

Flexy Board

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Overview of project

Idea and Drive:

Bring the physical experience of board games online.

What:

A table which can move pieces magnetically so a single player can play with a physical board against an online player.

How:

- A magnet mechanically moved underneath the table moves pieces.
- CV with camera above to match game state with opponent.



Full Idea:

2 boards able to be played wirelessly with each other.

MVP:

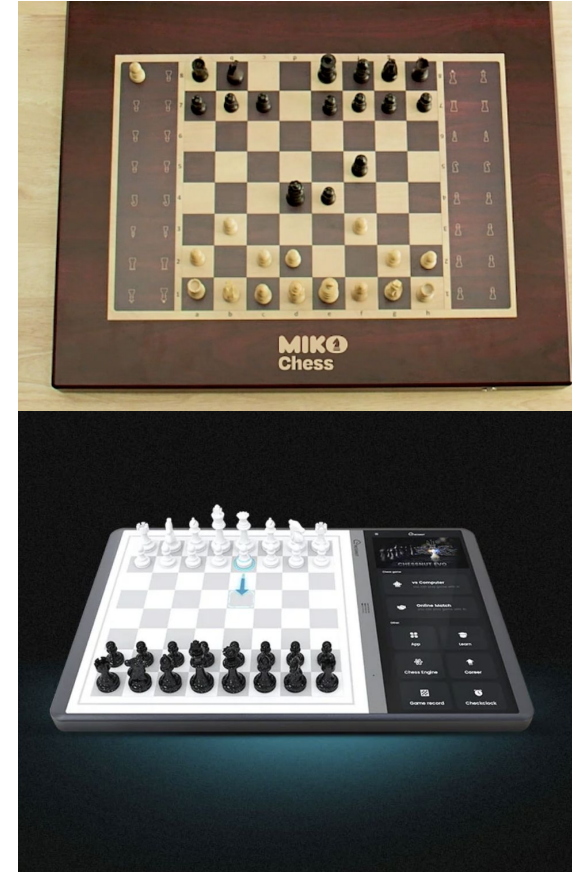
1 board with opponent on software.

Use-Case Requirements

- User is someone who wants physical play with a long-distance friend:
 - Enjoys the action of playing with physical pieces versus playing on a screen
 - Wireless/online with minimal lag so games can be played as if in-person
 - Easy and intuitive function: Not worth it if the experience is difficult
- User is aware of alternatives:
 - Must have a tangible benefit over current competition.

Similar Products

- Square-Off Robotic Chessboard - \$599.95
- Chessnut EVO AI Chessboard - \$899.99
- Competitor projects only support one game
- Flexy Board is compatible with more games at a lower price point



Components and Cost

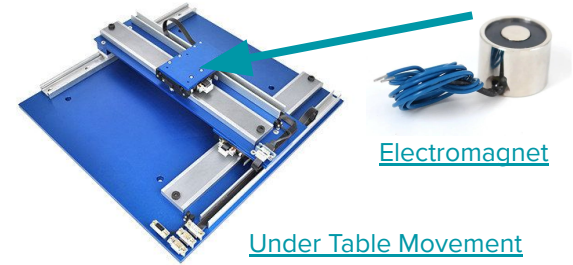
1. **Table:** Modify or/and laser cut
2. **Camera**
3. **Motors/servo under-table movement:** x, y translation
4. **Magnet and solenoid or electromagnet:** To move pieces from under the table
5. **Microcontrollers:** Raspberry Pi (CV, camera, wireless) and Arduino (motors)
6. **Miscellaneous:** Magnets under pieces, installation components, camera arm



[Camera](#)

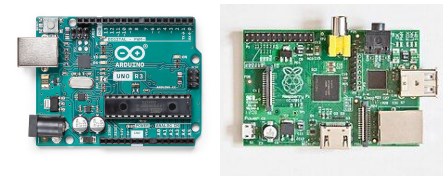


[Chess](#)

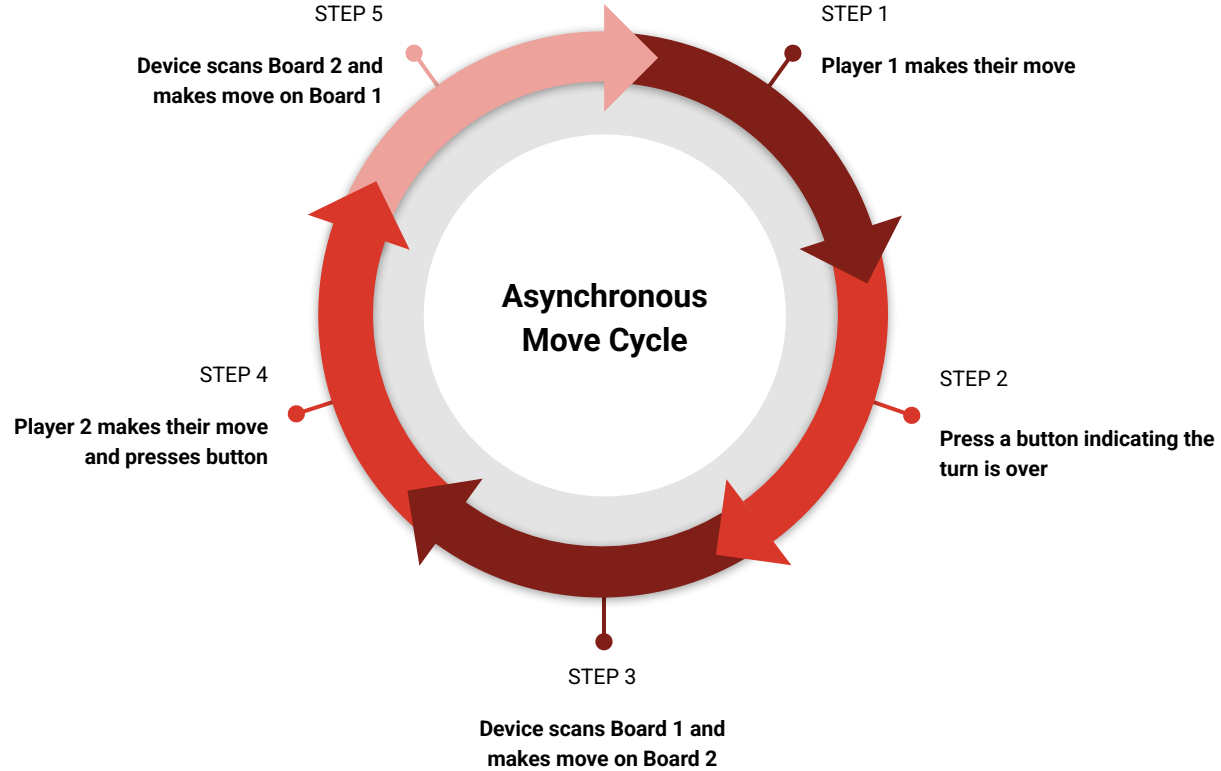


[Electromagnet](#)

[Under Table Movement](#)



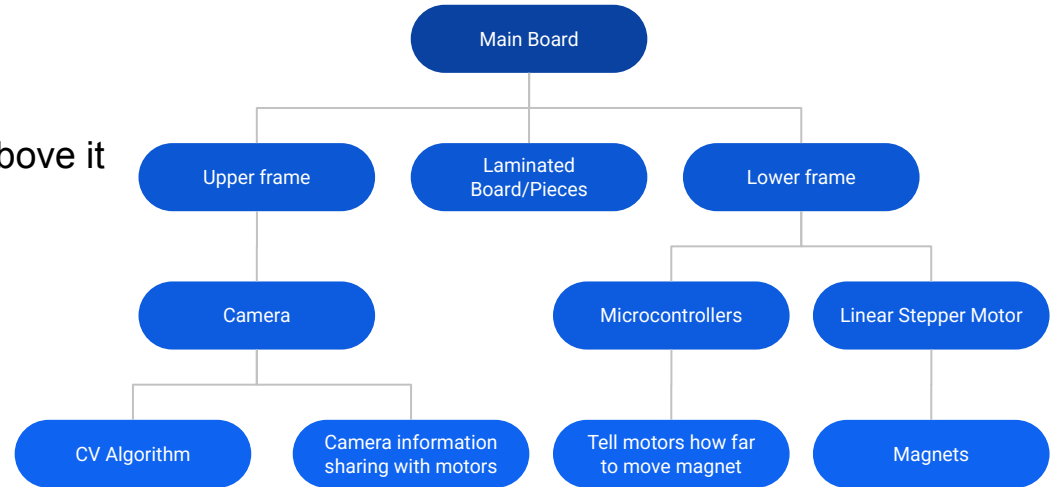
[Arduino](#) + [Raspberry Pi](#)



Approach to Solution

- **Physical design:**

- Square Board
- Frame for stability for Camera above it
- Under board:
 - Magnet, controller, motors
- Laminated board (any game)



- **Software approach:**

- CV Camera that detects changes in positions when end-turn button is pressed
- Sends position differences to a microcontroller
- Controls motors to move magnet from underneath pieces relocating them

Technical Challenges

Computer Vision:

Converting change in image to movement sent to stepper motors.

- Color tops of pieces
- CV tracking differences between start-of-turn and end-of-turn photos
- Algorithms to indicate taking a piece and “jumping” over pieces

Hardware Challenges:

- Calibrating gantry/magnet to correct x/y position
- Ensuring magnet engages/disengages appropriately
- Moving pieces over/across other pieces
 - e.g knight in chess

Our Testing Plan

- **Measure latency**

- Between player having made the digital move on the app (or other physical board) to how long until it is completed on the board (less than a human seeing the move)
- Aim for <5 Seconds for one move (based on chess study of estimated human time to translate: ~2s)

- **Test against multiple games (Chess, Checkers, Monopoly)**

- Record Accuracy across all games should be >95%
- Magnet doesn't move other pieces
- Corrections can be made by the physical user if move is obviously wrong

Testing Verification Metrics

- User study on enjoyability and function compared with fully physical and fully online board game experiences (is the flow nice or buggy?).
- Accuracy of movement (where it should be - where it is)
- Chance of error / malfunction
- Time for each move from initial move to fully being on the board

Division of Labor

Chris: Software integration, software algorithms

Iniyaa: Hardware integration, physical design

Harrison: Hardware integration, software integration

We will all be helping each other with everything at the end of the day.

Timeline of Project

