MaGomoku

Team C4: Shuailin Pan, Sizhe Chen, Zipiao Wan 18-500 Capstone Design, Spring 2024 Electrical and Computer Engineering Department Carnegie Mellon University



Product Pitch

In an era where connectivity defines our interactions, <u>MaGomoku</u> revolutionizes the way we play <u>Gomoku</u>, a strategy board game cherished worldwide. Addressing the need for a more connected and interactive gameplay, our product delivers a seamless, <u>automated networked</u> experience that bridges distances by enabling enthusiasts and casual players alike to compete on a physical board, regardless of their location.

By integrating an x-y **<u>stepper motor</u>** movement **<u>gantry</u>** with magnets, MaGomoku picks up and places game pieces, mirroring an opponent's moves as if they were right across the table. This real-time simulation of moves, combined with <u>hall</u> **<u>effect sensors</u>** that discern between different game pieces, elevates the traditional game into an intuitive, engaging, and dynamic platform.

System Architecture



System Description

Our system consists of the following subsystems:

- <u>Movement</u>

The movement system utilizes an electromagnet to attract magnets embedded in go pieces. The electromagnet is then mounted on an x-y gantry to allow for precise maneuvers guiding pieces along specific paths to their destinations.



Movement

Detection

The detection system employs 3 custom PCBs, each consists of a 3x9 hall effect sensor matrix connecting to two 16-channel analog multiplexer.

Together, the 3 PCBs construct a 9x9 hall effect sensor matrix that scans the entire board to read the strength of the different magnets within black and white go pieces, thus achieving piece detection.

<u>Locking</u>

To achieve more accurate detections and a smoother gameplay, we put one permanent magnet below each hall effect sensor to attract and lock the go pieces to a consistent location on the Gomoku board.



Detection & Locking





System Evaluation



Accuracy / Success Rate

Goal Actual



Timing

- Feeding

The feeding system comprises a vertical magazine for holding go pieces and a stepper motor responsible for pushing out the pieces to be retrieved by the electromagnet in the movement system.

- <u>Software</u>

Our software uses Django and HTML/CSS for the webapp and Telemetrix to parse the hardware data from Arduino. Additionally, Flask is employed to establish local communication and exchange data between the hardware program and webapp.



Feeding



Software



Goal Actual