# KATbot

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### **Application Area**

Storytelling robot that interacts with people to aid in language and reading comprehension

- Merging AI with educational tools
- Target Audience: early elementary school age children
- Child-friendly user experience



### Solution Approach

**Speech Processing & Text to Speech:** Convert speech to ML input and ML output to speech

- 1. Text to speech dialogue prompts user for input
- 2. User speech is processed and sent to the ML model
- 3. ML model returns the rest of dialogue

**Robot:** Custom-made robot inspired by Japanese lucky cats

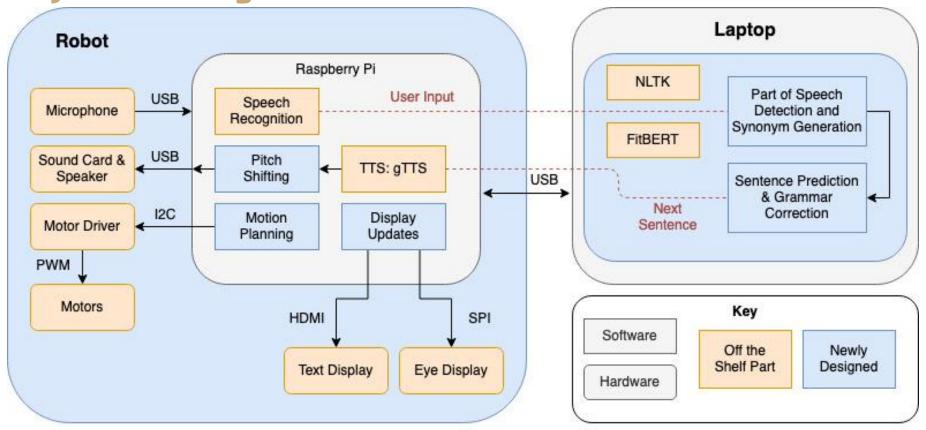
- 1. Robot houses all electronics needed for project
- 2. 2x one degree of freedom robot arms
- 3. Text display to display current sentence
- 4. Eye displays

### Solution Approach

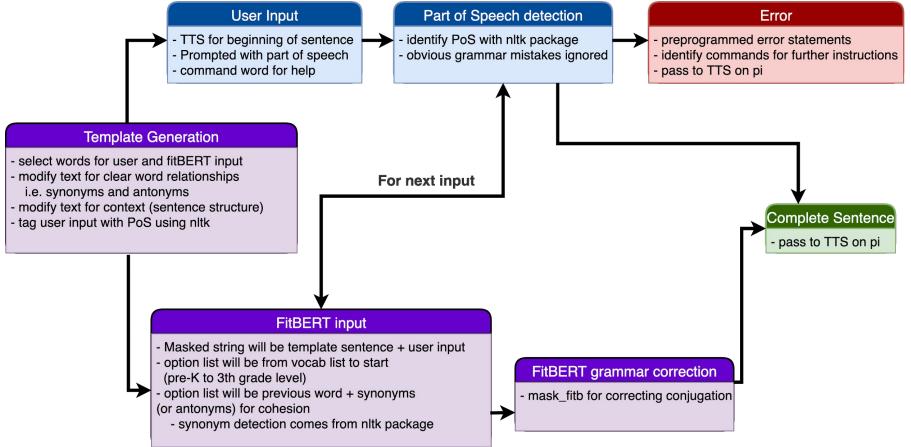
**Machine Learning:** receive user's input word, output sentence by sentence to TTS

- 1. Start with manually configured template, keywords removed
- 2. Prompts user for part of speech
- 3. User input goes through error detection and grammar correction
- 4. Algorithm predicts dependent words to customize the story

## System Diagram



**Story Generation Model** 



### Implementation Plan

#### **Machine Learning Storytelling**

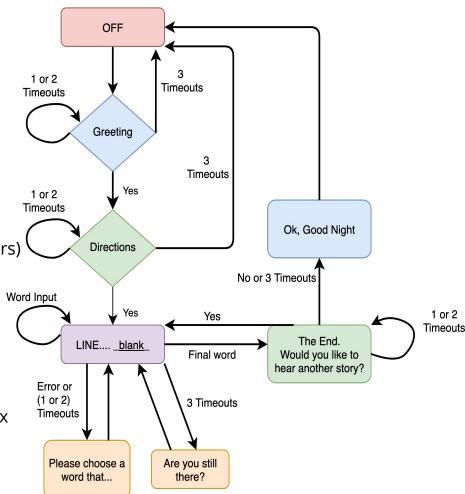
- Templates from Aesop's Fables (177 stories)
- NLTK natural language processing speech package
  - Part of speech tagging
  - Synonym generation and recall
- FitBERT 'Fill in the blanks' BERT

(Bidirectional Encoder Representations from Transformers)

- Sentence prediction
- Grammar correction
- Laptop for MVP, aim to put it on Nvidia Jetson Nano

#### **Speech Processing & Text to Speech**

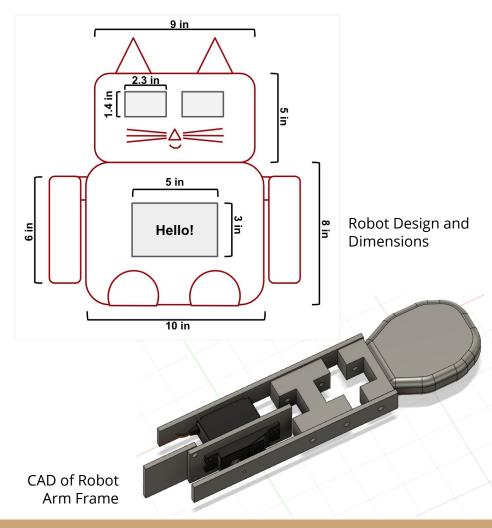
- Conference Microphone / USB Speakers
- Python Speech Processing Package with PocketSphinx
- Python gTTS
- Create a friendly voice by pitch shifting with PSOLA



### Implementation Plan

#### **Custom-made Robot**

- Laser-cut acrylic frame for support with
   3D-printed shell for aesthetics
- Body dimensions: 8" x 8" x 10"
   Head dimensions: 6" x 6" x 9"
  - Houses Raspi, batteries, displays, cables, etc
- 2x 1-DoF Robot Arms
  - o Dimensions: 1.5" x 1.5" x 6"
  - Servo motors provide enough torque to move weight of acrylic/PLA arm



### Metrics and Validation

Description	Goal	Verification Method				
Part of Speech Error Detection	90% accuracy	SW Testing - Test Dataset				
Synonym Recall	85% accuracy	SW Testing - Test Dataset				
Speech Processing Accuracy	15% Word Error Rate	Measure decoding errors				
System Latency	4 - 6 sec	Time user i/p to speech o/p				
Power	30 - 45 min	User testing				

### Metrics and Validation

Description	Goal	Verification Method				
Story Cohesion	Cohesion level falls between original stories and random stories	User survey - grade three types of stories based on 5 variables: Logical Sense, Themes, Genre, Narrator, Style				
User Satisfaction	<ul> <li>Liked the stories (87.5%)</li> <li>Wanted to play again (100%)</li> <li>Robot was friendly (87.5%)</li> <li>Robot's stories were interesting (87.5%)</li> <li>Robot's stories were understandable (100%)</li> </ul>	User Survey				

## Risk Management

Component	Risk Factor	Backup Plan				
Story Creation	Poor cohesion, Poor fill in the blank choices	Reduce number of user/FitBERT inputs in story templates				
Speech Recognition / TTS	Both rely on internet connection	Have local speech recognition and TTS capable packages				

# Project Management

	TASK TITLE	WEEK 1	WEEK 2	WEEK 3	WEEK 4	WEEK 5	WEEK 6	WEEK 7	WEEK 8	WEEK 9	WEEK 10	WEEK 11	WEEK 12	WEEK 13
	Dates	2/3/2020	2/10/2020	2/17/2020	2/24/2020	3/2/2020	3/9/2020	3/16/2020	3/23/2020	3/30/2020	4/6/2020	4/13/2020	4/20/2020	4/27/2020
	Important deadlines	Project Proposal			Design Presentation		Spring Break			Design Demo			Design Demo	Final Presentation
	Team Self-Education													
	Define detailed metrics													
	Research												Abha	
	> Audio input/output												Ashika	
	> Speech processing package												Jade	
	> Story generation pipeline + algorithm												Abha+Ashika	
77	> Robot design												Abha+Jade	
	> Communication protocols												Ashika+Jade	
	Evaluate solution approaches												Everyone	
	Design & Build MVP Parts													
	System Architecture Diagram													
	System interaction design													
	Hardware Benchmarks and Metrics													
	Software Benchmarks and Metrics													
	Write Design Document													
	Prepare for Design Presentation													
	Bill of Materials/Order Parts													
	Analog input/output schematics													
	Audio input implementation													
	Speech Processing on RPi													
	Text to speech on RPi													
	Communication Protocols			The state of the s										
	Face Display													
	Robot arms													
	Path Planning for arms													
	Robot Shell and Aesthetics													
	ML dataset gathering													
	Part of speech tagging													
	> Error detection for user input													
	> Synonym detection													
	> Template making													
	Fill in the blank													
	ML story generation unit testing													
	Integration and Testing													
	Audio input to ML algorithm													
	Robot displays text from ML algorithm													
	Robot text to speech													
	Gesture evaluation													
	Design Evaluation & Improvement													
	Whole system testing													
	Design evaluation													
	Improvements													
	Final system testing													
	Prepare for Final Presentation													