

What did you personally accomplish this week on the project?

- Contracted the illness
- Recovered from the illness
- Mounted and wired all sensors on robot frame
 - 3 ultrasonic sensors angled away from each other so they don't cause interference
 - Secured thermal camera below middle ultrasonic
- Test ultrasonic sensors and thermal camera with raspberry pi setup
 - Some issues with ultrasonic feedback
 - Battery charged
- Although the load sensor is wired up, it needs to be tested

Schedule:

- The next week will have to complete all necessary components, and any extra time will be dedicated to stretch goals, such as the speaker.

What deliverables do you hope to complete in the next week?

- Test load cell with tray configuration
- Add "kill switch" to instantly stop motors