

Team A2

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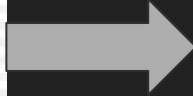
Make sure to cover:

- Use Case
- Requirements
- Solution Approach
- Testing, Verification and Metrics
- Tasks and Division of Labor
- Schedule

LaSEEr

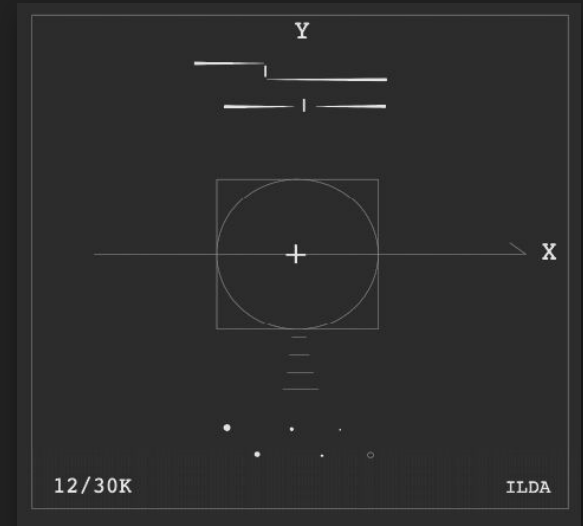
Laser Display with Edge detection

Use Case



Requirements

- The system shall be able to draw a minimum of 10 frames per second.
- The system shall be able to use a camera feed as an input.
- The system shall be able to draw the ILDA 12k or 30k test patterns with greater than 90% accuracy.
- The safety subsystem shall never allow the laser to persist in an unsafe state for more than 100ms.
- The laser shall be visible in a brightly lit room and should have a minimum projection area of 5'x5'.



Solution Approach

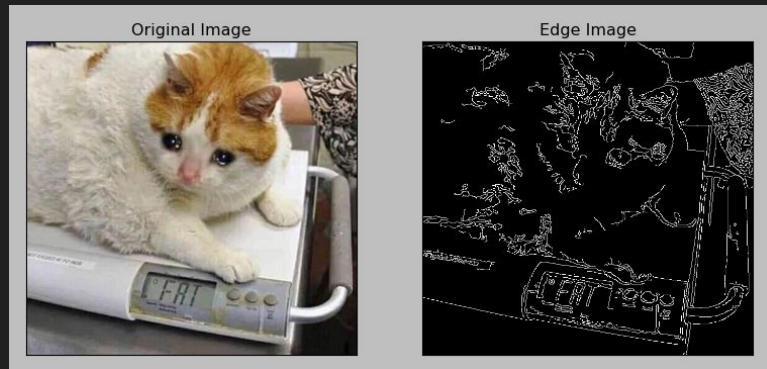


Camera to Frames

- Decided to use Raspberry Pi 4 for the platform.
- Don't want to waste time writing camera driver.



Frames to Coordinates



Camera Feed + Canny Edge Detection



ILDA Format (.ild)

DAC

- Need to create voltage offsets to control the galvanometer.
- Also need to be able to dim the lasers.

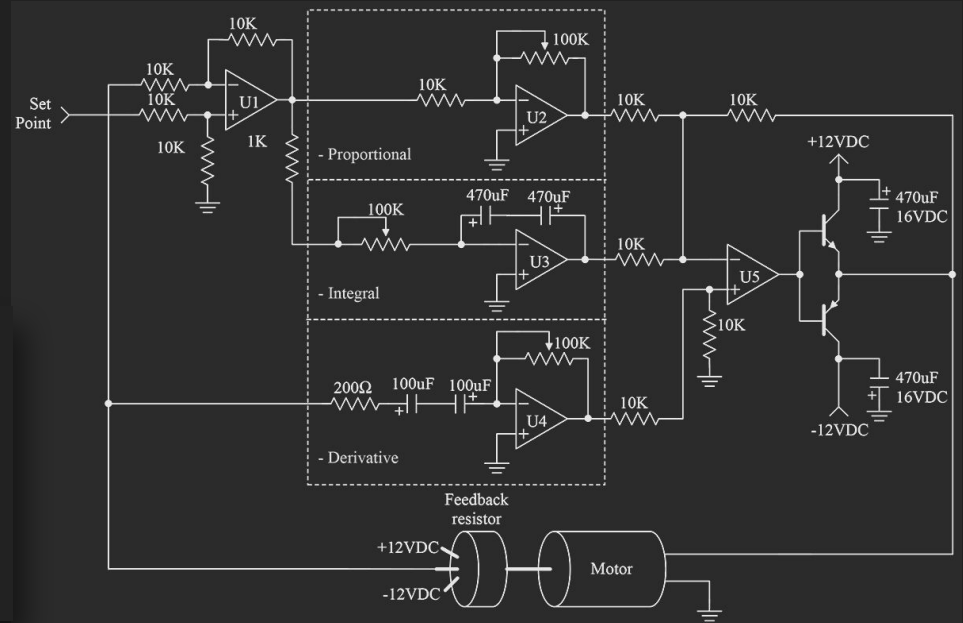
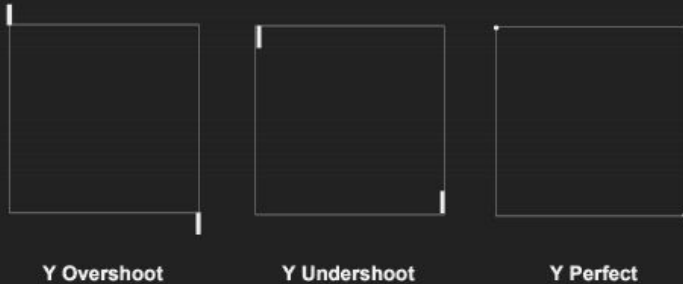
Why not just use onboard RPi DAC?

- DC Blocking



PID

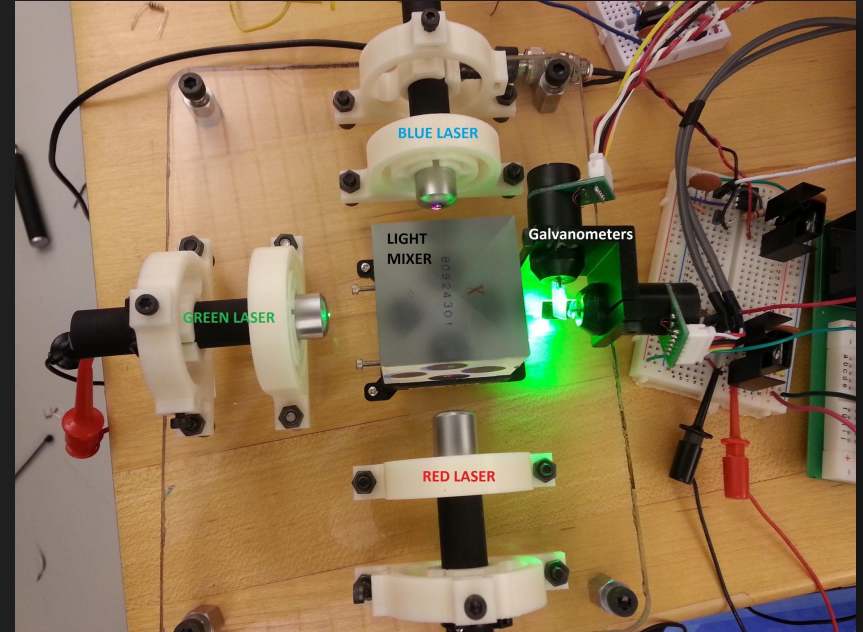
- Plan to do this with analog circuits.
- Minimize processing power.
- Also it's a fun challenge.



https://www.nutsvolts.com/magazine/article/the_pid_controller_part_1

Laser Setup

- Red, green, and blue color lasers combined with a light mixer cube.
- Galvanometers with mirrors for X and Y axis used to project laser to screen.



Safety Subsystem

- Emergency power cut-off switch for lasers.
 - Lasers can easily be damaging to eyes.
- Monitoring for laser power draw and galvanometer movement.



Testing, Verification and Metrics

- Edge Detection and Coordinate Creation
 - Testing pipeline with sample video, images with different edge density
 - Verify that system can process 640x480 video at 10fps and if not properly downsize the content

- Hardware and Lasers
 - Use ILDA test patterns prepared for various points per second ratings for testing
 - Verify that our hardware is able to run galvanometers at 20K points per second speed without overheating

Tasks and Division of Labor

- High level Software - Enes (50%), Eliana (50%)
- Low level Software - Enes (50%), Eliana (50%)
- Hardware - Jake (80%), Enes (10%), Eliana (10%)
- Flexibility to help as needed

