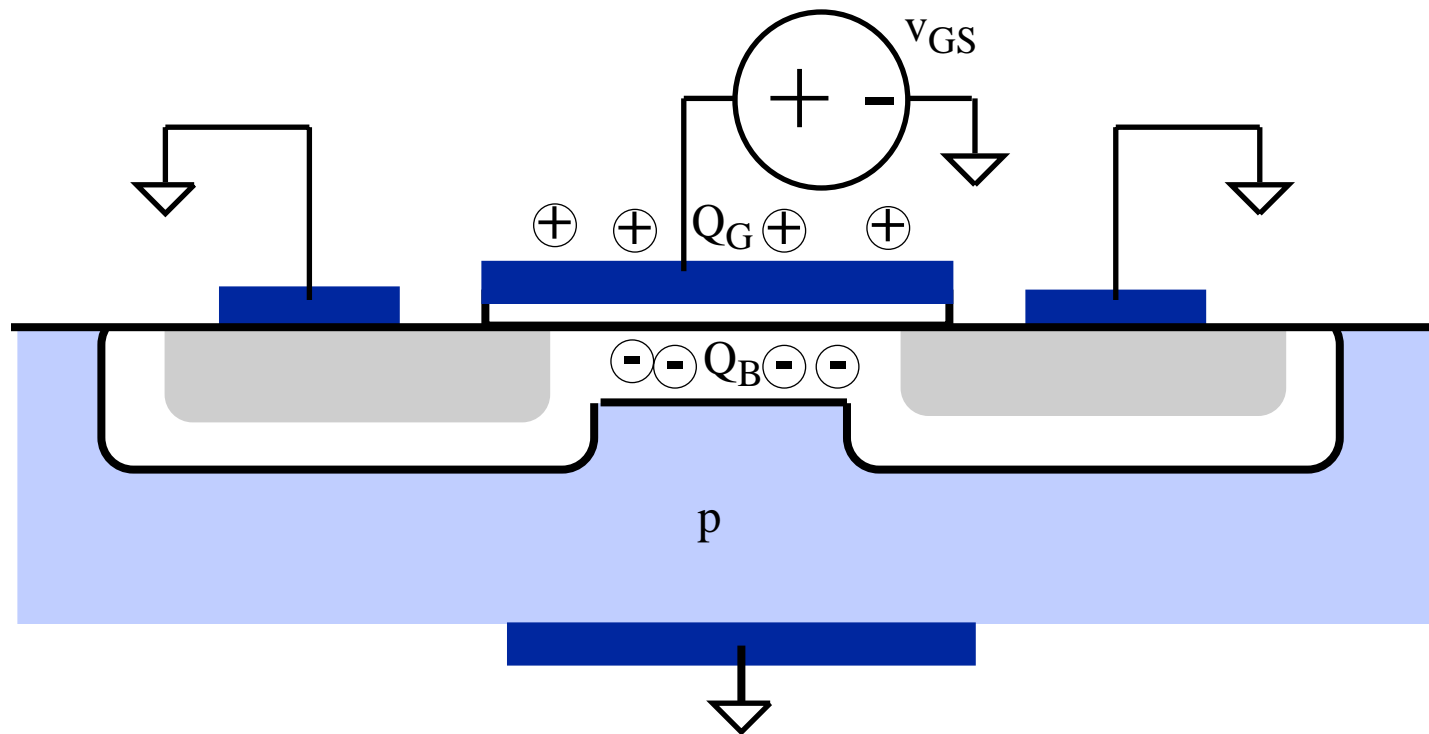
## Enhancement Mode MOSFETs

- The gate is used to establish a connection between the source and drain nodes
- Positive gate voltage (for this NMOS enhancement transistor):
  - sets up an electric field from gate to bulk which tends to repel positive charges in the p-type bulk and create a depletion region
  - negative charge from the source and drain regions is attracted toward the channel by the same electric field



# Enhancement Mode MOSFETs

- Gate to bulk acts like a capacitor

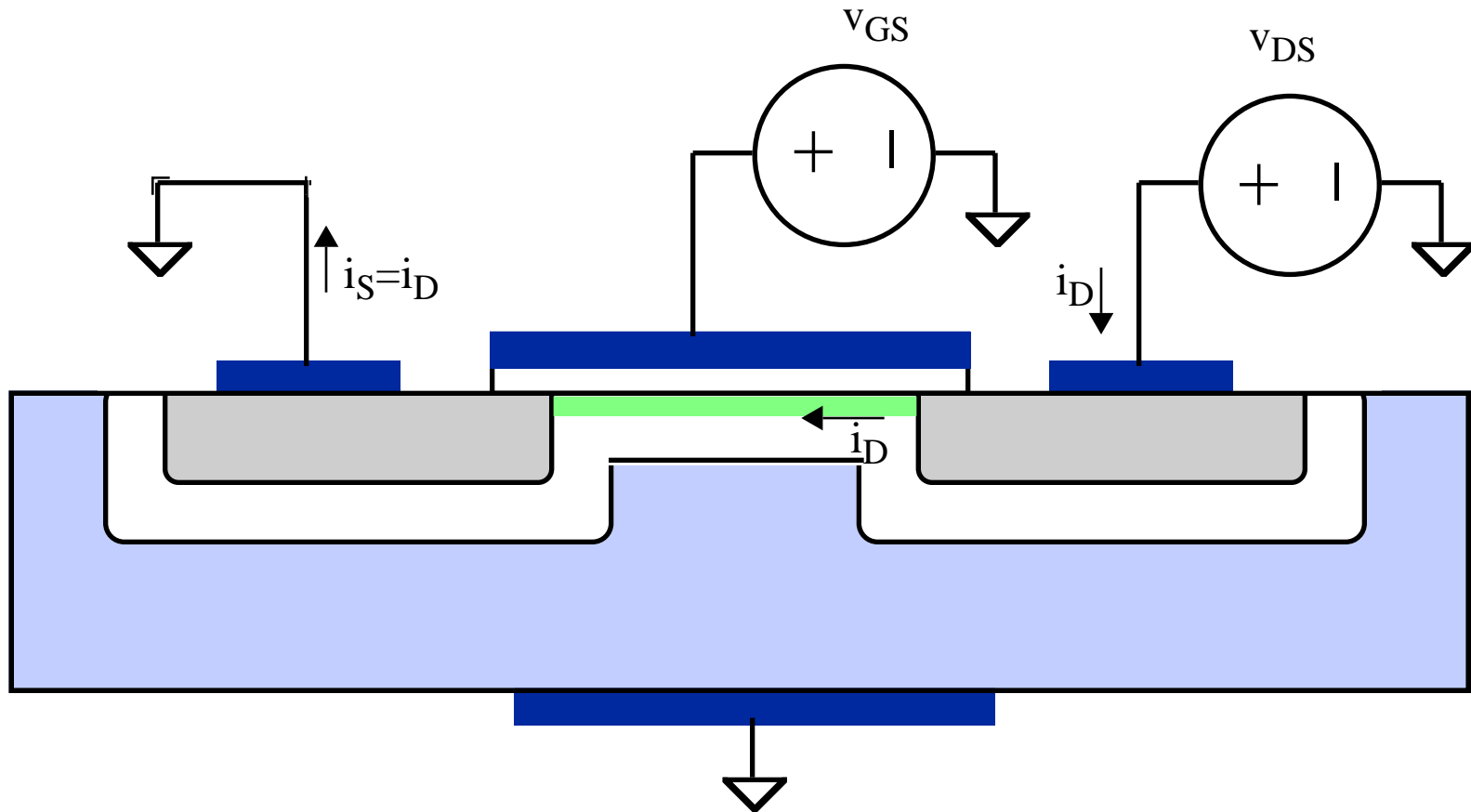






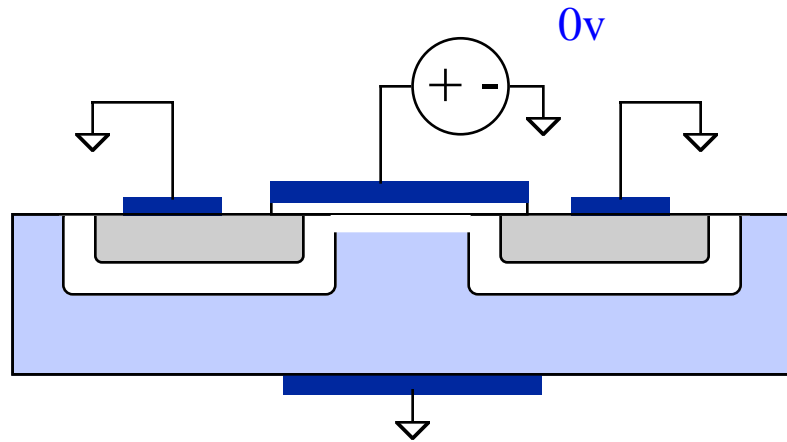
# Threshold Voltage

- The gate voltage required to create strong inversion
- If there is a small potential difference between the drain and source, then a current will flow across the inversion layer which acts like a resistor

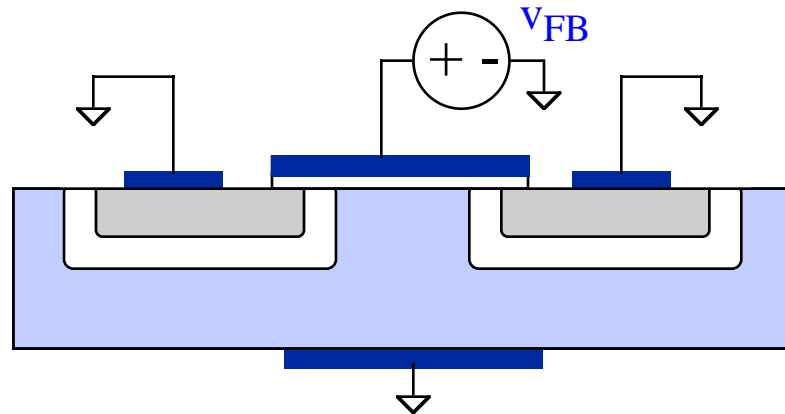


## Flatband Voltage -- $V_{FB}$

- There is a depletion region (negative  $Q$ ) under the channel even with  $V_{GS} = 0$ 
  - Due to dangling bonds at the material interfaces and unwanted positive charges at the surfaces and in the oxides

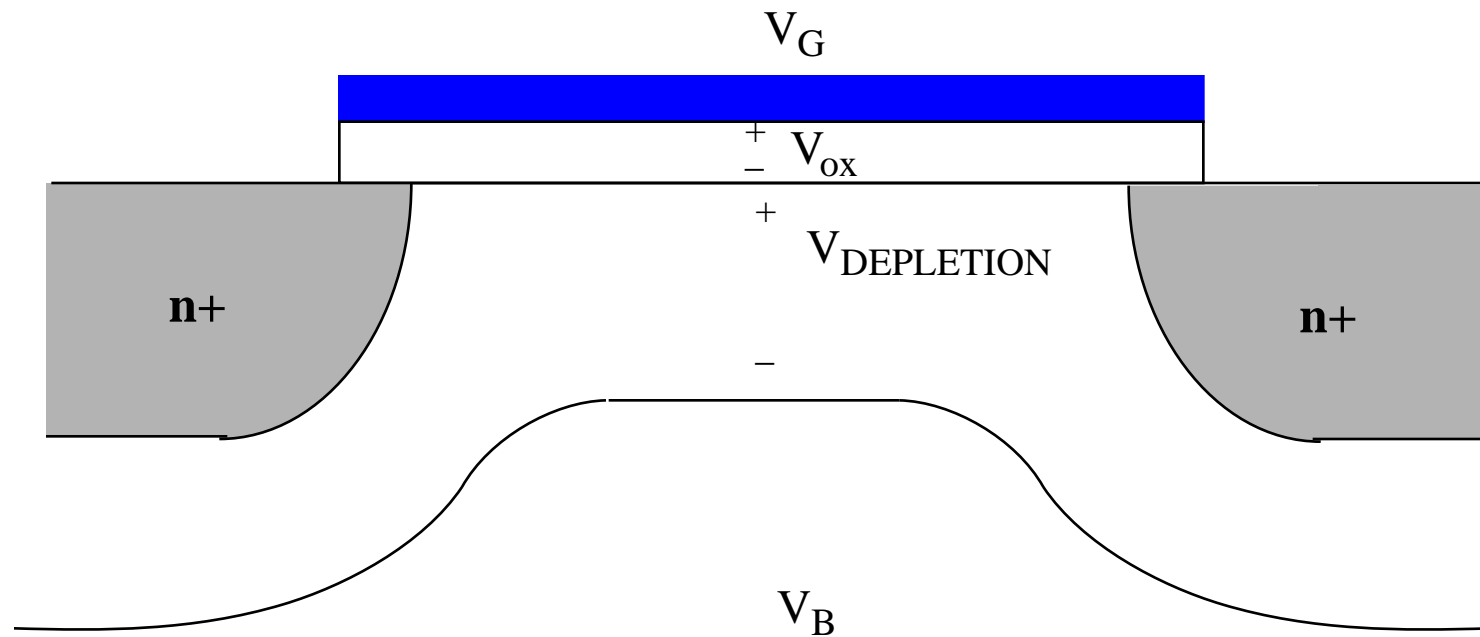


- The flatband voltage (generally negative) is the gate voltage required to exactly cancel this charge



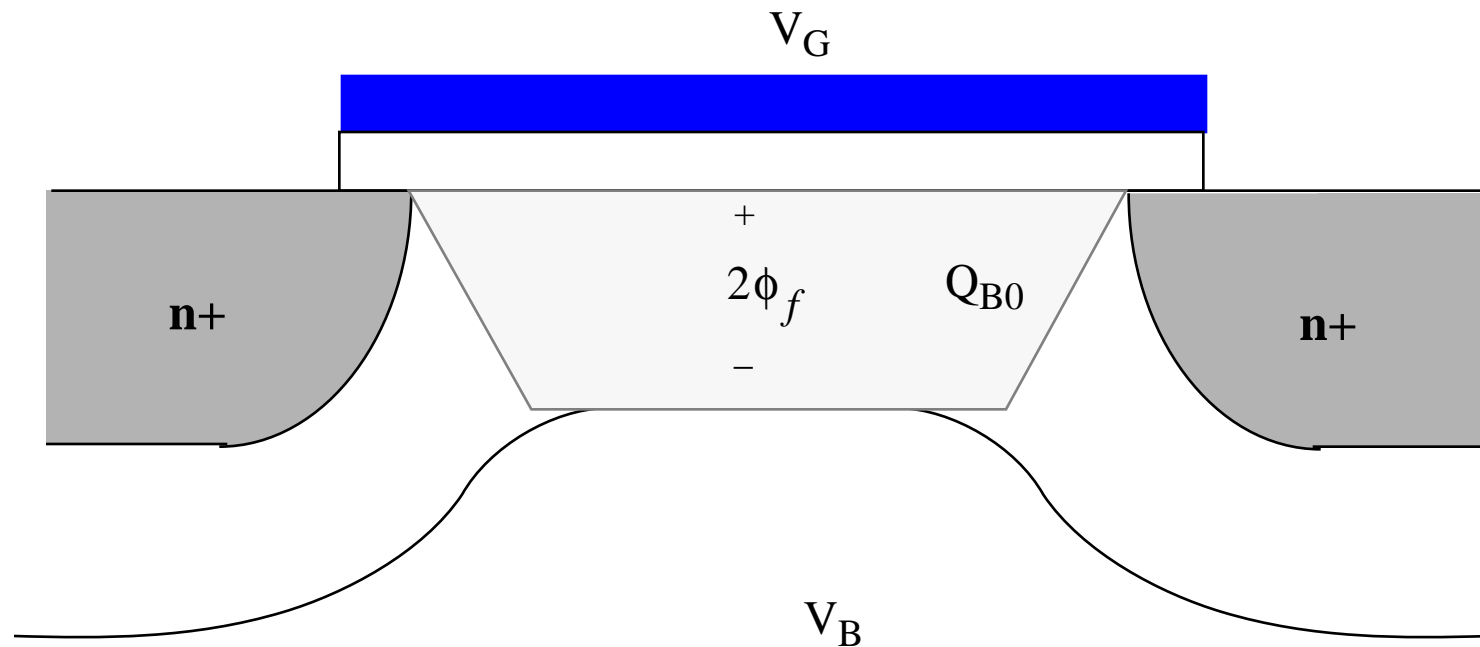
# Threshold Voltage

- The threshold voltage is the flatband voltage plus whatever voltage is required to cause inversion in the channel



# Threshold Voltage

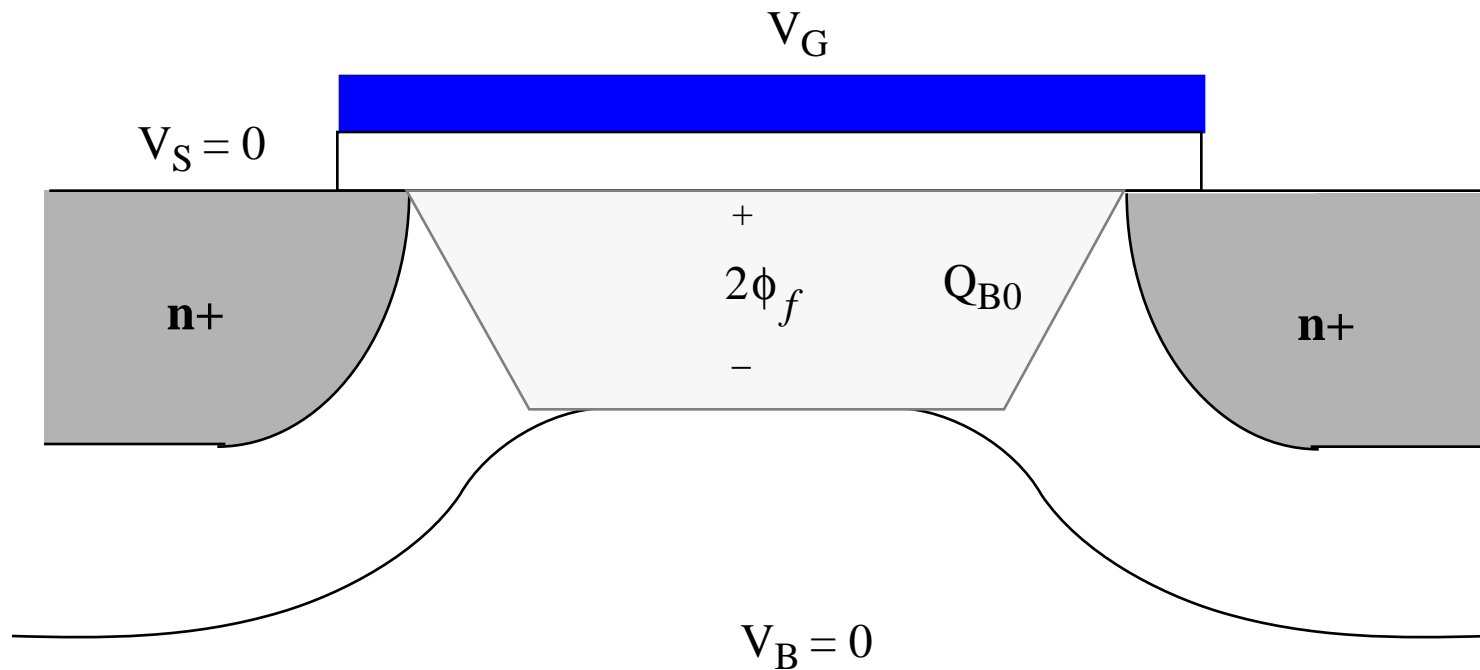
- Once  $-Q_B = N_A$ , then further increases in gate voltage brings about the inversion layer
- The depletion charge *and voltage* becomes fixed at a value called respectively:  $Q_{B0}$  and  $2\phi_f$
- Increases in channel charge correspond to the inversion layer charge,  $Q_I$



# Threshold Voltage

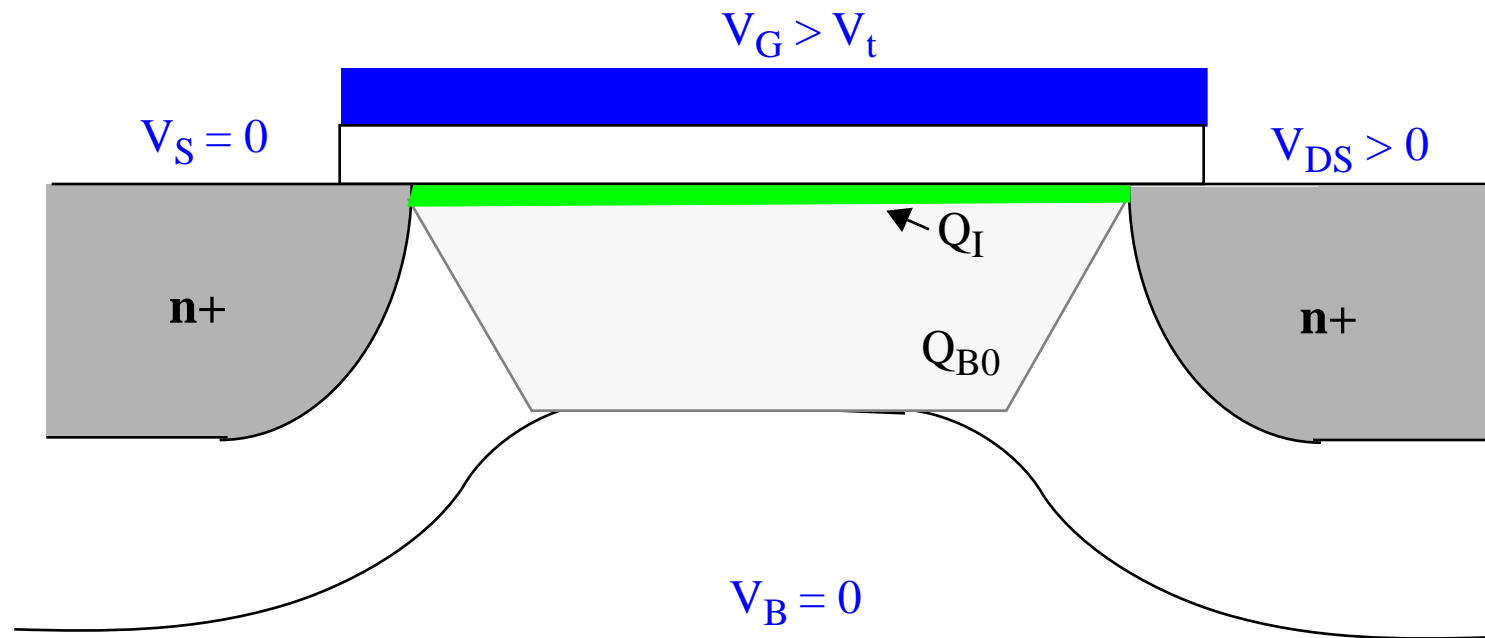
- Assuming  $V_B$  and  $V_S$  are both zero, the threshold voltage is:

$$V_{t0} = V_G|_{threshold} = V_{OX} + V_{DEPL} + V_{FB}$$



## Strong Inversion

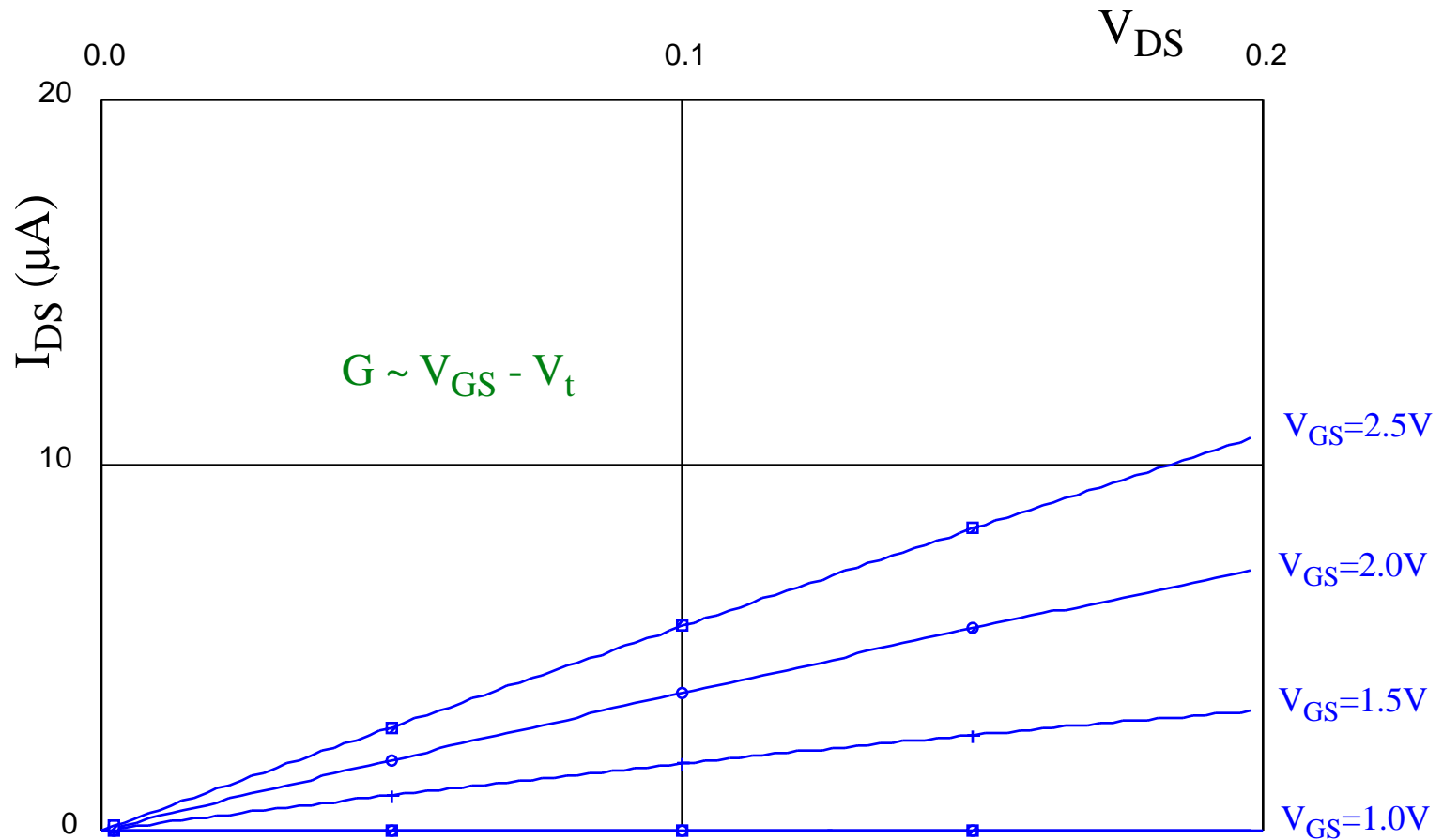
- With a small positive drain voltage, the inversion layer charge will drift from source to drain



- The conductance of the layer is proportional to  $V_{GS} - V_t$

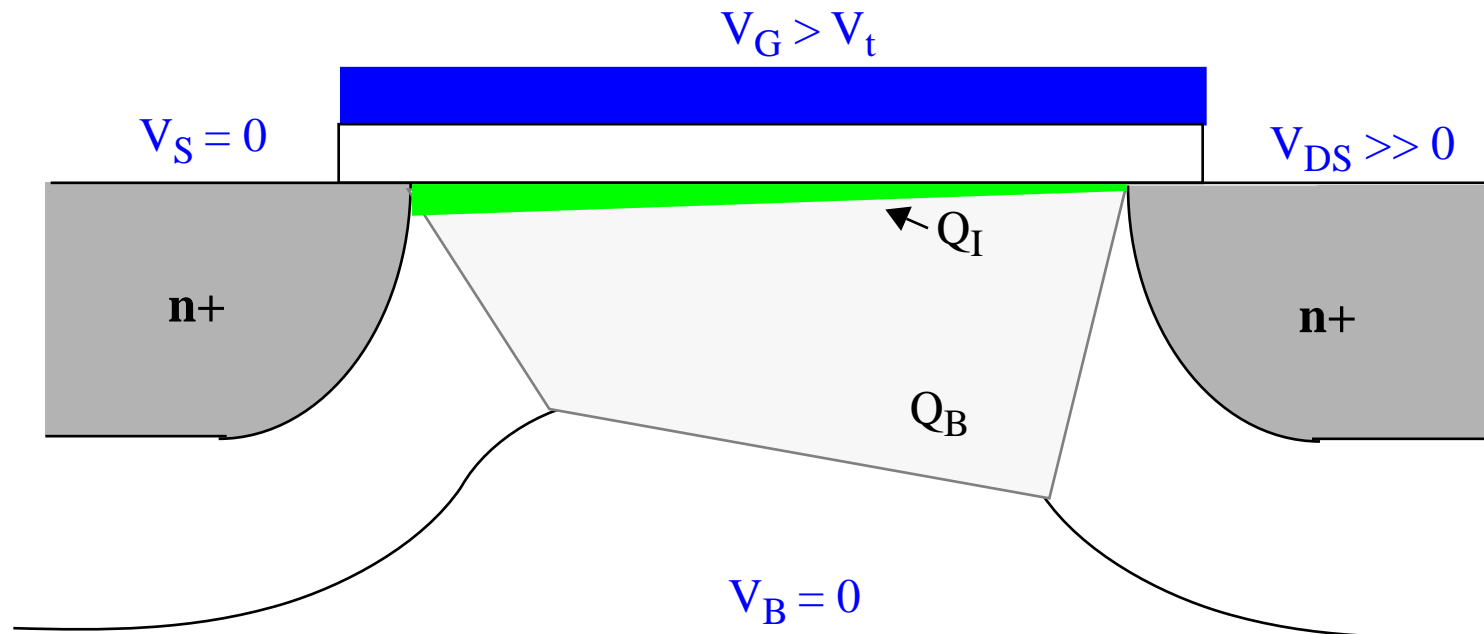
# Inversion Layer Conductance

- Triode or linear region of operation
- Example:  $W=L=1$  micron



## Pinch-Off Region --- Saturation

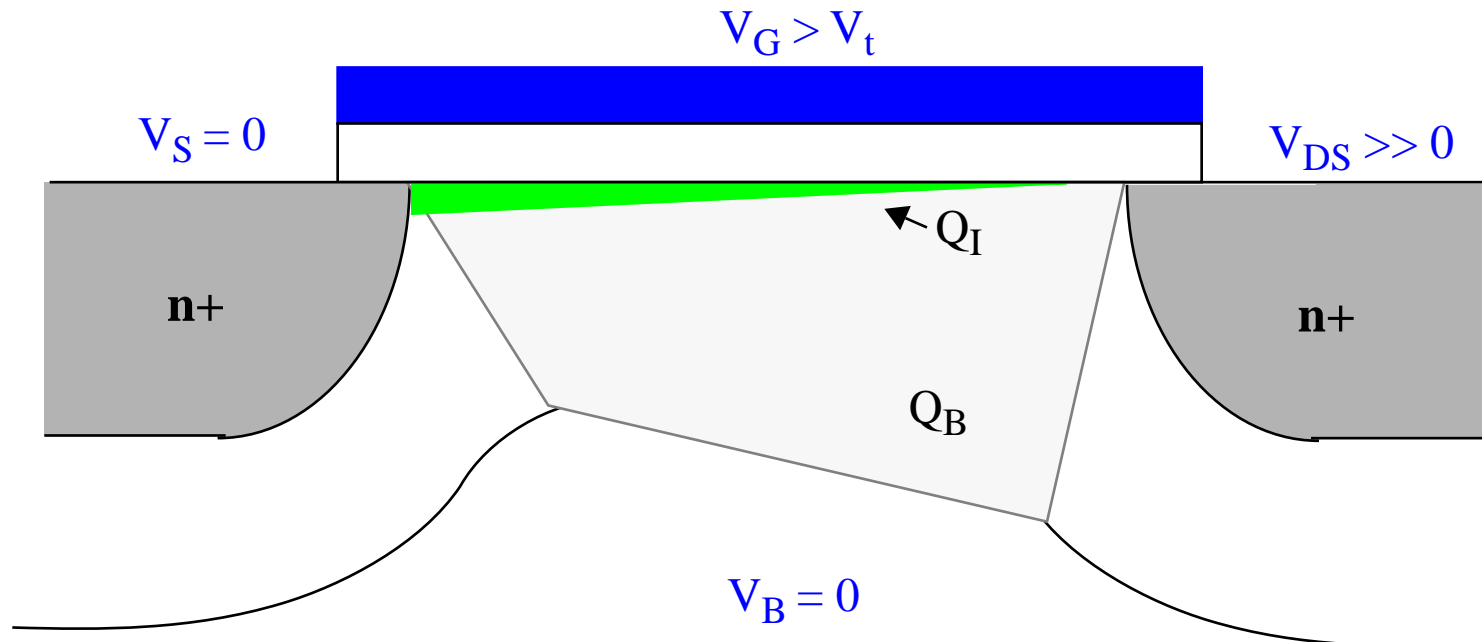
- The conductance is not always proportional to  $V_{GS} - V_t$  for all  $V_{DS}$
- As  $V_{DS}$  increases, the bulk charge closer to the drain increases, and the inversion layer charge there decreases
- Conductance varies with position along the channel





## Pinch-Off Region --- Saturation

- As  $V_{DS}$  increases further for a fixed  $V_{GS}$ , the inversion layer eventually goes to zero at the drain edge of the channel --- pinch-off

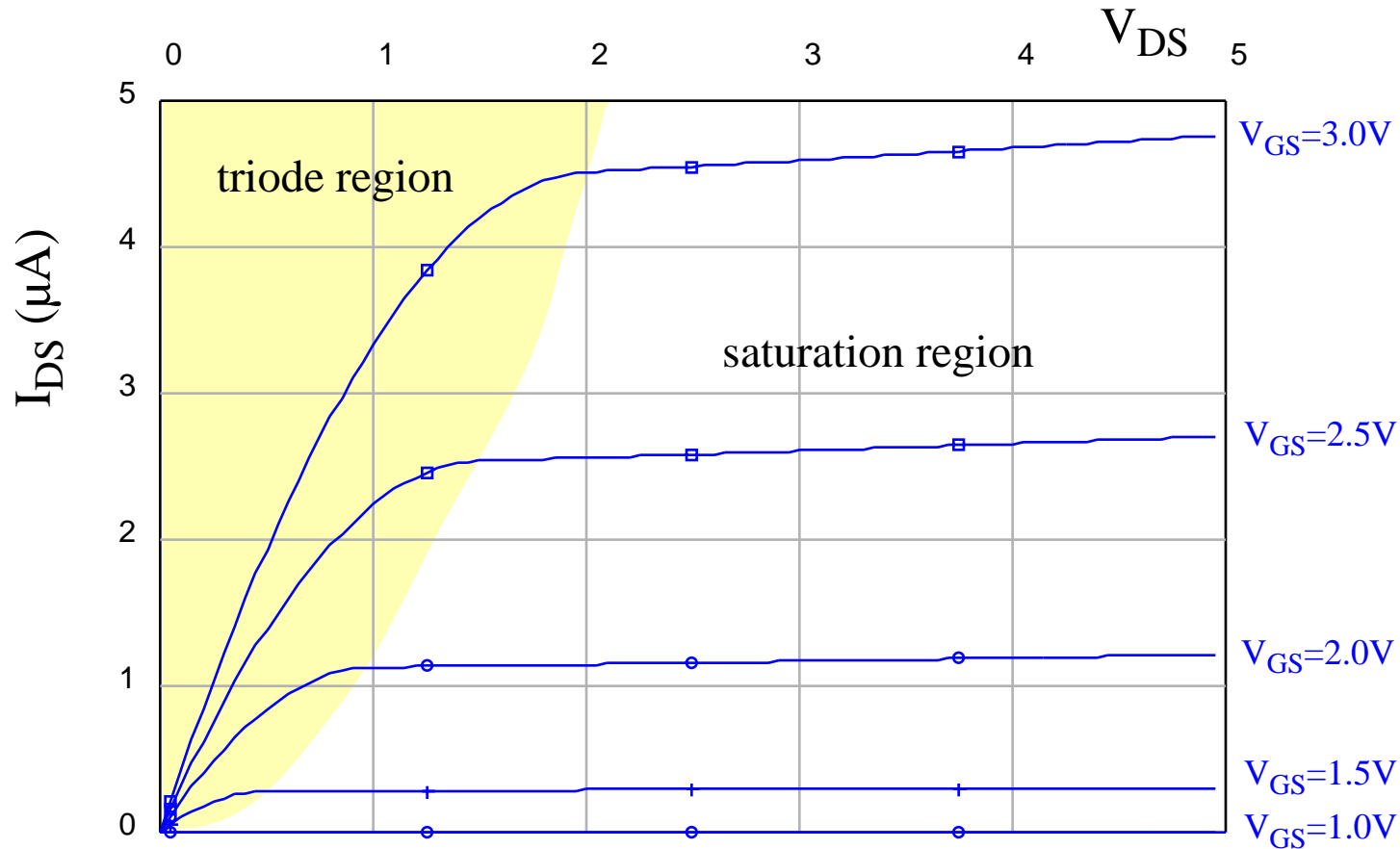


- Current is considered to **saturate** at this point since further increases in  $V_{DS}$  do not increase the current significantly

$$V_{DS}|_{sat} \cong V_{GS} - V_t \quad \text{why?}$$

# Saturation Region

- Region of interest for analog design
- $W=1$  micron and  $L=10$  microns



Here, saturation means “current saturation” which is **different** than “voltage saturation” in bipolar transistors

# Equations

- Triode region equations for enhancement mode N-MOSFET

$$v_{GS} \geq V_t \quad v_{DS} \leq v_{GS} - V_t$$

$$i_D = K[2(v_{GS} - V_t)v_{DS} - v_{DS}^2] \quad K = \frac{1}{2}\mu_n C_{ox} \frac{W}{L}$$

$$\text{In SPICE: } K_n = \mu_n C_{ox} \left[ \frac{A}{V^2} \right]$$

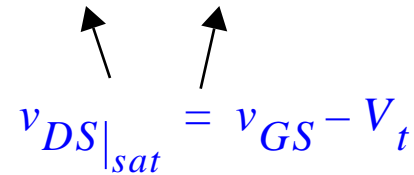
- For very small  $v_{DS}$ , as on page 15, what is  $r_{DS}$ ?

# Equations

- Saturation region equations for enhancement mode N-MOSFET

$$v_{GS} \geq V_t \quad v_{DS} \geq v_{GS} - V_t$$

$$i_D = K[2(v_{GS} - V_t)v_{DS} - v_{DS}^2]$$


$$v_{DS}|_{sat} = v_{GS} - V_t$$

$$i_D = K[(v_{GS} - V_t)]^2$$

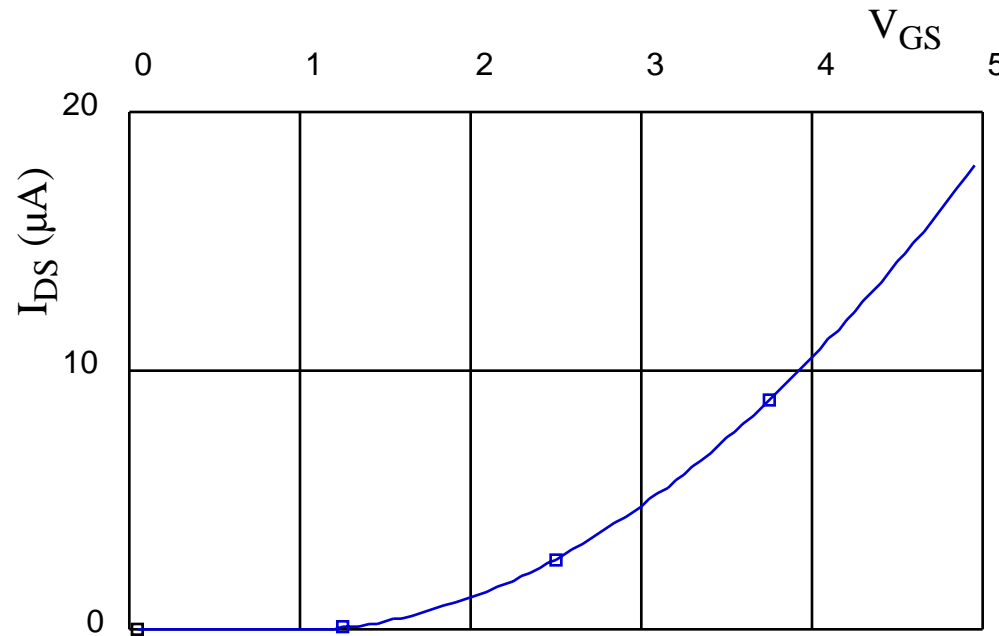
$$K = \frac{W}{2L}K_n$$

$$K_n = C_{ox}\mu_n$$

- Current varies quadratically with  $v_{GS}$

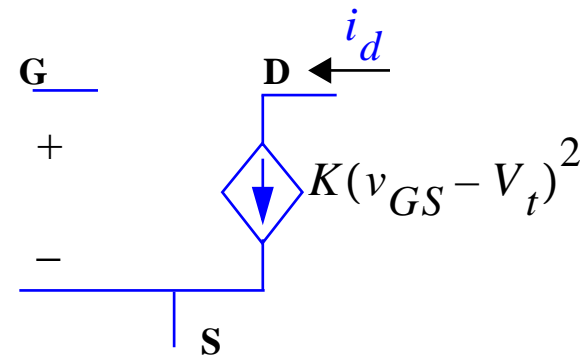
# Saturation

- For  $v_{DS} \geq v_{GS} - V_t$



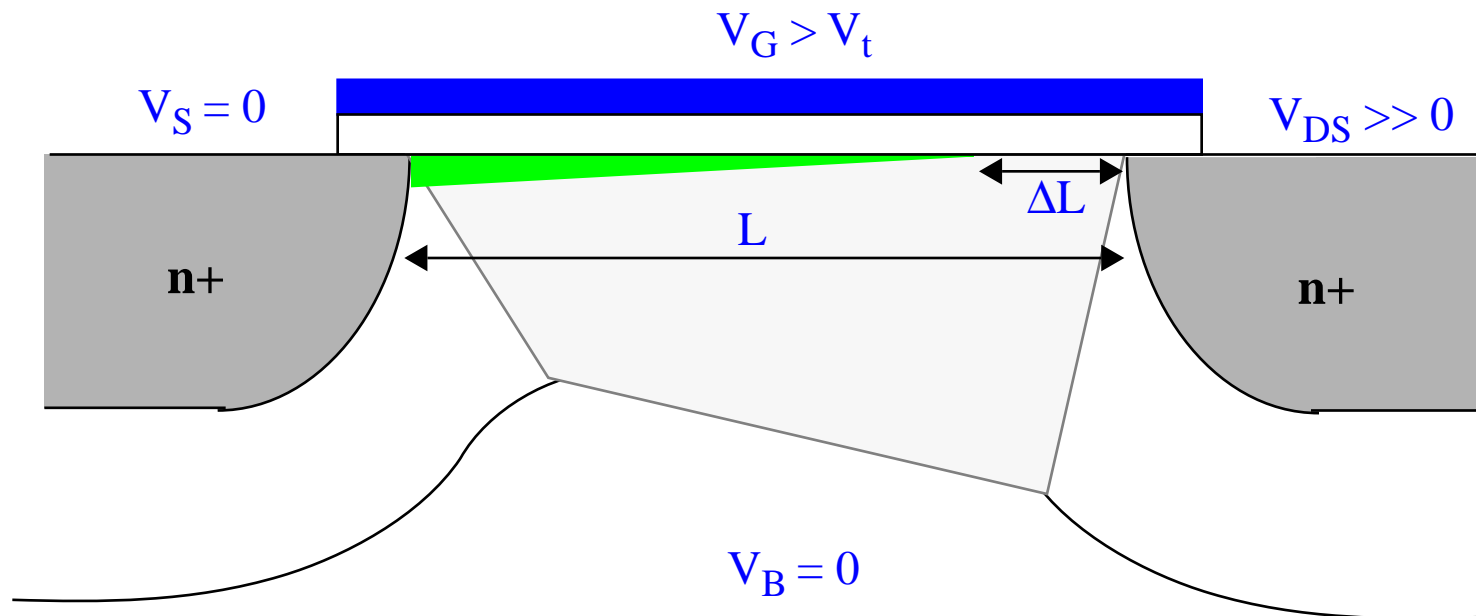
**W=1 micron**  
**L=10 microns**  
 **$V_{t0}=1$  volt**  
 **$K_n=2e-5$  ( $\text{A}/\text{v}^2$ )**

- Large signal model in saturation



## Saturation --- Channel Length Modulation

- $V_{DS}$  at the edge of the inversion layer remains fixed at  $V_{GS} - V_t$
- But the **effective length** of the channel decreases with increasing  $V_{DS}$
- Especially a factor when channel length is short



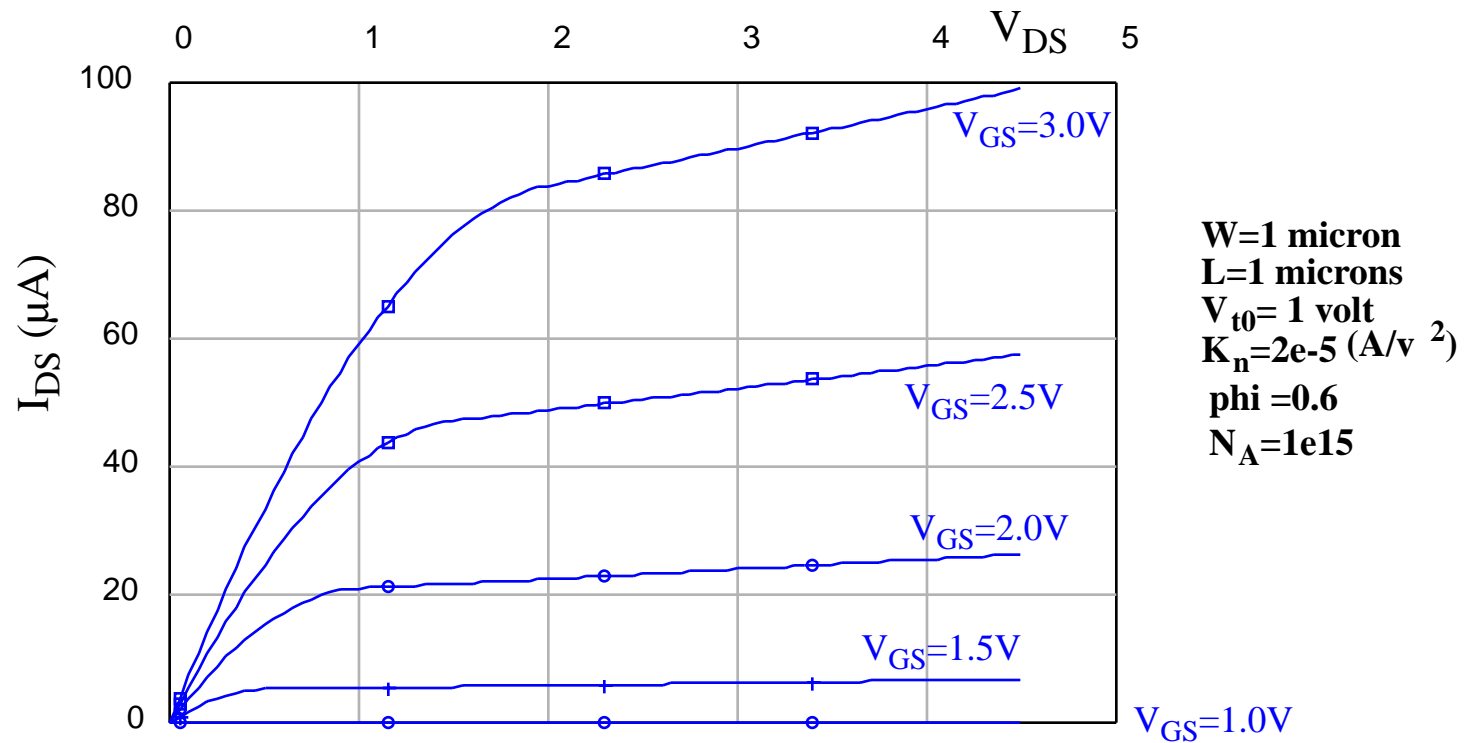
$$i_D|_{sat} = \frac{K_n W}{2(L - \Delta L)} [(v_{GS} - V_t)^2]$$

## Saturation --- Channel Length Modulation

- Sometimes expressed in terms of **channel length modulation** parameter

$$i_D|_{sat} = \frac{K_n W}{2L} [(v_{GS} - V_t)^2] (1 + \lambda v_{DS})$$

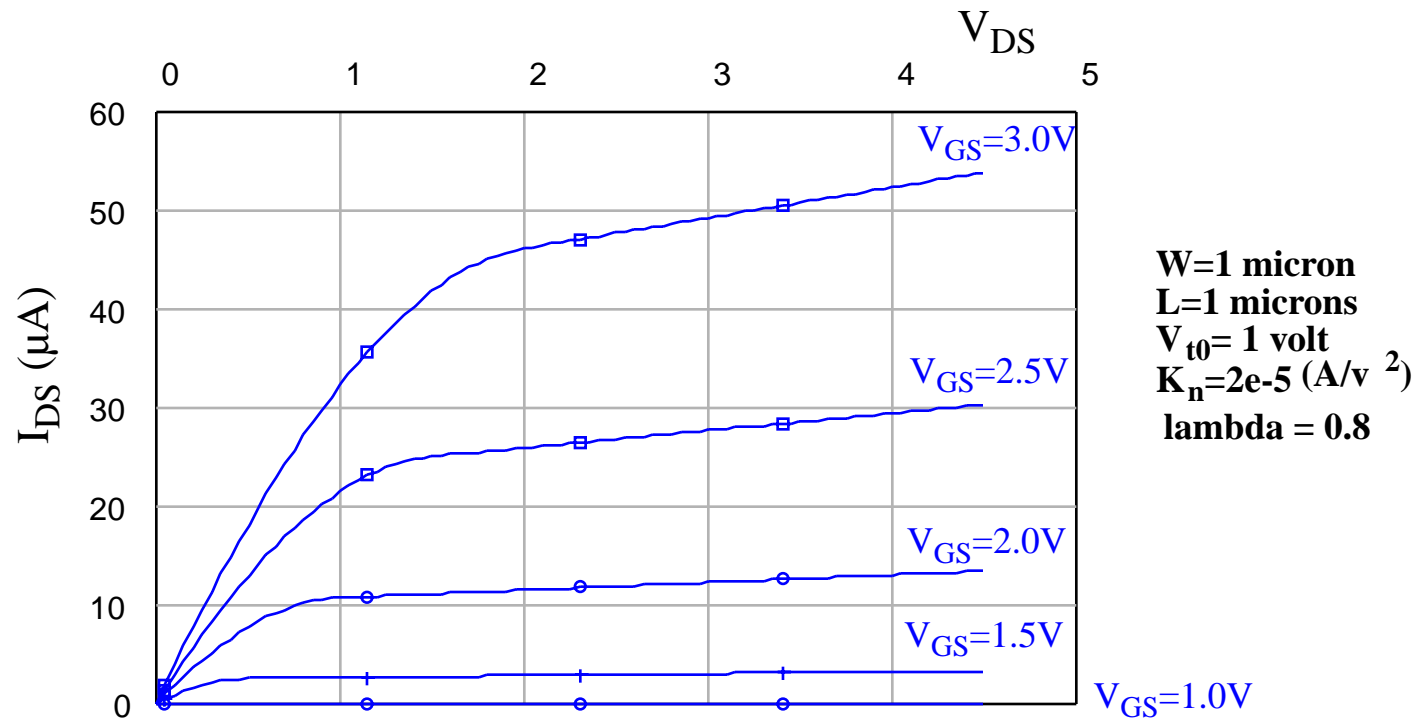
- SPICE can calculate the modulation for you...



# Saturation --- Channel Length Modulation

- Or we can specify lambda explicitly in the model

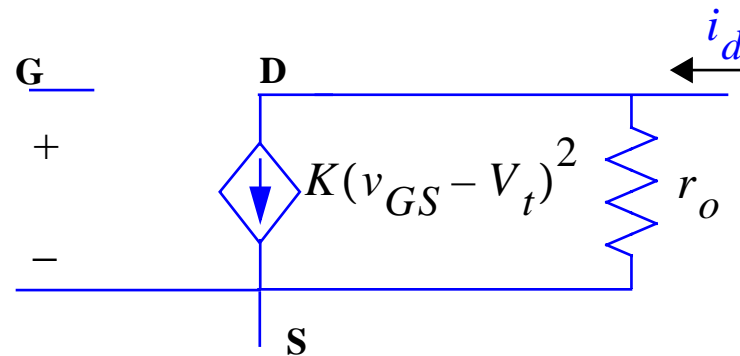
$$i_D|_{sat} = \frac{K_n W}{2L} [(v_{GS} - V_t)^2] (1 + \lambda v_{DS})$$





# Output Resistance

- We can add a resistor to model the channel length modulation effect for the large-signal model in saturation



- What is the value of  $r_o$ ?

$$r_o = \left( \frac{\partial i_{DS}}{\partial v_{DS}} \right)^{-1} = \left[ \lambda K_n \frac{W}{2L} (V_{GS} - V_t)^2 \right]^{-1} \approx \frac{1}{\lambda I_{Dsat}}$$