Gesture Glove

B4 - Rachel Tang, Stephanie Zhang, Sophia Lau

Use Case/Application Area

- Help people who sign ASL communicate with others who do not understand ASL
- Recognizes gestures and hand directions
 - 26 ASL letters



Quantitative Requirements

| Requirement | Measurement |
|---------------|------------------|
| Accuracy | 90% |
| Latency | Less than 100ms |
| Frequency | .5 S per gesture |
| Craftsmanship | 200 g |



Solution Approach



Block Diagram







System Specification

- Spectra Symbol Flex Sensors
- InvenSense ICM-20948 9-DoF IMU
- Arduino Nano







ML Models

- Support Vector Machines
- Perceptron
- KNN
- Random Forest
- Neural Network (scikitlearn default of two layers w/ 10 nodes per layer)



Generating Fake Data

- Normal distributed selection of angles for fingers
- Random choosing of accelerometer + gyroscope data since we are mostly looking at static poses
- Magnetometer selected from a range based on directions
- Sample data:
 [42.42 23.83 15.07 18.95 15.84 1.62 0.92 0.02 4.84 4.02

2.67] Flex sensors, accelerometer, gyroscope, magnetometer,





Comparing ML Models

Random Forest: 0.8177



SVM: 0.7362



Neural Net: 0.7308



Perceptron: 0.6369



KNN: 0.7438





Metrics and Validation

| Requirement | Measurement | Testing Procedure |
|---------------|------------------|--|
| Accuracy | 90% | Have 10 people make each gesture 3 times |
| Latency | Less than 100ms | Start a software timer beginning when the gesture is finished and end a timer when the algorithm outputs the gesture recognition |
| Frequency | .5 S per gesture | Glove should be able to detect two signs per second |
| Craftsmanship | 200 g | Measure the weight of the glove after fabrication |



Implementation Plan



Schedule

| | 9/13 | 9/20 | 9/27 | 10/4 | 10/11 | 10/18 | 10/25 | 11/1 | 11/8 | 11/15 | 11/22 | 11/28 |
|--|------|------|------|------|-------|-------|-------|------|------|-------|-------|-------|
| Make proposal presentation + website | | | | | | | | | | | | |
| Order parts (arrive by 9/27 - expedite shipping if necessary) | | | | | | | | | | | | |
| Do proposal presentation | | | | | | | | | | | | |
| Build and order PCB | | | | | | | | | | | | |
| Write program for serial streaming | | | | | | | | | | | | |
| Attach flex sensors | | | | | | | | | | | | |
| Test that we get consistent data from flex sensors with each gesture | | | | | | | | | | | | |
| Prepare design review | | | | | | | | | | | | |
| Do design presentation | | | | | | | | | | | | |
| Design report | | | | | | | | | | | | |
| Install PCB onto glove | | | | | | | | | | | | |
| Attach IMU | | | | | | | | | | | | |
| Test that we get consistent data from IMU with each gesture | | | | | | | | | | | | |
| Determine ML Model | | | | | | | | | | | | |
| Integrate glove with Software side | | | | | | | | | | | | |
| Collect data (for training and testing) | | | | | | | | | | | | |
| Train model | | | | | | | | | | | | |
| Test model ourselves | | | | | | | | | | | | |
| Get other people to test (gather survey data) | | | | | | | | | | | | |
| Make adjustments as needed from feedback | | | | | | | | | | | | |
| Make final presentation | | | | | | | | | | | | |
| Final presentation | | | | | | | | | | | | |
| Final report | | | | | | | | | | | | |

everyone

sophia stephanie

rachel

stephanie + rachel