Use-Case

The goal of our project is to create a device that will <u>assist our users in picking</u> <u>an outfit</u> for their busy day.

By implementing <u>AI Vision technology</u> and a <u>user-driven database</u> consisting of their wardrobe, we can create a smart mirror that is able to <u>analyze your top and</u> <u>give you suggestions</u> on how to complete your outfit.





Use-Case Requirements

- Prioritize smooth and enjoyable experience
 - Convenience
 - Time efficiency
 - Accuracy
- Identify the necessary metrics
 - App Response Times
 - Recommendation Times
 - Detection Accuracies
 - Storage Capacity



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Use-Case Requirements Explanation



Quantitative Use-Case Requirements

<u>APP</u>

Database Latency < 200 ms

ON/OFF Response Time < 1 s

LED Lighting Control < 1 s

Database Storage Capacity > 2GB

Database input time < 1 s

ANALYSIS

Outfit Recommendation < 5s

Torso Detection Accuracy > 99%

Color Detection Accuracy > 95%

Solution Approach







System Specification

Outfit recommendation

- 1. User) Stands up in front of the mirror
- 2. App) Adjusts lightings
- 3. Camera) Takes an image input
- 4. Jetson) Send the img file to software
- 5. Software) Detects torso & color
 - Recommends outfit
- 6. Mirror) Outputs results



Outfit storage

- App) take a pic of 1 outfit(t-shirt, pants, etc) load & analyze the pic(color, type) store @ DB Weight clothes by preference, when they were last worn, etc
- 2. User) remove from DB if clothes are not available





7

Hardware Components



Item Nvidia Jetson Xavier nx Arducam B0250 36x24 Two-Way Mirror 27-inch HP Monitor 16 GB micro-SD card

- Items purchased so far

Implementation Plan

• Hardware Components

- Jetson Xavier NX
- Arducam 12MP IMX477
- 32 inch Monitor
- 42 inch two-way mirror



• Software Components

- App Development: Swift or React Native
- Color Detection API: ColorThief
- Torso Detection: Openpose
- Real-Time Weather API: National Weather Service API
- Data Analysis: OpenCV in C++
- Database: CSV file



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Testing

Requirement	Test	Metrics	
Torso Detection	Analyze fixed points	99% accuracy	
Color Detection	Within range	100% within	
Outfit recommendation time	Average over 10 trials	0.5s margin of error	
Mirror On/Off response time	Average over 10 trials	0.1s margin of error	
LED lighting On/Off time	Average over 10 trials	0.1s margin of error	
Database input time	Average of 10 trials	0.1s margin of error	

Risk Mitigation

- Risks of torso detection
 - Set an outline or specific distance/angle of the camera that will increase accuracy of torso detection
- Risks of inconsistent lighting
 - LED Lighting
 - Recommend user to stand in well-lit environment





D4

12

Project Management

- User Interfaces
 - Wonho
 - Ramzi
- Hardware Implementation
 - Wonho
 - Ramzi
- Torso Analysis
 - Jeremy
 - Yun
- Color Analysis

 Jeremy
 - JeremyYun
 - ⊖ iuii Outfit Apolyo
 - - Jeremy
 - Yun
- Wonho

Item	Manufacturer	Model Number	Source	Cost
Nvidia Jetson Xavier nx			ECE Inventory	\$0
Arducam B0250			ECE Inventory	\$0
36x24 Two-Way Mirror	SPEEDYORDERS		Amazon	\$192
27-inch HP Monitor	Hewlett Packard	M27ha	Amazon	\$174.08
16 GB micro-SD card	Sandisk	SDSQUAR-016G-GN6MA	Amazon	\$8.83

