TEAM C3: InteracTable

Suann Chi Isha Iyer Tanushree Mediratta

Application Area

Better collaboration with others

Larger surface area to work on

Lower cost and more portable than market alternatives

Solution Approach

Portability and Larger Working Area

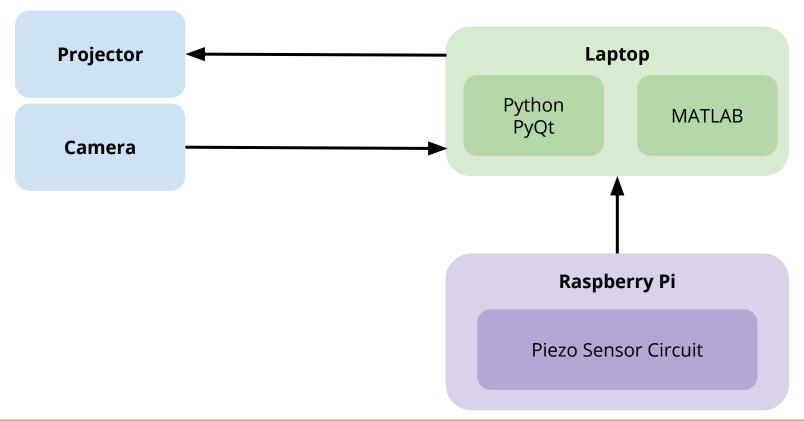
Foldable stands Small projector, webcam Small Circuit

Projector focus adjustable Stand height adjustable Algorithms

Color Detection
Circle Detection

Lucas-Kanade Tracking

System Specification: Overall Design



Software Flow Diagram Camera Laptop **MATLAB Python** Raspberry Pi Tap detected Data Handler Object Detection/ Tracking GUI Tap coordinates **Piezo Sensors**

Metrics and Validation

Distance from detected coordinate of blob center to the desired center coordinates

Detected coordinate within button boundaries

Low latency - ideally less than 1 second

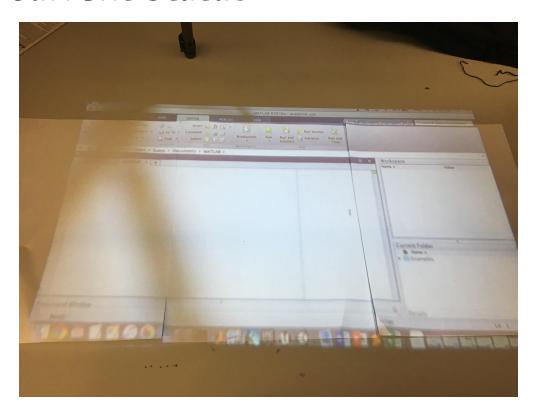
How accurate the piezo sensor can detect a tap

Project Management



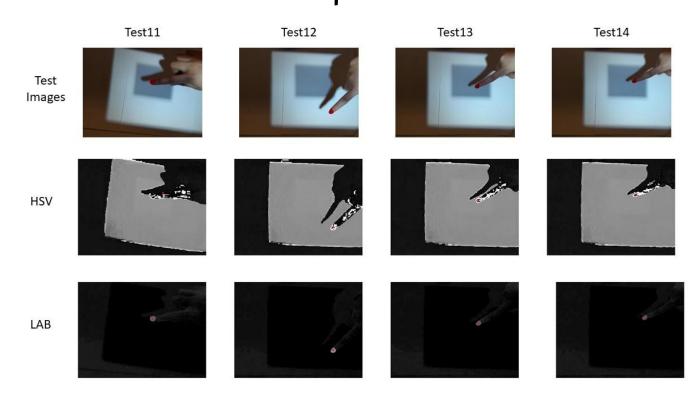
	Jan	I		Feb	Mar				Apr				May			
Davage al Dalissandhiae	28	3	6	13	20	27	6		ľ	27	3		17	24	4	
Personal Deliverables	28	3	0	13	20	21	ь	13	20	21	3	10	17		1	8
1000 SI																
Slack									-	-						
Finish Color Detection							4									
Tracking Algorithm																
Lucas Kanade						_										
Blob Detection																
audio manipulation																
Object Detection																
with tracking/detection																
integrate with																
parts (stands, camera,																
Create sensor circuit																
decide threshold																
with projector and																
and sensor data																
environment																
presentation																
Write paper																

Current Status

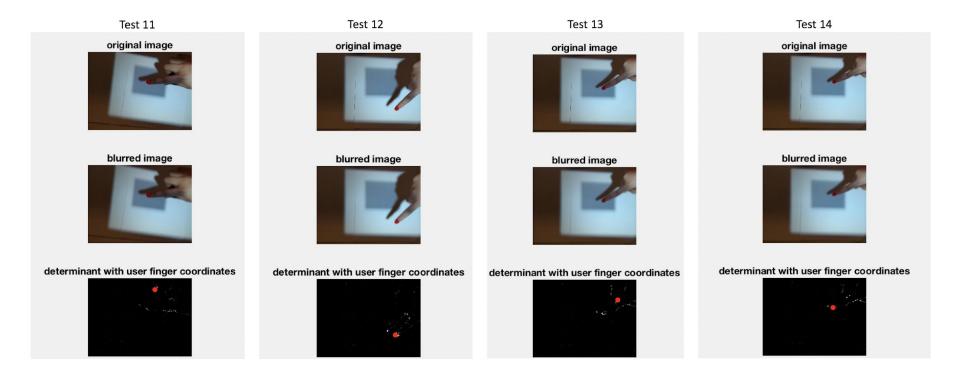




Current Status: Results for Color Detection



Current Status: Results for Circle/Blob Detection



Conclusion

Detection algorithms have preliminary results. Need more testing.

- Sprint 2:
 - Piezo sensor circuit
 - K-means clustering
 - MATLAB-Python pipeline