

DRIVAID

A smart driving monitor



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Application Area

Why?

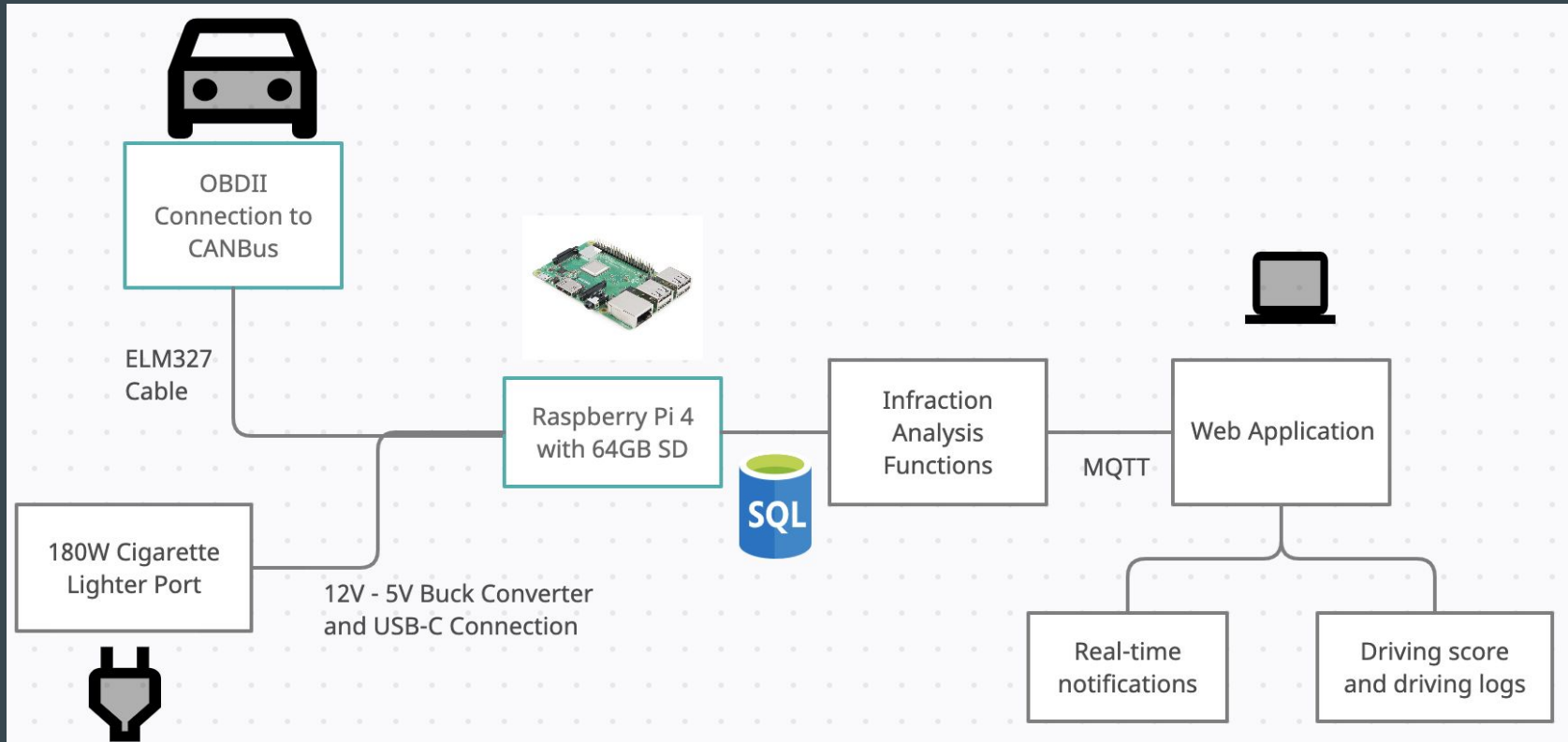
- Drivers need feedback to improve their driving
- Lack of feedback and constructive criticism available

Solution

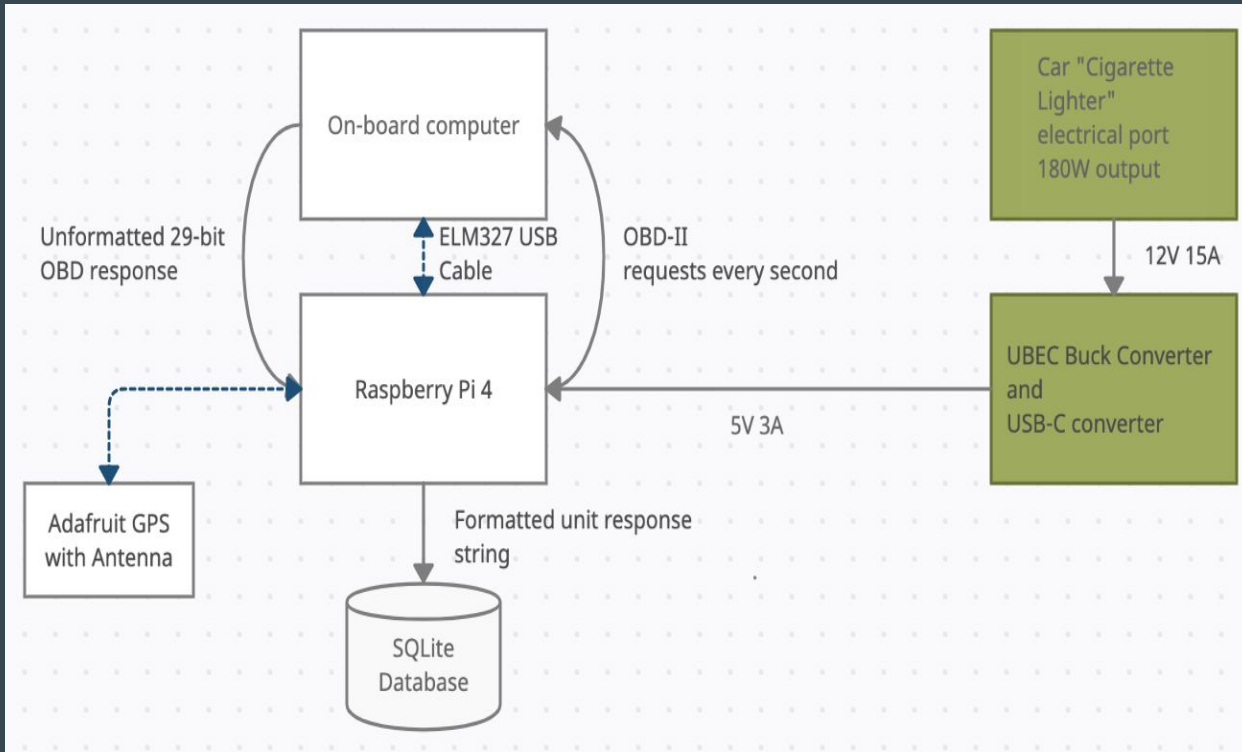
- Detect and identify poor driving habits
- Notify driver in real time of infractions
- Log and share driving records / data



Solution Approach



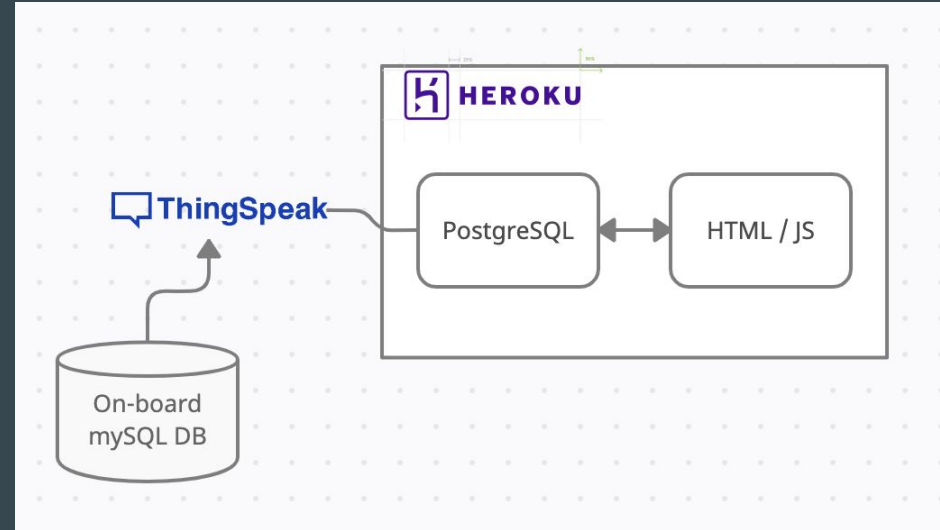
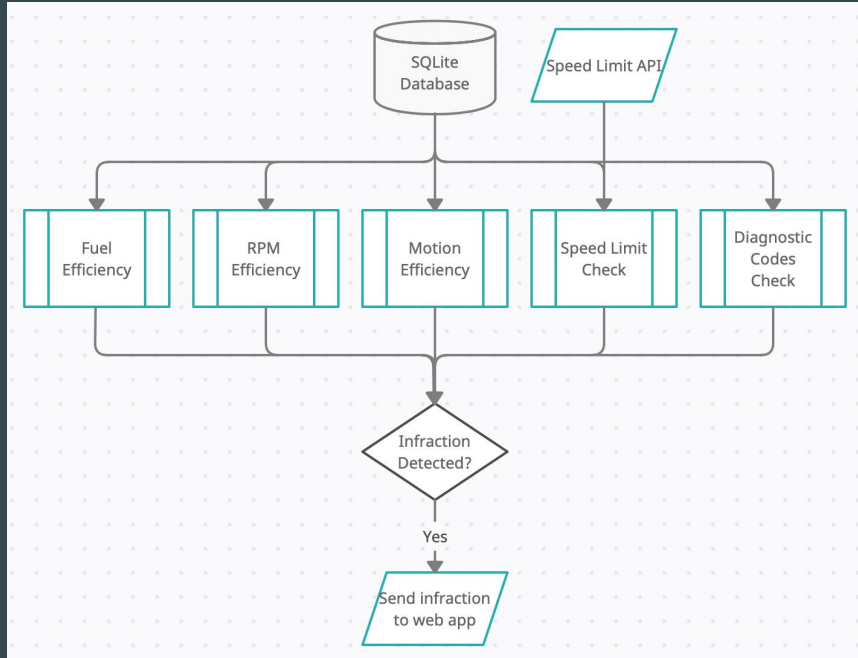
Complete Solution - Signals and OBD-II



CHANGES:

- We swapped the PiCan2 after not receiving data despite communication with the founder and creator among many repeated attempts
- We also added an antenna to our GPS hardware

Complete Solution - Infraction Detection and Website

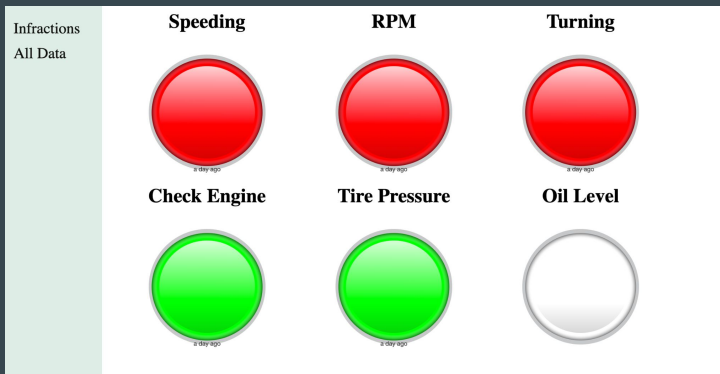
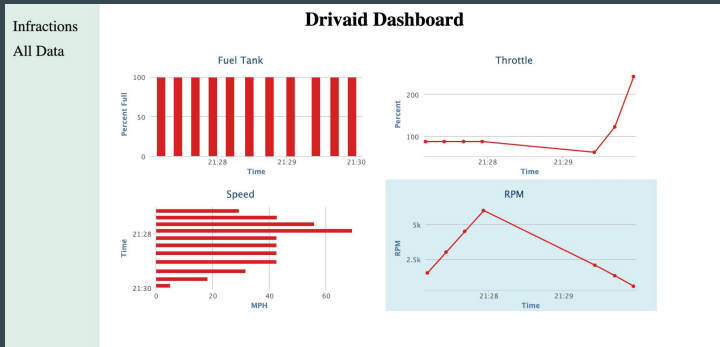


CHANGES:

Different measurements on Infraction detection due to unreadable data.

Different data storage approach for website.

Complete Solution



Testing, Metrics, and Validation (OBD-II Logger)

| Requirement | Testing / Metrics/ Verification | Results |
|---|--|---|
| Request and receive data from OBD-II across timestamps | Comparing vehicle dashboard to database file and web app | ECU returned data in controlled driving test in parking lot, alongside non-driving tests |
| Handling zeroed data returned by the onboard computer/ECU | Viewing database file after zero detection in moving and non-moving positions | No seen spikes in web application after timestamp control during driving test |
| Data formatting correlates with SQLite | Error checking in ELM Logging file and creating dummy improperly formatted data to be checked before sending to DB | Python types match up and improper formatting is caught before DB and replaced with previous timestamp data point |
| Arduino receives 5V 3A from UBEC Converter | Multimeter recording verification | No current recordings above 3A, voltage steady at 5.2V, power steady at 15W regardless |

Testing, Metrics, and Validation (Algorithms and DB)

| Requirement | Testing / Metrics/ Verification | Results |
|----------------------------|--|---|
| Speed Limit Check Accuracy | Find longitude and latitude points with speed limits of 25, 35, and 55 mph and verify they return correct limit | Success, locations on Forbes, Fifth, and highway all returned correct speed limits |
| Fuel Efficiency accuracy | Go for a 10 minute drive and compare fuel efficiency calculated to the car's fuel efficiency | Success, result calculated was within 5 miles of fuel efficiency displayed from the car |
| RPM Efficiency accuracy | Run RPM check on data set with 100 points that bring the RPM above 6500 | Success, check found exactly 100 infractions |
| Motion Efficiency accuracy | Run motion efficiency check on data set with 50 points that bring acceleration above 1.5 m/s^2 and 50 that bring it below -1.5 m/s^2 | Success, check found exactly 100 infractions |

Testing, Metrics, and Validation (MQTT and Website)

| Requirement | Testing / Metrics/ Verification | Results |
|---|--|---|
| Data is sent and updates within 5 seconds on the website | Sending test data and observing the response time | Success, the website updates consistently with an average of ~5 seconds |
| Data is properly stored on the site without data corruption or faults | Data stream test script to the hosting service and observing that data is correctly places | Success. The data sent from the script consistently matches the data being stored |

Testing Results (Integrated System)

- Driving and stationary tests showed correct data transfer from the OBD-II port to the web application
- Ran a driving test in an empty parking lot and recreated inefficient driving events (accelerate then brake constantly over short distance) to see if fuel efficiency light shows up on Web App
- In park, we revved engine to see if RPM light turned red
- Passenger-side database monitoring allowed us to tweak some of the algorithms after we saw that they were too sensitive to small changes in acceleration/throttle



Trade-offs

| Tradeoff | Issue | Solution |
|------------------------------------|--|--|
| PiCAN | Not able to view data using the PiCAN board. Tested the board and contacted support | Switched to ELM327 usb interface |
| Steering wheel angle & turn signal | Could not read the steering wheel angle or turn signals. These values cannot be accessed using standard OBD-II codes | Removed these metrics and replaced with readable data |
| Odometer | Similarly, odometer is restricted due to security and cannot be accessed via OBD-II contrary to original belief | Instead, we calculate accurate mileage by using speed and timestamps to compute a distance |
| Google Places API | Could not get speed limits without special license | Pivoted to OpenStreetMaps API to access speed limits (more limited dataset) |

