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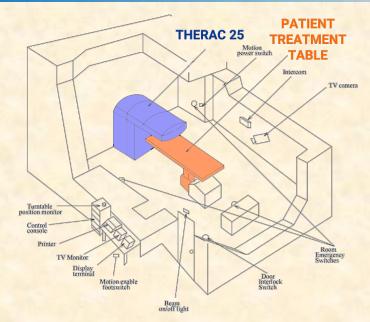
Race Conditions

"The race is not always to the swift, nor the battle to the strong, but that's the way to bet." - Hugh E. Keough

Race Conditions



- Anti-Patterns for Race Conditions:
 - Unprotected access to shared variables
 - Shared variables not declared volatile
 - Not accounting for interrupts and task switching in timing analysis
 - Ignoring non-reproducible faults
- Race condition: multiple threads compete
 - Computation outcome depends upon timing
 - Usually it is infrequent and hard to debug
 - Concurrent access to shared variable
 - Need to lock shared resources
 - Not accounting for multi-tasking
 - Task switch or interrupt causes delays
 - "Starvation" and priority inversion



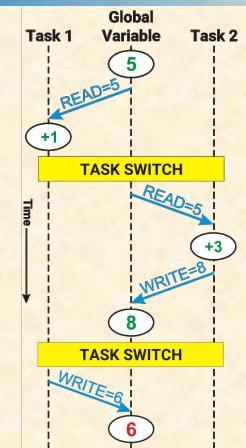
(1985 – 1987) THERAC 25 Software-Controlled Radiation Therapy Mishaps

Problems included:

- Operators "too fast" on keyboard (8 second window)
- Bypassed safety checks when counter rolled over to 0

Concurrency Management Bugs

- CPU switches among its tasks (multi-tasking)
 - What if switching happens at the wrong time?
- Concurrency bugs due to shared resources
 - Example: shared global variable, two tasks
 - Task 1 reads shared variable and computes new value
 - Task 2 preempts task 1, updates shared variable
 - Task 1 resumes, over-writing task 2's update
 - Results of concurrency bug depend upon ordering
 - Usually bug won't manifest (example: 9)
 - Sometimes bug will result in wrong value (example: 6, 8)



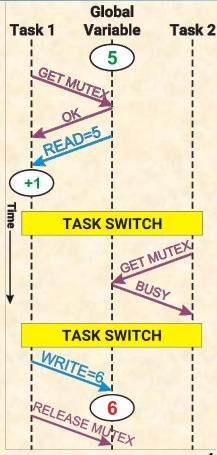
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Mutex For Concurrency Management

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- Easy solution for concurrency bug:
 - Disable interrupts when touching shared variable
 - Inhibits task switches
 - But, need to keep it very brief to avoid timing problems
- To hold resources longer, use a mutex
 - "Mutual Exclusion" flag; True=busy / False=available
 - To access shared resource:
 - Get the mutex (wait for it to be false, then set to true)
 - Access shared resource
 - Other tasks will wait while mutex is locked (resource busy)
 - When done, set mutex to false to release resource
 - Mutexes are themselves a special type of shared variable
 - And therefore subject to race conditions!
 - Getting them right is tricky; let the RTOS do this for you



Bounded Priority Inversion

TASK

PRIORITY:

High

Low

- Minimize time interrupts are disabled
 - Disabled task switching delays task switching
 - Blocking Time: high priority tasks can miss deadlines
- Mutexes indirectly cause blocking time
 - Priority Inversion:

low priority task blocks high priority task

- Locked mutex prevents high priority task from making progress
- Only affects tasks that actually use mutex, not all tasks
- BUT... there is a critical problem (next slide)

TIME

Get Mutex

Fails To

F



Bounded Priority Inversion

Μ

F

Μ

M

Normal

Execution

M

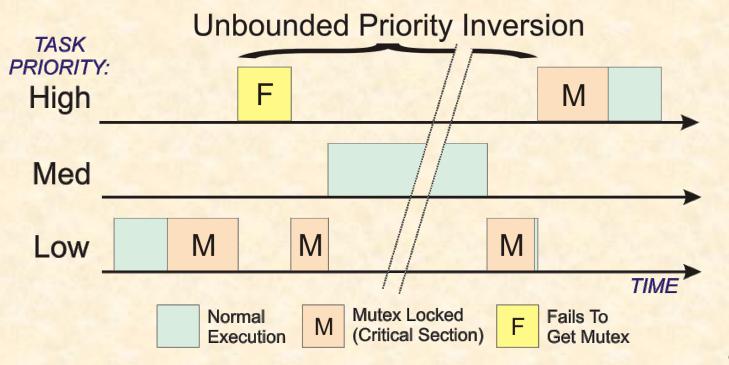
Mutex Locked

(Critical Section)

Unbounded Priority Inversion

Priority inversion can be unbounded for three tasks:

• Medium priority task blocks high task without ever touching mutex:



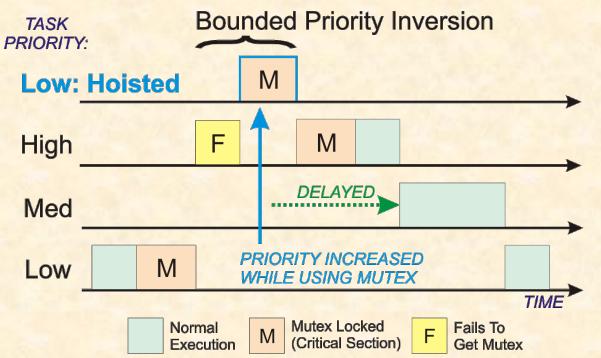
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Priority Inheritance

Solution to unbounded priority inversion: priority inheritance

- Task priority elevated when locking mutex; restored when frees mutex
- This is complicated! Let the RTOS handle it

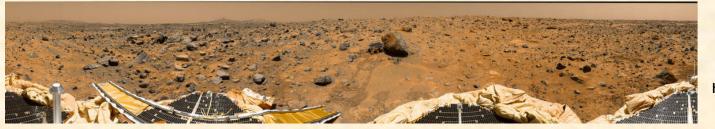


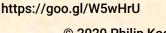
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Mars Pathfinder Incident

- July 4, 1997 Pathfinder lands on Mars
 - First US Mars landing since Vikings in 1976; first rover
- But, a few days later...
 - Multiple system resets occur via VxWorks RTOS
 - Watchdog timer saves the day! Sets system to safe state
 - Reproduced on ground; patch uploaded to fix it
 - Scenario pretty much identical to High/Medium/Low priority picture
 - Developers didn't have Priority Inheritance turned on!
 - Why? "The data bus task executes very frequently and is time-critical -- we shouldn't spend the <u>extra time in it to perform priority inheritance</u>" [Jones07]







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Best Practices Avoiding Race Conditions

- Always consider task interactions
 - What if task switches at a bad time?
 - What if tasks read data at different times?
 - What if half-formed data structure is read?
 - What if multiple writers compete for data?
 - Use RTOS services to help

Pitfalls:

- Failing to use interrupt masking or mutexes
 - Failing to deal with unbounded priority inversion
 - Failing to declared shared variables volatile
- Assuming that non-reproducible problems aren't bugs
- Trying to write your own bullet-proof concurrency services

18-348 Lecture explaining mutex operation at: https://goo.gl/wH9Q44



https://goo.gl/AjS3cX

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