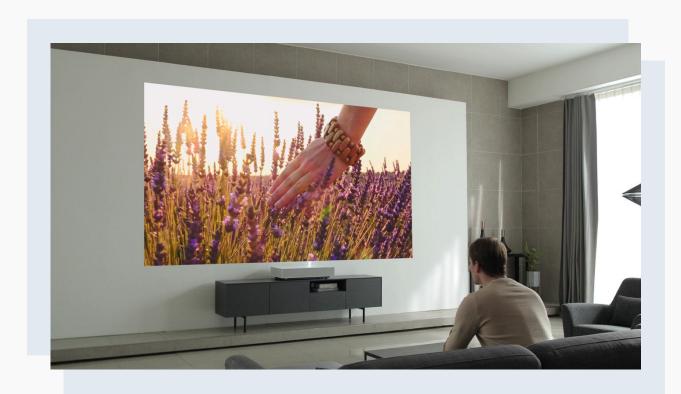


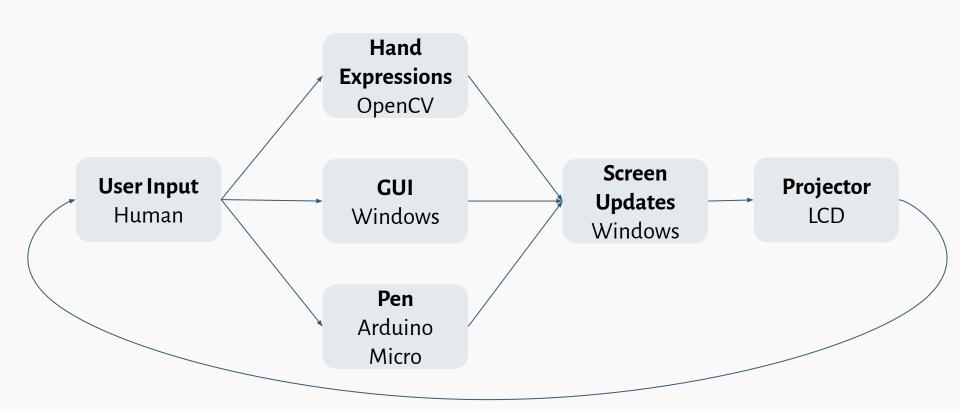
Bradley, Jenny, Jade



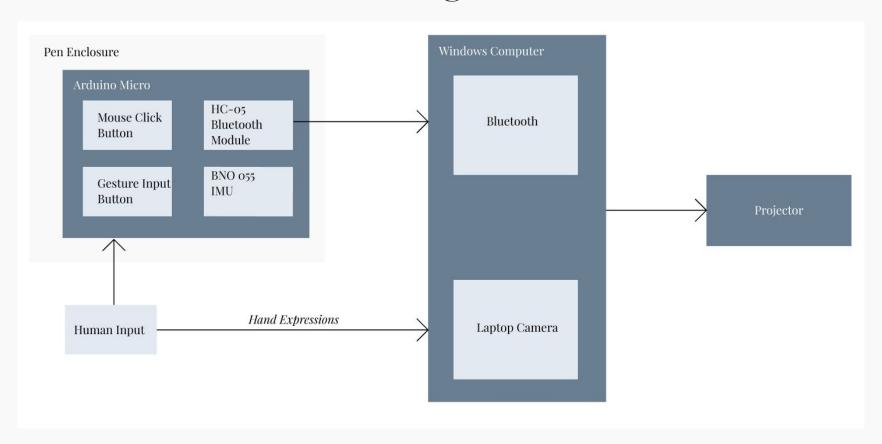
# **Application Area**



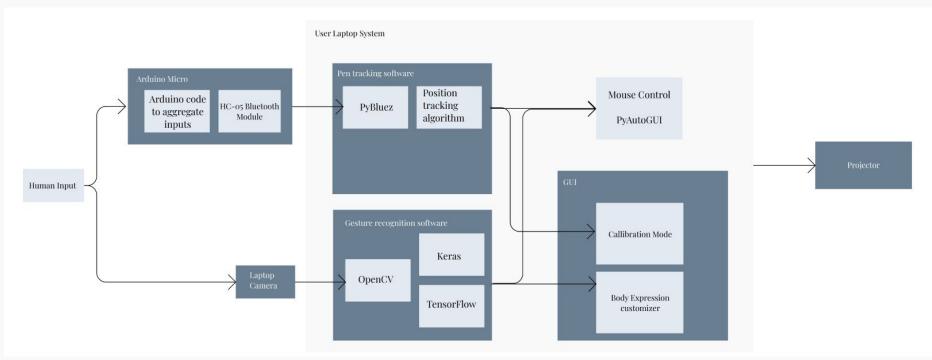
### **Solution Approach**



## **Solution Design Hardware**



### System Design Software



### **Complete Solution**



#### Pen

Mouse tracks pen location on the screen, clicks and hovers



#### **Projector**

Displaying the screen and mouse movements



#### **Hand Expressions**

Saving new gesture Running macro



#### **System**

Distance calibration
Mouse events

### **Metrics and Validation**

Segment	Metric	Performance
Pen	~1 inches when used with a projector ~50 ms button clicks response ~100 Hz polling rate	~2 inches when used with a projector ~20 ms button clicks response ~50 Hz polling rate
Gesture Recognition	~95% accuracy Add/remove new gestures	~85% accuracy Saves up to 10 different gestures
System/Projector	Calibration for distances of 5-15 ft	Calibration for 5-10 ft

### Results

- Pen
  - o 50 Hz polling rate
  - Click and drag/draw functionality
  - o 20 ms input delay for moving/clicking
  - Accurate to ~2 inches when used with a projector
  - Can calibrate orientation of pen in 0.5 seconds
- Gestures
  - o 3 default gestures (fist, open hand, OK sign)
  - User has ability to create their own gestures
  - Can remap gestures to any keyboard shortcuts
- GUI
  - Calibration of camera for pen tracking
  - Management of gestures and macros

### **Tradeoffs**

- OpenCV
  - Added OpenCV as additional input for pen data readings
  - More processing on software side
  - But allowed for more accurate readings
- Accelerometer/Orientation vs Accelerometer/Orientation
  - Accelerometer had quite a bit of drift but allowed the pen to be its own contained unit
  - OpenCV supplemented by orientation data was very accurate/smooth but required more materials
- BNO055 vs. MPU6050
  - O BNO055 had more stable gyroscope/orientation readings
  - MPU 6050 was cheaper and simpler to work with
- Windows
  - Switched to MacOS due to lack of compatibility with several Python modules (especially bluetooth)
  - O Difficult to work efficiently due to only ½ team members having a Windows system

## **Project Management**

TASK NAME	START DATE	END DATE
Pen		
Code for calibration mode	5/2	5/7
Improve accuracy of pen tracking	5/2	5/10
Assemble pen parts (Arduino, Bluetooth, Buttons, Gyroscope, etc.) into good ergonomics	5/7	5/10
Projector/System		
Create callibration mode	5/2	5/7
Body Expressions		
Remove body expression	5/2	5/4



