
The Design Behind Kerby

Team C1

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Recap: Kerby's Use Case



- Current parking apps only work in garages or enclosed parking lots.
- What about street parking?

Recap: Kerby's Requirements

Description	Motivation
Car length < 16 ft	Avg. car length = ~14.5ft
Location accuracy within 30ft	30 ft = ~2 cars
Sensors wake up every 5 min	Takes people at least ~3 min to park and leave
Find street parking within <0.5mi to destination	To keep benefit of street parking over garage parking
Cheap spot modules < \$50	To enable future scalability

Solution Approach



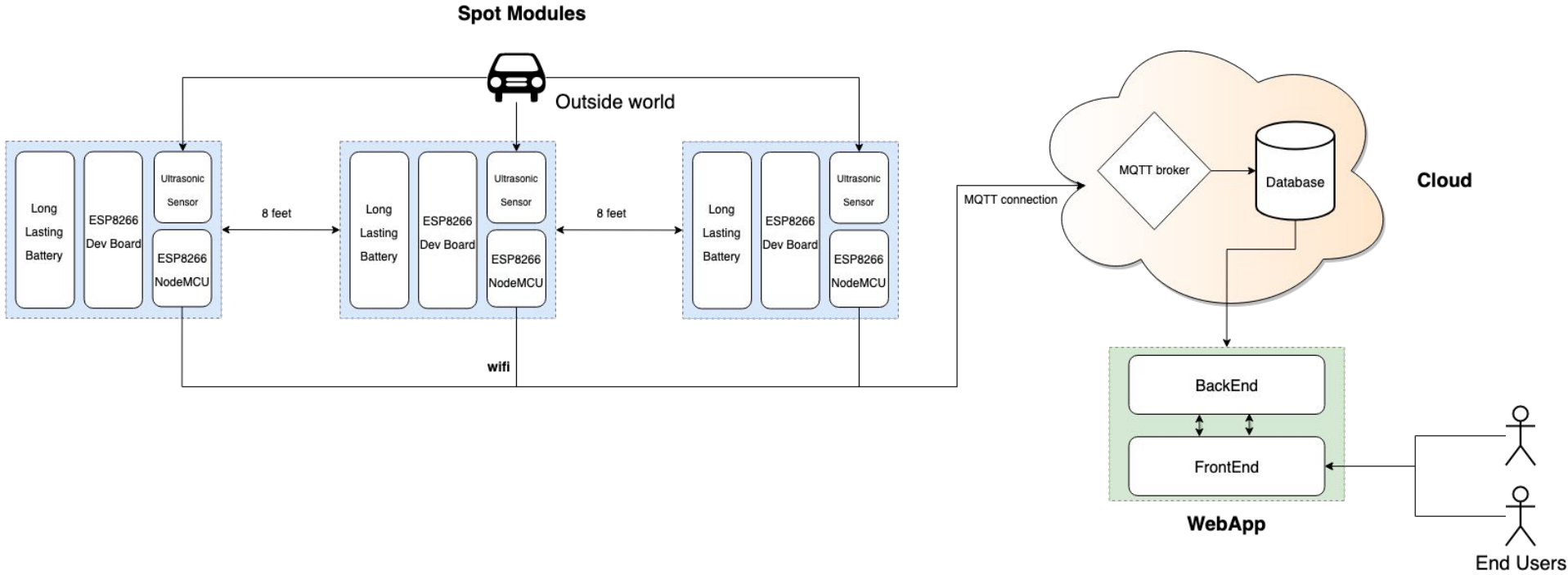
The Main Problem:
wasting time



The Solution:
Easy installation, modular design, control in the hands of the drivers

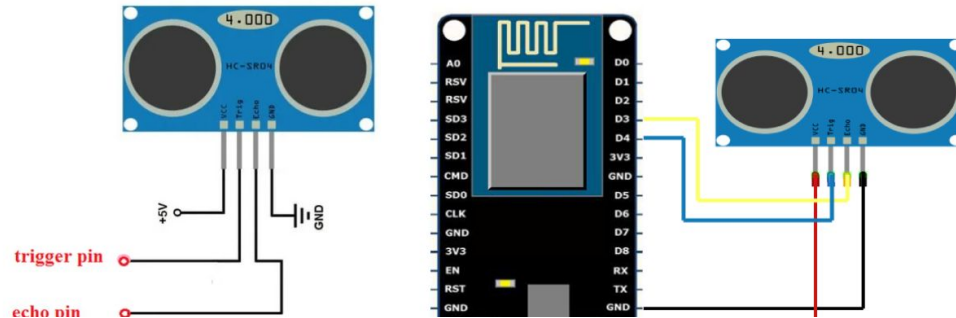


Kerby's System Specifications



Implementation Plan: Hardware

Step 4: Interface HC-SR04



Spot components: HC-SRO4 sensor + ESP8266 Wi-fi module

Programmability:

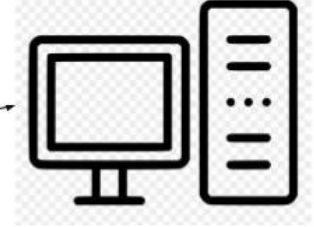
- [MicroPython](#) firmware
- Micro-USB cable
- [Ampy](#) to load lightweight programs from PC to 2MB flash memory
- [Machine Pin](#) library to take sensor readings

Implementation Plan: Software

a) Deploy Atlas cluster
b) Provision CloudMQTT configurations - topic, ports, clients etc
c) Initialize MongoDB collection(s)



SUBSCRIBE
over Wi-Fi



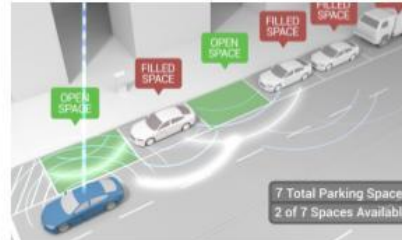
PUBLISH over
Wi-Fi

a) Install paho-mqtt client in MCU programming interface
b) Bind wifi (SS)ID to sensor data
c) Publish sensor data to MQTT broker

a) Install pymongo library
b) Subscribe to MQTT broker
c) Execute callback on message_received

a) Install pymongo library
b) Obtain Atlas credentials
c) Message data for persistence in MongoDB
b) Insert JSON blobs into MongoDB collections

a) Start webapp on host server
b) Execute periodic MongoDB batch queries
c) Run block detection algorithm
d) Provide payload response to client request



Implementation Plan: E2E + Subtleties

- X spots : 1 publisher to subscriber ratio for single topic
- Local publishing, Remote subscription
- MQTT Acknowledgement Semantics (Quality of Service)
- Distinct Backend (Subscribe + DB Insert) + Web (Client request) entrypoint scripts

Testing - Verification & Metrics

Requirement	Measurement	Goal
Find closest street parking to destination	Using google maps api to find distance between given spot and destination	< 0.5 mi
Accurate parking location	Distance between provided location and actual parking spot in real world	< 30ft
Accurate representation of real world	Confusion matrix from testing with large number of users and requests	< 20% False Positive and Negative
Relatively cheap for scalability	Compare to cost of regular parking meters	< \$50 per spot module
Easy-to-use web app	User Testing and recording ratings from 1(bad) to 5(great)	> 3.5/5 stars on average
Easy to install	User Testing and recording time	< 5 min on average

Testing - MVP

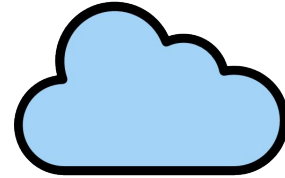
1 User



2 Spot Modules



Web software



- Using 2 ends of Margaret Morrison parallel parking
- Using different requests for different destinations on campus

