Smart Mirror: Final PresentationTeam B8

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Application Area







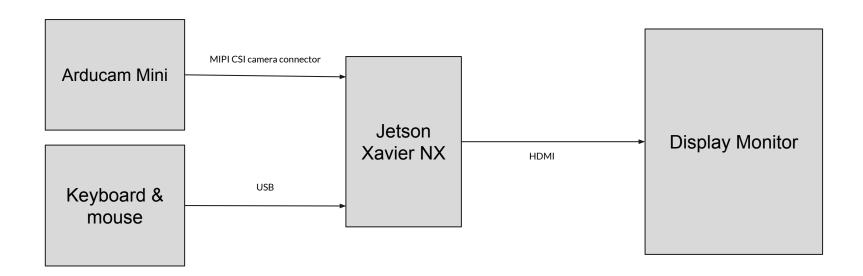
Lulu Lemon's MIRROR HiMirror Vanity DIY Smart Mirror

Solution Approach (overall)

We want to make a simple, inexpensive and accessible smart mirror that utilizes a torso* recognition computer vision algorithm to allow users to select and try on tops.

*Note: to maintain manageable scope, we are limiting our recognition algorithm to tops only.

Complete Solution (hardware)



Complete Solution (Overall) Legend Module (Self-Implemented) Sub-module (Self-Implemented) Off-the-shelf Package/Library Image Processing (Jetson Xavier NX) Mirror System Image Recognition Matching Module UI (Remote) **Clothing Detection** Inputs (Keyboard and Mouse) Clothing Fixed Points **OpenPose** Calibration Fixed Point Landing Page Calibration Pose Detection Selected Image Torso Fixed OpenPose Torso Recognition Points Picture Feed 5 frames/sec (Arducam) Image Modification Outputs (Monitor) Calibrated/ Modified Output Image Imposed Image **Output Processing Position Calibration** Image Warping

The Mirror







The Interface

Hello, Welcome to Smart Mirror!

Choose a top to try on:









Testing, Metrics, Validation

Requirement	Test	Metrics
Clothing, Image Processing Speed	Time Decorator/Stopwatch	~5.5 seconds
OpenPose Torso Detection	Analyze fixed points	100% precision
Clothing/Torso Matching	Ran on 2032 model images, manually pick passable images	68% precision
Camera/Mirror Calibration	Display video feed over mirror	30 fps

Testing Results: Clothes Matching

- Tested 2032 images
- From a sample of 100, 68 are passable, better than the 50% goal we originally had previous set
- Criteria:
 - Center alignment
 - Low percentage of body shown
 - Neck alignment is a good indicator
- Observation:
 - Doesn't work well on models that have angled or unconventional poses
 - We assume similar conditions for our mirror (well lit, minimal background)













Testing: Clothes Warping



Tradeoffs

Hardware Tradeoffs

- Acrylic vs glass mirror
- IR touch frame vs keyboard & mouse
- TV stand vs frame
- Xavier NX vs nano

Software Tradeoffs

- OpenPose processing speed on Jetson is an average of 5.5 seconds vs our goal of 3.5 seconds
 - Optimizing speed from 5.5 to 3.5 seconds was not a priority
- Matching
 - Using OpenPose on clothing as opposed to a designated clothing detection algorithm made matching very intuitive

Project Management



