



Group E1: Drivaid

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Application Area

Why?

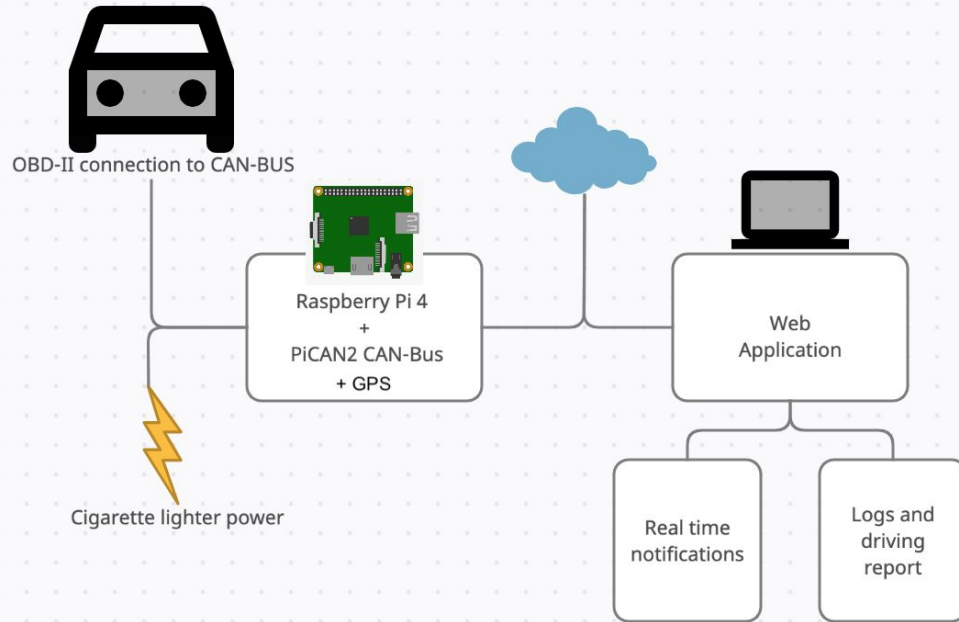
- Drivers need feedback to improve driving
- Lack of feedback or constructive criticism

Solution:

- Detect and identify poor driving habits
- Notify driver in real time of infractions
- Log and share driving records



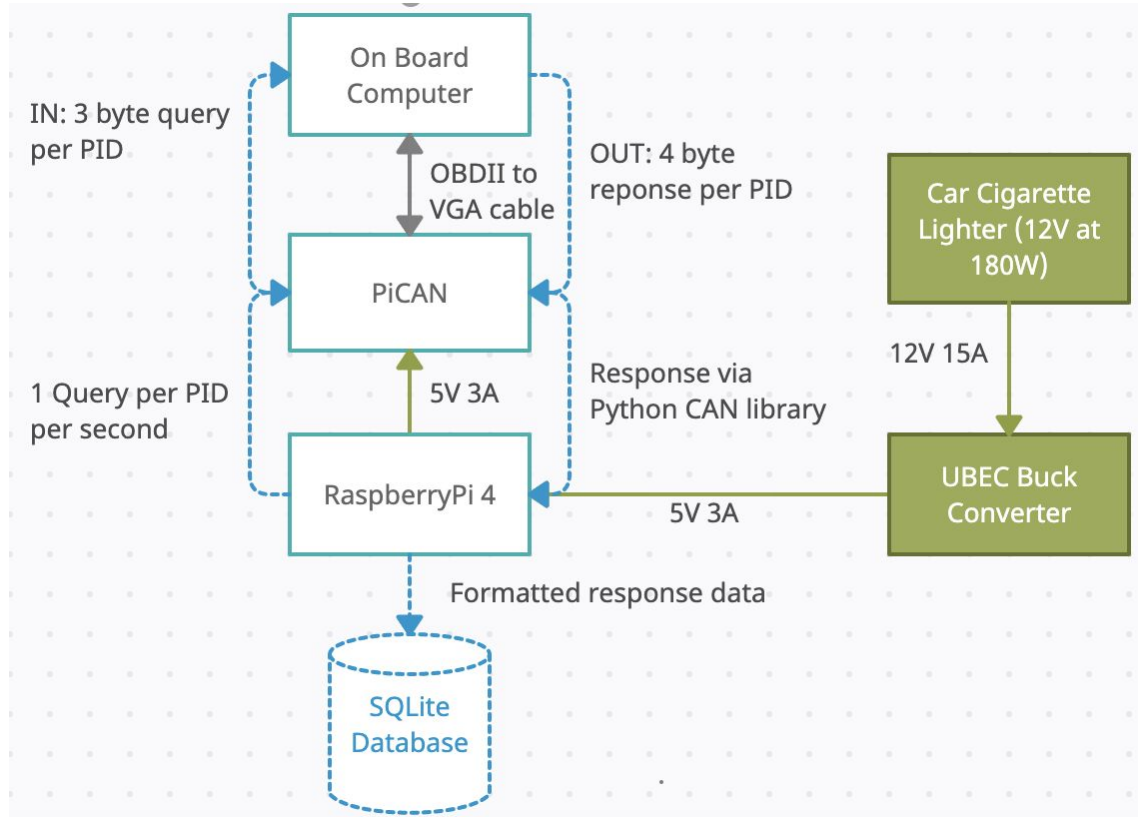
Solution Approach



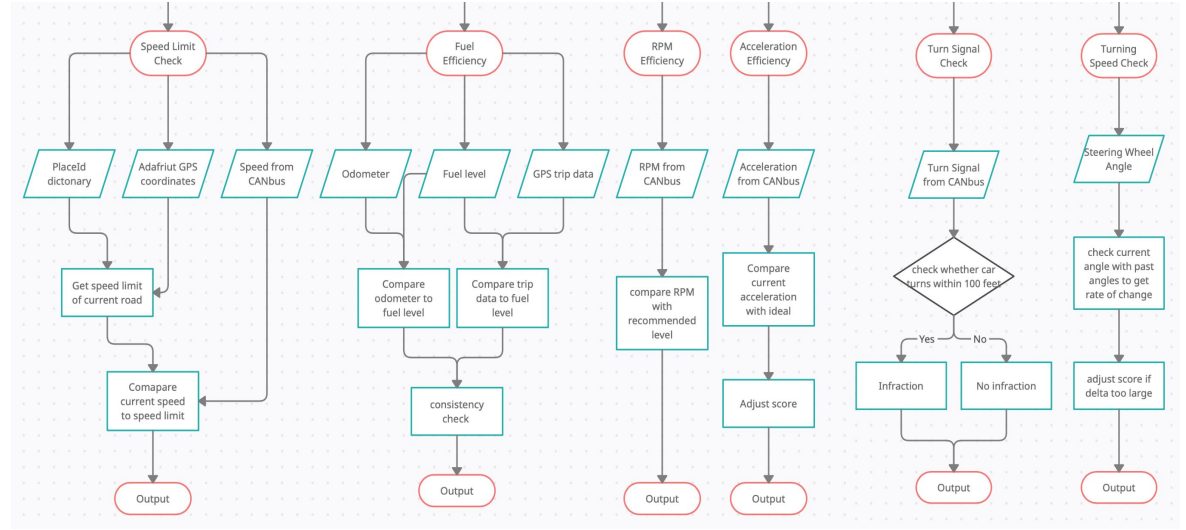
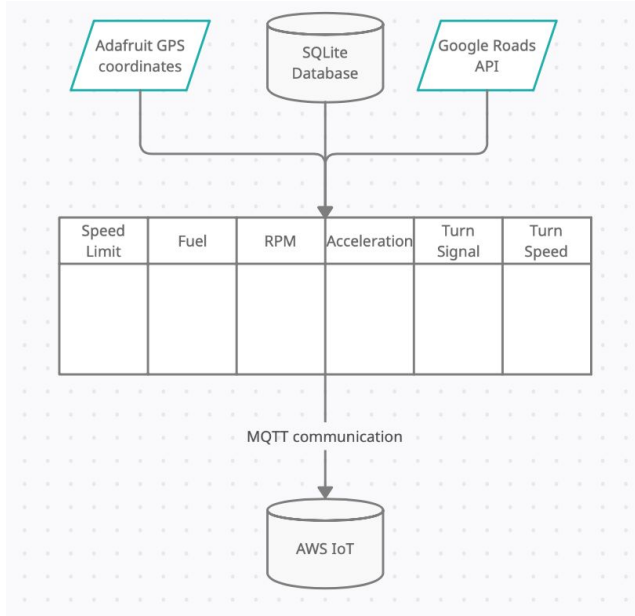
Main Components:

- PICAN2
- GPS
- Raspberry Pi 4
- Web Application
- Driving Report/Logs
- Power from car cigarette lighter outlet

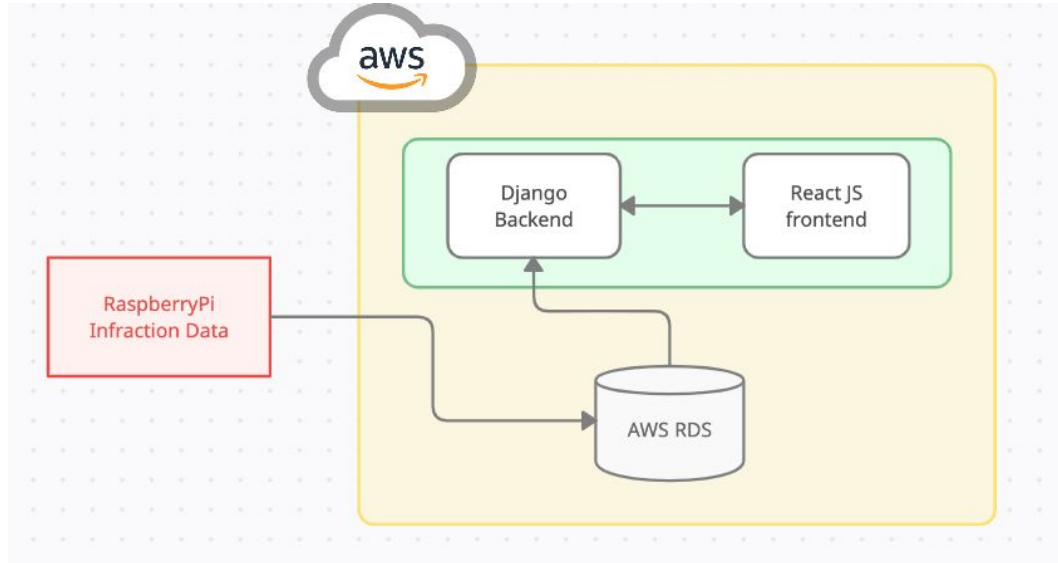
System Specification / Block Diagram (OBD-II Logger)



System Specification / Block Diagram (Infraction Detection)

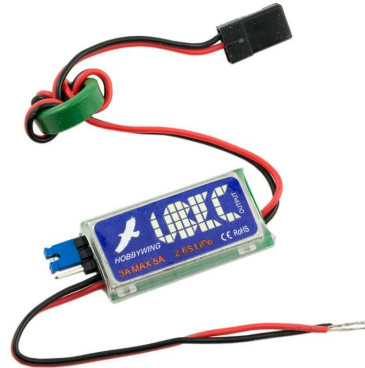
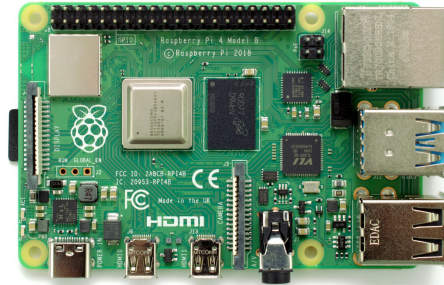
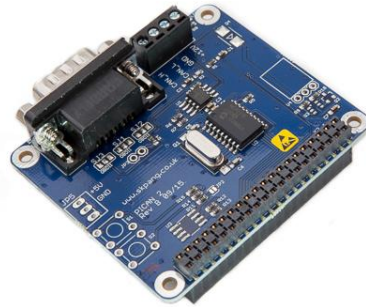


System Specification / Block Diagram (Web Application)



Implementation Plan

Buying



Implementation Plan

Designing

- Program to query the CANbus for specified data once per second
- RaspberryPi SQLite in-memory database to hold messages in specific schema
- Algorithms to detect driving infractions from CANbus data
- Web Application to visualize trip data and notify user of infractions

Metrics and Validation

Requirement	Testing, Verification, and Metrics
Data Logging	<ul style="list-style-type: none">• Verify all data is being sent and processed correctly between OBD-II and RPI in real-time• Monitor data log to ensure connection and compare to commercial system• Complete a driving test to make sure velocity, steering wheel angle, turn signal, RPM data, acceleration, fuel levels, and odometer data is stored on Raspberry Pi
Web Application	<ul style="list-style-type: none">• Unit testing and database testing

Metrics and Validation

Requirement	Testing, Validation, and Metrics
Speed Limit Check	<ul style="list-style-type: none">● Simulate exceeding the speed limit with 5 different speed zones
Fuel Efficiency	<ul style="list-style-type: none">● Simulate a odometer and fuel level data over a 100 mile trip
RPM Efficiency	<ul style="list-style-type: none">● Simulate bringing the RPM above 6500
Acceleration Efficiency	<ul style="list-style-type: none">● Simulate accelerating above 1.5 m/s^2 and breaking faster than -1.5m/s^2
Turn Signal Check	<ul style="list-style-type: none">● Simulate switching lanes 90 ft. and 110 ft. after using turn signal
Turning Speed Check	<ul style="list-style-type: none">● Simulate making a right/left turns from 5 mph to 35 mph

Risk Factors/Unknown

- How to obtain steering wheel and turn signal data?
 - These are not standard PIDs and they vary from car make to car make
- Storing data logs and sending to database
 - Organizing data so that it can be accessed easily
- Testing in a safe controlled environment, especially with speed and hard turning

