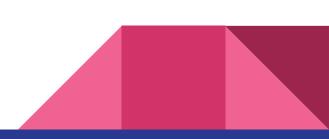
## Team E8: Smart Poker Table Design Review

Zongpeng (Steve) Yu, Brandon Hung, Patrick Kollman

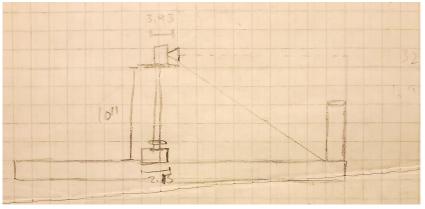
## **Application Area**

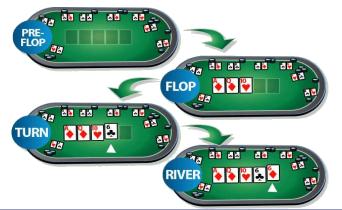
- Display poker statistics (pot size and player stack sizes), that are available in online poker games, to real life poker players in a casino
- CV provides relatively robust and fast stack height/color reading
- Intuitive Software for dealer to keep track of the game state

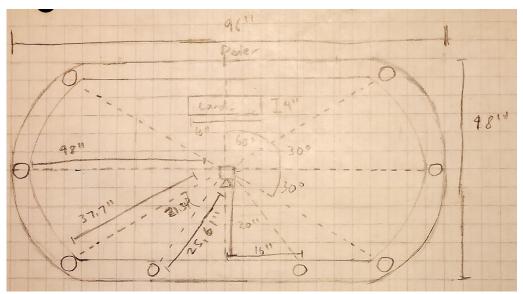


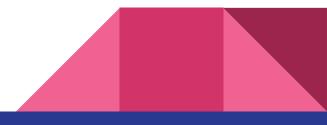


## **Solution Approach**



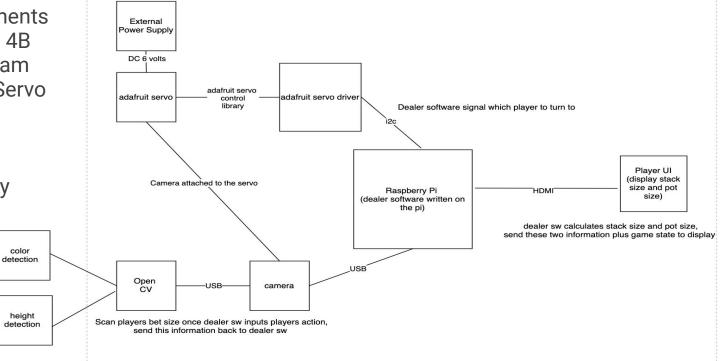






#### Hardware, Systems, and Subsystems

- Hardware components
  - Raspberry Pi 4B
  - IFROO Webcam
  - 16 Channel Servo Driver
  - Servo
  - Power Strip
  - Power Supply Adaptor

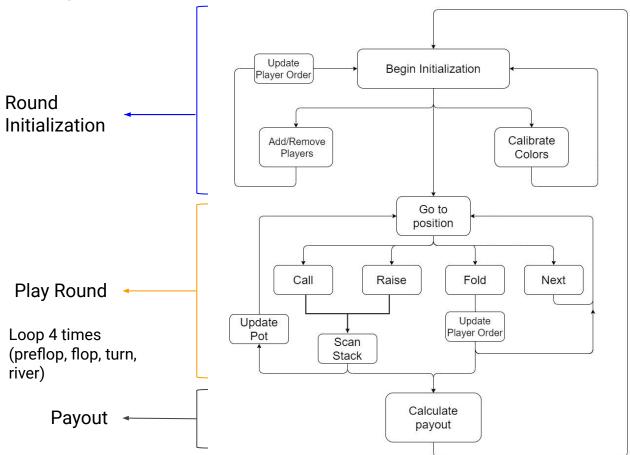


## **Implementation Plan**

- Purchased
  - Hardware
- Designed
  - Servo-driven turntable, dealer/player UI, stack detection algorithm, game state representation algorithm
- Downloaded/Open-Source
  - Servo library, hardware communication protocols, OpenCV

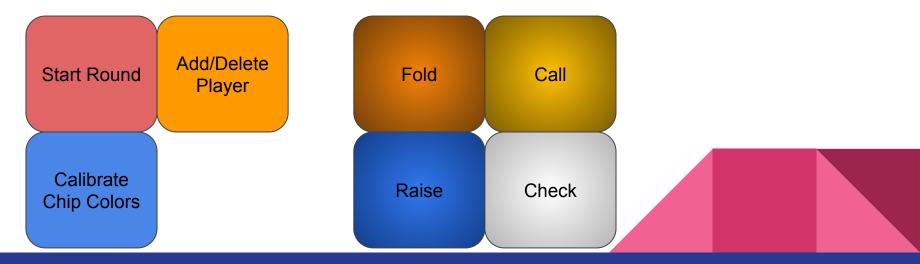


#### **Implementation Plan for SW**



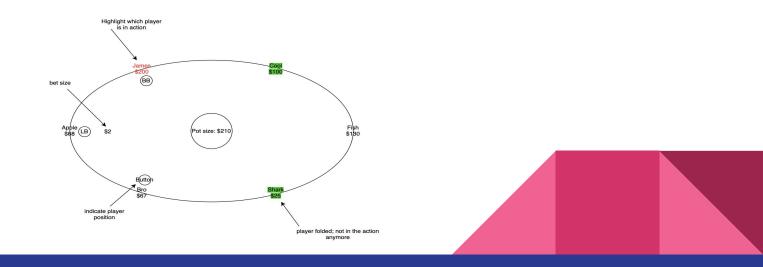
## **Dealer UI**

- Simple button interface
- Round Start: add/remove players, calibrate chip colors, start round
- Play round: fold, call, raise, check
- Payout: N/A



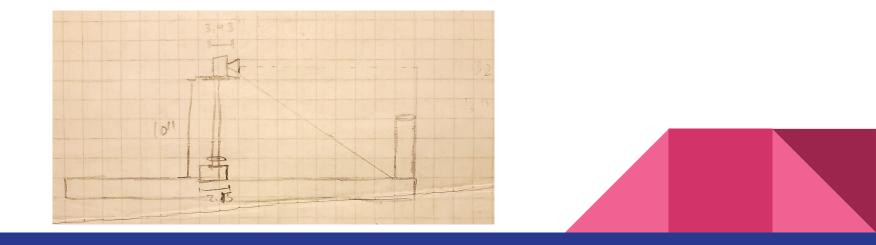
#### **Player UI**

- Monitor displays pot and stack sizes
- Modelled from online poker games
- Updates when players bet or are added/removed



#### State Tracker

- Round start: update player order, calibrate chip color
- Play round: go to position, scan stack/update pot, update player order
- Payout: reward winners with correct amount



#### **Metrics and Validation**

Component	Testing Strategy	Metrics	Challenges				
Servo Motor	Input: unique ID assigned to each player Output: servo rotating to the specified position	Camera rotate within +/- 4.5 inches of target; camera should rotate to the position within 5 seconds	Motor provides enough torque; power supply				
Computer Vision	Input: unoccluded picture of bet Output: total value of bet	Verify +/-10% of total stack value	Different distances/lighting can lead to detection challenges				
Software	Input: Game state inputs entirely simulated in software Output: game state, stack sizes, and pot size update correctly in the simulation						
Overall System	Input: dealer software controls Output: servo position and updated game state, stack, and pot size to monitor display	After integration, the previous subsystem metrics hold and the display is updated within 5 seconds	Successful integration				

# Steve Pat Standon Pat Standon

## **Project Management**

			Brainstorm/ Designing Phase				Development Phase					Finalization					
		Task Owner	Week 1	Week 2	Week 3	Week 4	Week 5	Week 6	Week 7	Week 8	Week 9	Week 10	Week 11	Week 12	Week 13	Week 14	Week 15
Brainstorm/ Designing Phase	Purchase components(camera/ motor/controller/buttons)	All															
	pick approporaite OpenCV library	Brandon															
	Design UI Interface	Pat															
	Design Motor and how it hooks up to the camera	Steve						_									
	Design control for game state	All															
	Design the Physical table	All															
Development Phase	Set up environment for Rasberry Pi	All															
	do research on i2c and libary	Steve															
	Write firmware for the motor	Steve															
	research on open cv library	Brandon															
	Write firmware for the CV	Brandon															
	Write code for UI	Pat															
	Write code for Game State control	All										_					
	Test Motor Control	Steve															
	Test CV component for one player	Brandon															
	UI testing	Pat															
	Game State control Testing	All															
	Slack	Slack															
Finalization	Integrate Servo with Dealer SW	Steve/ Pat															
	Integrate camera with Dealer SW	Brandon/ Pat														-	
	Connect mutiple components together	All															1.16
	Final testing	All															
	Slack	Slack															