

Lecture #2

# Embedded Hardware

18-348 Embedded System Engineering

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Friday, 15-Jan-2016



Carnegie  
Mellon

## Announcements

- ◆ **Many posted materials are accessible only from a CMU IP Address**
  - Look for this on course web page:  
If you can't access a file due to access restrictions, you need to get a campus IP address for your web browsing requests. Use [Cisco VPN Anyconnect...](#)
- ◆ **Course web page has schedules, assignments, other important info**
  - <http://www.ece.cmu.edu/~ece348>
  - Blackboard will have grades, announcements, sample tests
  - Look at blackboard announcements before sending e-mail to course staff
- ◆ **Lab board handouts in progress**
  - See Blackboard/admin page for TA office hours
  - OK to go to any scheduled lab section (but, give priority to scheduled students)
  - For Friday prelab give a good faith attempt to get things working by the deadline
    - If you hit a showstopper get it fixed on Tuesday so you can do Prelab 2 on time.

## Design Example: Rack-Mount Power Supply

### ◆ Power supply for server

- AC to DC conversion (750-1000W)
- Coordinates 2 redundant supplies to maximize uptime
- Safeguard against power problems (under/over-voltage; over-current; over-temp)

### ◆ Typical approach:

- General microcontroller for AC, alarms, housekeeping
- DSP runs control loop on DC side at > 10 KHz to provide stable DC power

### ◆ Key requirement:

“Doesn’t emit smoke”



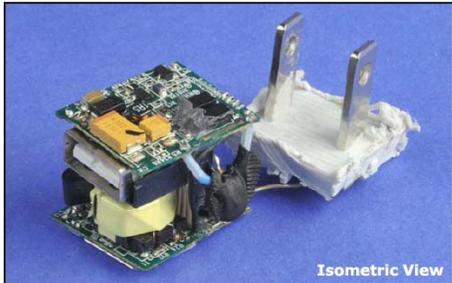
<http://accessories.us.dell.com>  
Dell 870W Power Supply for PowerEdge R710 Server

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Portelligent **AC Adapter (Internal Components)** iPhone 3G

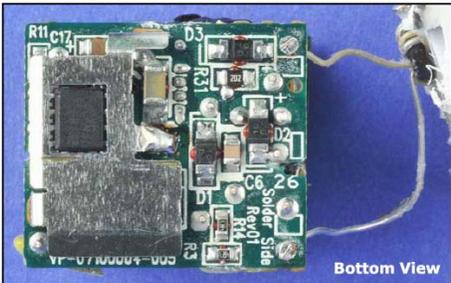


Top View



Isometric View

Top, Bottom, and Isometric views show two PCBs, each populated on both sides.



Bottom View



© Copyright 2008 Portelligent Inc., All Rights Reserved. Comments about costing? Email us at [feedback@teardown.com](mailto:feedback@teardown.com) Apple 3G iPhone 11000-080711-BCf - Page 10

## Where Are We Now?

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- ◆ **Where we've been:**
  - Course Intro
- ◆ **Where we're going today:**
  - Embedded system hardware
- ◆ **Where we're going next:**
  - Microcontroller assembly language
  - Engineering design approaches
  - Embedded-specific C
  - ...

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## Preview

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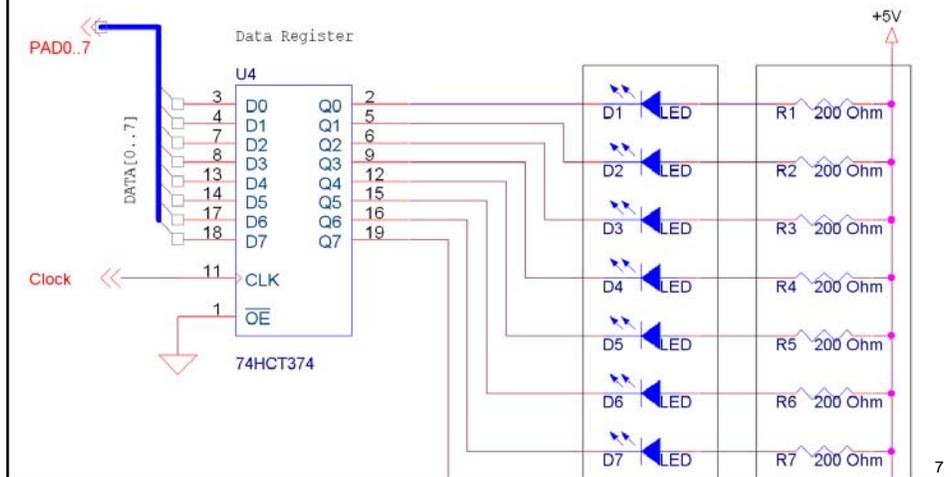
- ◆ **Microcontroller Hardware**
  - How does a microcontroller connect to the rest of the system?
  - I/O bus
  - Support circuitry
  - Power supplies
- ◆ **Hardware implementation**
  - Prototyping techniques
  - Printed circuit boards
- ◆ **Data sheets**
  - Tour of typical data sheet values

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## Hardware Schematics For Digital Electronics

### ◆ Conventions:

- Chips are rectangles (except small logic gates); inputs on left; outputs on right
- Pin numbers shown to make wiring easier
- Thick blue line indicates a “bus” (8 wires bundled into one in this case)



## Schematic Capture Tools

### ◆ OrCad or other professional-grade tools

- (Schematic on previous page drawn with demo OrCad)

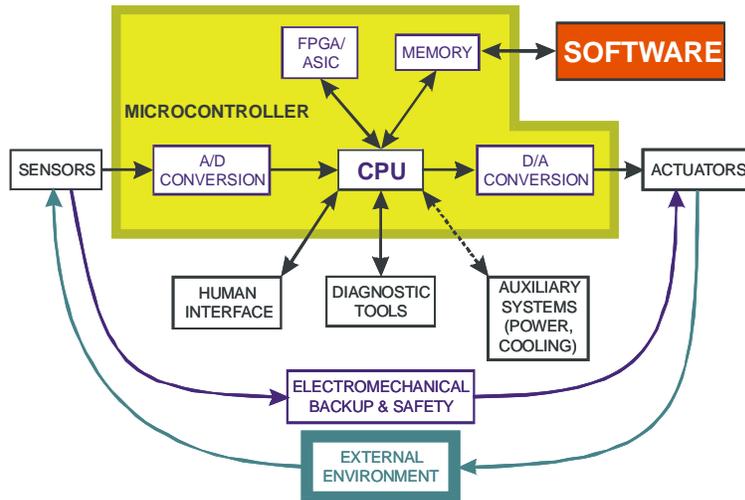
### ◆ Free tools from PCB vendors (“Printed Circuit Board”)

- For example, [www.expresspcb.com](http://www.expresspcb.com) (although I’ve never used their actual board service); there are several such vendors
- <http://www.freepcb.com/> open source (GPL)
- Search term: printed circuit board prototype

## Stuff that goes around a microcontroller/overview

### ◆ A microcontroller can't do much without surrounding parts

- Even though it has a lot of things already built into it
- Let's talk about how you hook a chip up into a system

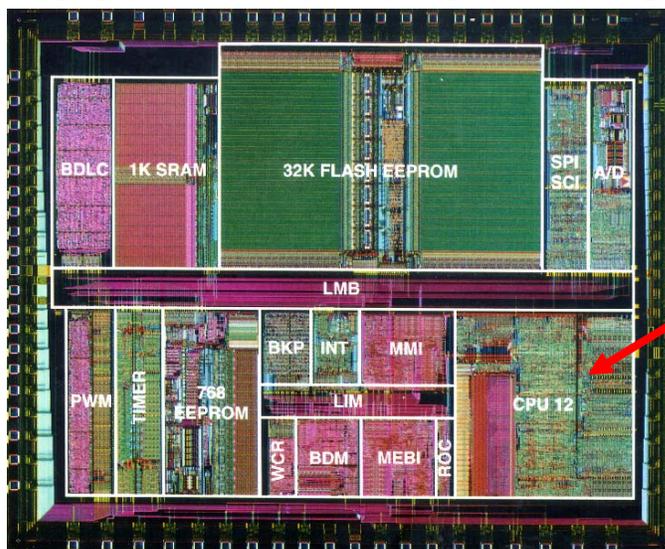


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## CPU 12 Microcontroller

### ◆ The actual "CPU" is only a part of the chip

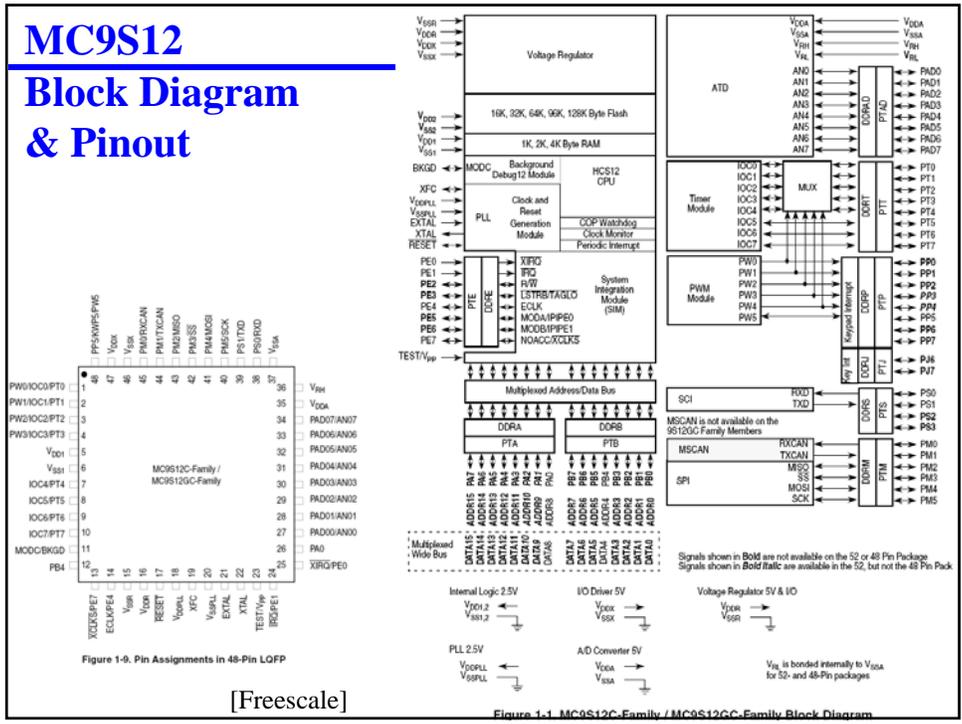
- Many peripherals and memory already integrated onto the chip



[Freescale]:

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# MC9S12 Block Diagram & Pinout

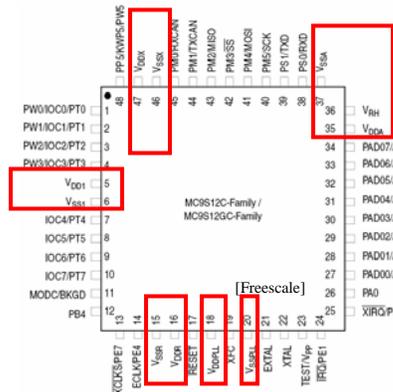


## Power

- ◆ DC electrical power to run the CPU and power I/O circuits
- ◆ Some standard voltages
  - 5V DC – old style from the first commercial logic chips, but still in common use (“TTL logic levels”)
  - 3.3V DC – common in newer designs
  - Lower voltages often used for low power

- ◆ MC9S12C family:
  - 5V for Analog functions and 5V interface – 2.97 to 5.5 volts allowed; can run at 3.3V
  - 2.5V for internal logic – 2.35 to 2.75 volts allowed
  - 25 mA maximum per pin drive current
  - Multiple power/ground pins

- ◆ Actual voltages used depend on power strategy
  - Will this chip run on two NiCd or NiMH batteries? Does that provide 3V?



## Embedded Power Supplies

### ◆ Battery

- Primary battery – alkaline is 1.5V nominal
- Secondary battery (rechargeable) – NiMH is 1.2V nominal (so is NiCd)

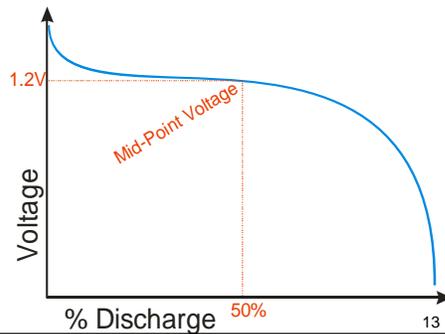
### ◆ Wall transformer

- A/C to DC conversion (a.k.a. “wall wart”) – usually 5V to 12V DC output

### ◆ Sometimes, on-board battery recharging (e.g., solar cells)

### ◆ Need DC voltage regulation – even for batteries

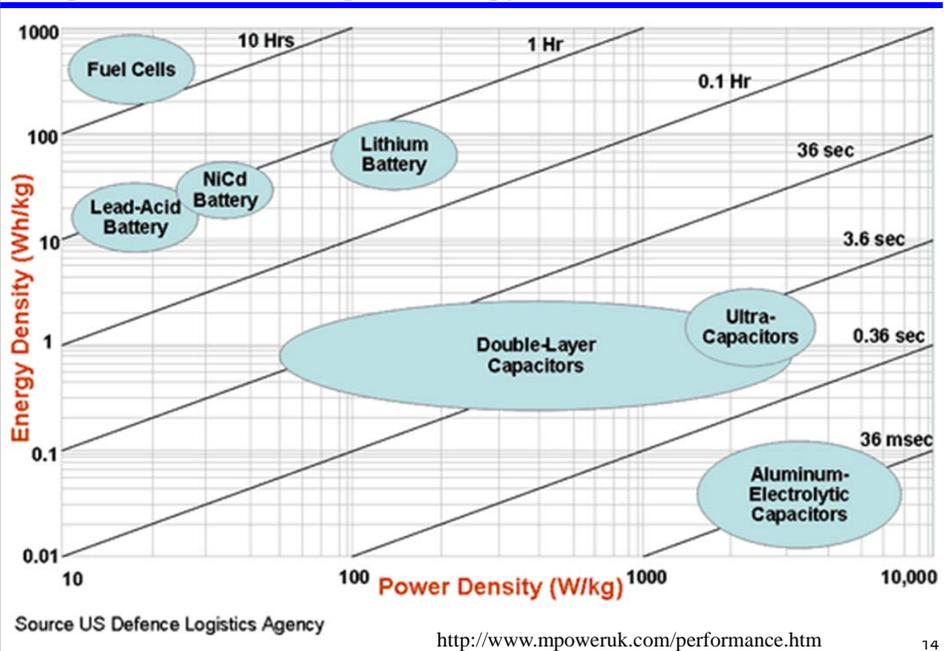
- Battery voltage isn't constant
- Nominal rating at mid-point voltage
- 4 @ NiMH cells 1.2V nominal => 4.8V
- Mostly discharged, 1.1V/cell => 4.4V total



### ◆ On-circuit board power regulation:

- Usually DC to DC converters
- “Boost” converter increases DC voltage
  - Usually inefficient
  - But, reduces # of battery cells needed
- “Buck” converter decreases DC voltage

## High Power or High Energy (but not both)



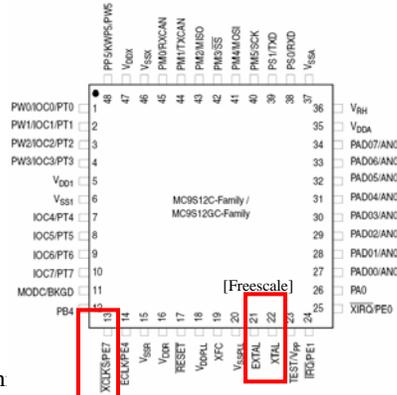
# Oscillator/“clock”

## ◆ Periodic square wave for clocking the CPU

- Has an internal low-quality oscillator
- Permits use of an external high-quality oscillator
- **Why both options? -- cost**

## ◆ MC9S12C family oscillator speeds

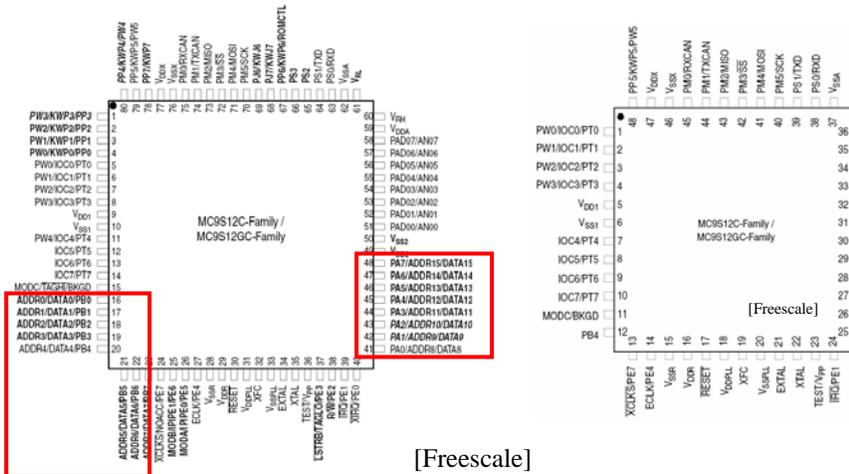
- 0.5 to 16 MHz on internal oscillator
- 0.5 to 40 MHz external (input must be ~50% duty cycle)
  - Each edge triggers internal actions
- XCLKS used at startup to select internal vs. external oscillator
- **Why “slow” clock speeds?**
  - Keeps costs down – can use old process tech
  - Saves power; reduces need for cooling
  - Fast enough for many purposes
  - Reduces emitted radio interference



# I/O bus: data; address

## ◆ We’re using a smaller package (48 pin) to reduce costs

- That package doesn’t put the memory bus on the pins



Signals shown in **Bold** are not available on the 52- or 48-pin package  
 Signals shown in **Bold Italic** are available in the 52-pin, but not the 48-pin package

Figure 1-7. Pin Assignments in 80-Pin QFP

## Available I/O pins

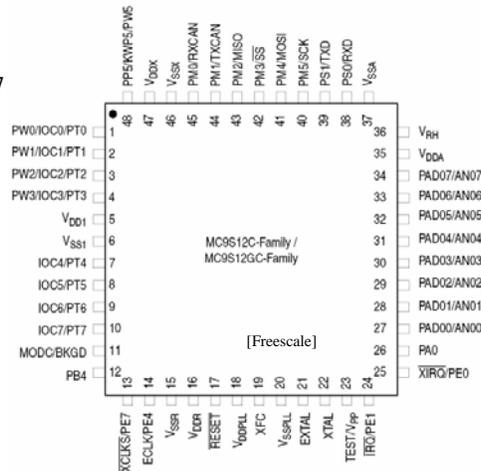
### ◆ Pins are used for multiple purposes to reduce packaging costs

- Configuring chip to put right signals on the right pins is chapter 2 of data sheet
  - It's really tricky and confusing
- Initially, we'll give you code to set up chip the right way for labs

### ◆ Most important pins:

- PAD00..PAD07 // AN00 .. AN07 provides digital and analog I/O
- PT0..PT7 provides additional digital I/O
- PW0..PW3 provides hardware-assisted pulse generation

### ◆ Data sheet lists all the signals



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## Registers & Memory Maps

### ◆ How do you get data on and off the pins?

- Interface to I/O is done via **“registers”** (a set of flip-flops on the chip)
- Write to registers to configure the pins – e.g., is it digital or analog?; in or out?
- Read/write other registers to actually do I/O
  - Read a byte from switches by reading register associated with digital inputs
  - Write a byte to LEDs by writing a register associated with digital outputs
  - But in both cases, first configure I/O via setting some register, then read/write values from a different register

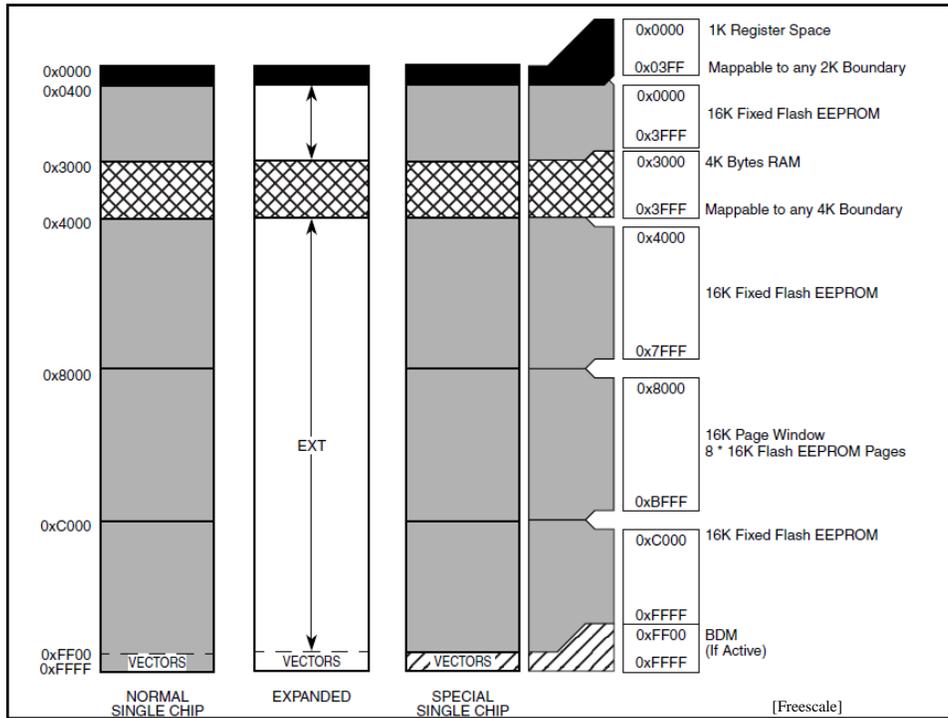
### ◆ How do you access these registers?

- In some processors, an I/O instruction (x86: IN and OUT)
- In our processor, I/O is **“memory mapped”**
  - Use “load” and “store” instructions to special memory addresses

### ◆ A memory map tells you where things are in memory

- Some of memory is RAM
- Some of memory is ROM
- Some of memory is I/O register space
- Look for the memory map in the data sheet. Lots more detail in later lectures

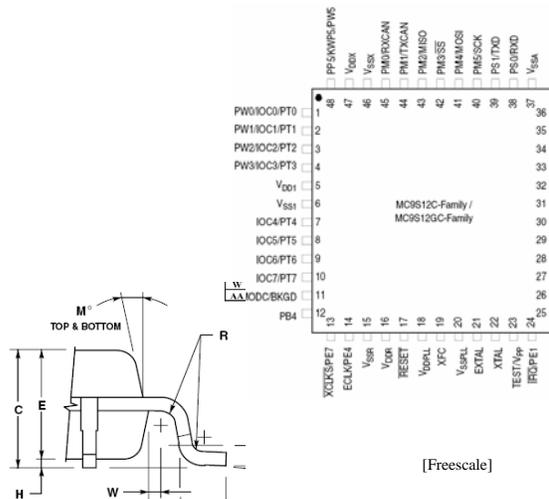
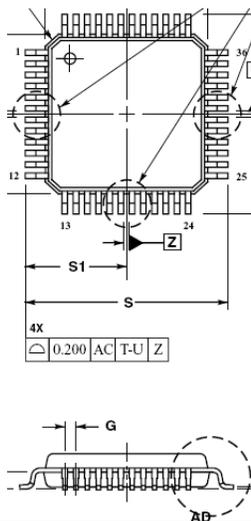
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## Chip packaging

### ◆ 48-pin LQFP (low-profile, quad, flat package)

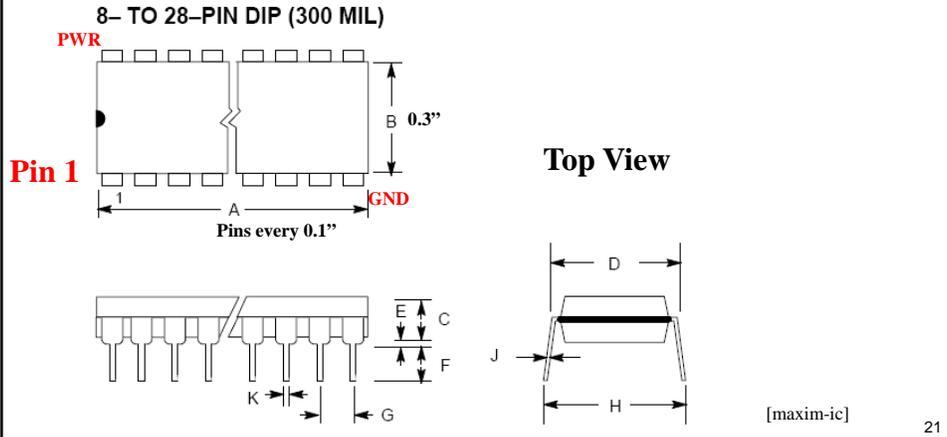
- (surface mount – pins soldered to top layer of circuit board)
- Pin 1 is found at the molded circle in the package



## Which one is pin 1???

### ◆ DIP = “dual in-line package”

- Through-hole mounting – chip pins go through circuit board
- For N-pin DIP, ground is pin N/2; power is pin N  
e.g., 20-pin DIP – pin 10 is ground; pin 20 is power
- *If you put the chip in backward, you reverse power & ground; smoke ensues*



## Breadboards/proto-boards

### ◆ Simple to use – push in wires, DIPs, other components

- Easy to use, but fragile (easy to pull out wires)
- After a few hundred insertions, they wear out

### ◆ Tips:

- Try to keep wires neat
- Put all pin 1s to the left (if horizontal) or top (if vertical)

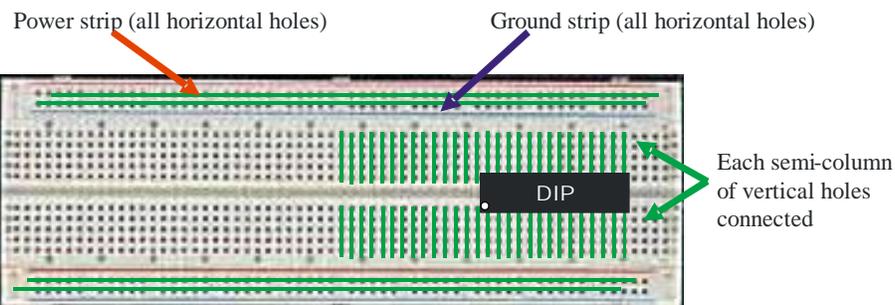


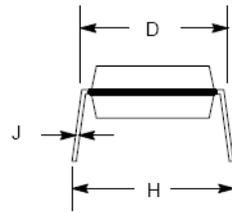
Photo portion: [Axiom]

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## How to insert a chip in a socket or proto-board

### ◆ Pins are further apart than socket holes

- Dimension “H” is bigger than Dimension “D” but sockets are sized for Dimension “D”
- This keeps pins from dropping out of holes for printed circuit boards without sockets – but it makes using sockets a problem



[maxim-ic]

### ◆ To insert a chip

- Touch something metal first to discharge any static (in industry, use a grounding strap on your wrist or ankle)
- Use a chip insertion tool if you have one (it pushes the pins straight) OR gently bend the pins together using a flat table top so they are straight
- Push the DIP in, making sure than no pins get bent under

### ◆ To remove a chip

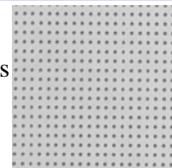
- Use a chip removal tool if you have one
- Else use a small screwdriver to pry the chip loose at each end, then rock it free

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## Other Prototyping techniques

### ◆ “Perf board”

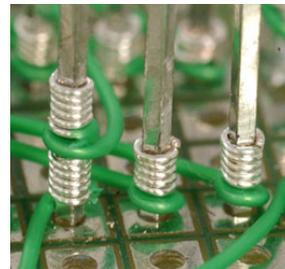
- Boards with “perforated” (punched) holes on 0.1” centers
- Can put in sockets and solder wires to make connections



[Jameco]

### ◆ Wire wrap

- Usually perf board, but with special sockets with long square pins
- Wire wound around the square pins makes the connections
- Pins are long enough to fit three wrapped wires



### ◆ Printed circuit boards

- You can get ‘quick turn’ boards in small numbers fairly inexpensively
- But, making changes is painful



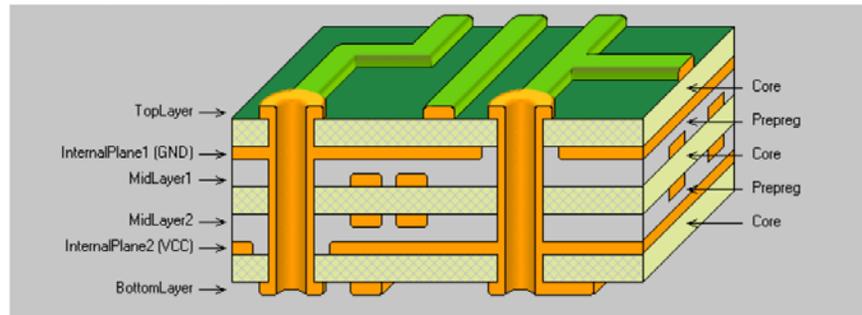
[Jameco]

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## Printed circuit boards

- ◆ **One or more sheets of thin fiberglass coated with copper on both sides**
  - Copper is etched away to leave circuit traces and “pads”
  - Holes are drilled through to make “vias” and places for DIP pins
  - Insulation between fiberglass is “prepreg” – pre-impregnated bonding layers
- ◆ **Good idea to have plenty of power and ground**
  - Usually want dedicated ground layer & dedicated power layer

### Multi layer Design



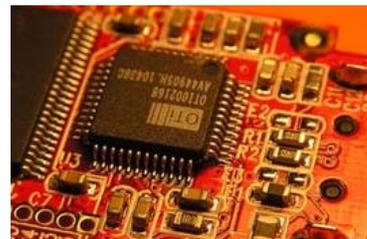
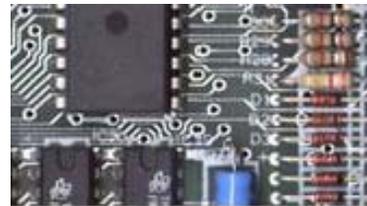
Typical 6 Layer PCB Construction

[Jones94]

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## Through-hole vs. surface mount

- ◆ **Through-hole**
  - DIP pins and resistor leads, etc. go all the way through the PCB
  - Each pin eats up space on every layer of the board
  - Older technology – requires wide pin spacing and works poorly with more than about 8 layer PCBs
- ◆ **Surface mount**
  - Pins only attach on top layer
  - Finer pitch pins, higher density
  - Newer technology
  - Difficult (or with Ball Grid Array pretty much impossible) to hand-solder prototypes without using sockets.



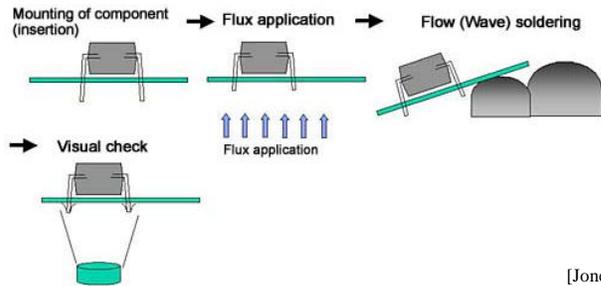
[Wikipedia]

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## Getting Components On To The Board

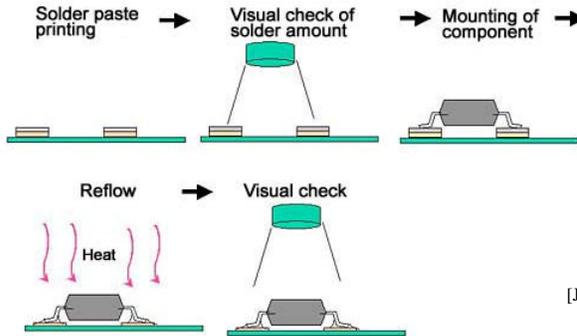
### ◆ Wave soldering:

**RoHS:** Restriction of Hazardous Substances (get the lead out of solder)



[Jones94]

### ◆ Reflow Soldering:



[Jones94]

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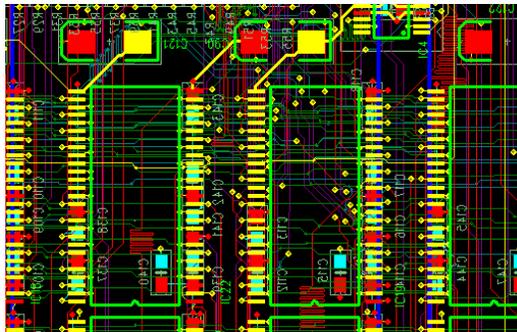
## Layout tools & challenges

### ◆ Layout is a difficult 2.5-dimension puzzle

- K layers, where K is usually even
- Pretty much like IC layout – very similar algorithms
- Auto-routers have gotten better over time, but still some hand-assist
- Using a CAD tool, each layer is a different color

### ◆ Common design strategies

- Dedicated layer for power and for ground (helps with noise)
- Even layers are mostly horizontal, odd layers are mostly vertical



[einternational.net]

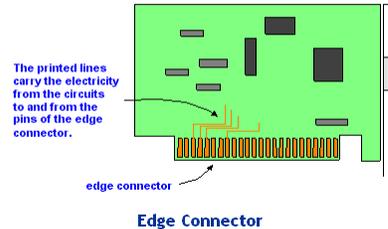
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## External connectors: headers; edge connectors

From Computer Desktop Encyclopedia  
© 2005 The Computer Language Co., Inc.

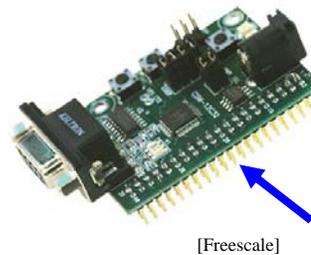
### ◆ Edge connectors

- Plated areas of circuit board
  - Usually gold or copper
  - Tin tends to corrode – unreliable
- Old-style PCs used these to connect onto motherboard (ISA bus)



### ◆ Headers

- A set of posts for connecting
- Posts insert into sockets or can be clipped, wire-wrapped, soldered to, etc.
- Especially popular – ribbon cable (caution, most ribbon cables only good for a half-dozen insertions before becoming unreliable!)



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## Switches

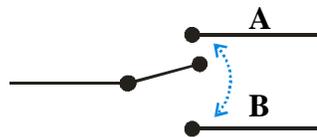
### ◆ Single pole, single throw switch

- E.g., ordinary house lighting switch
- It's "on" or "off" and switches a single line
- Stays "on" or "off" unless moved



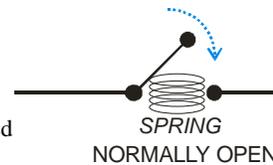
### ◆ Double pole, single throw switch

- 3-way house lighting switch
- Either "side A on" or "side B on"
- Stays on A or B once there, unless moved



### ◆ Momentary switch

- "normally open" – "off" normally, "on" when pressed
  - These are the switches on the lab project board
- "normally closed" – "on" normally, "off" when pressed
  - The brake pedal on your car is this type of switch



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## Data sheets overview

### ◆ Data sheets are the roadmap to a chip

- Vary between 1 sheet and 500+ sheets
- Every circuit part has a data sheet – even a resistor or socket
- In industry, there is a library of data sheets for approved parts (and getting a new part approved is a huge deal – so you use parts that are already approved)

### ◆ Data sheet content

- Pinout
- Physical characteristics (package size, pin type, etc.)
- Electrical characteristics
- Thermal limits
- Etc.

### ◆ MC9S12C data sheet Appendix A has electrical characteristics

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## Key items in data sheet: speeds

### ◆ Propagation delays

- Low to high and high to low are sometimes different speeds
- Speeds depend on operating conditions

PARAMETER	SYMBOL	TEST CONDITIONS	V <sub>CC</sub> (V)	25°C			-40°C TO 85°C		-55°C TO 125°C		UNITS
				MIN	TYP	MAX	MIN	MAX	MIN	MAX	
<b>HC TYPES</b>											
Propagation Delay Clock to Output	t <sub>PLH</sub> , t <sub>PHL</sub>	C <sub>L</sub> = 50pF	2	-	-	165	-	205	-	250	ns
			4.5	-	-	33	-	41	-	50	ns
		C <sub>L</sub> = 15pF	5	-	15	-	-	-	-	-	ns
		C <sub>L</sub> = 50pF	6	-	-	28	-	35	-	43	ns
Output Disable to Q	t <sub>PLZ</sub> , t <sub>PHZ</sub>	C <sub>L</sub> = 50pF	2	-	-	135	-	170	-	205	ns
			4.5	-	-	27	-	34	-	41	ns
		C <sub>L</sub> = 15pF	5	-	11	-	-	-	-	-	ns
		C <sub>L</sub> = 50pF	6	-	-	23	-	29	-	35	ns

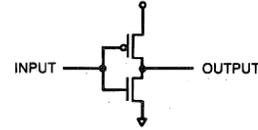
[TI]

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## Outputs & Inputs

### ◆ Regular output driver and input buffer:

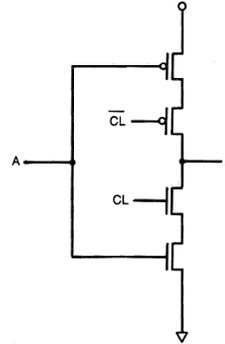
- Amplifies on-chip to off-chip current capability
- Usually just an inverter with big (high drive) transistors
  - (real chip implementations more complex; but that's the basic idea)



[Weste95]

### ◆ Tri-state output drivers:

- Has ability to output “0”, “1”, or “Hi-Z” (off)
  - CL high turns it on, propagating input A
  - CL low turns output off (Hi-Z)
- Allows multiple chips to drive the same signal



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## Key items in data sheet: electrical specifications

### ◆ Be sure to look for

- Power consumption when running
- Input and output parameters, especially
  - Input switching thresholds:  $V_{IH}$ ,  $V_{IL}$
  - Output drive currents:  $I_{OH}$ ,  $I_{OL}$  (in mA or ‘standard loads’)

DC Electrical Specifications (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS		$V_{CC}$ (V)	25°C			-40°C TO 85°C		-55°C TO 125°C		UNITS
		$V_I$ (V)	$I_O$ (mA)		MIN	TYP	MAX	MIN	MAX	MIN	MAX	
Quiescent Device Current	$I_{CC}$	$V_{CC}$ or GND	0	6	-	-	8	-	80	-	160	$\mu A$
Three-State Leakage Current	$V_{IL}$ or $V_{IH}$	$V_O = V_{CC}$ or GND	-	6	-	-	$\pm 0.5$	-	$\pm 5.0$	-	$\pm 10$	$\mu A$
<b>HCT TYPES</b>												
High Level Input Voltage	$V_{IH}$	-	-	4.5 to 5.5	2	-	-	2	-	2	-	V
Low Level Input Voltage	$V_{IL}$	-	-	4.5 to 5.5	-	-	0.8	-	0.8	-	0.8	V

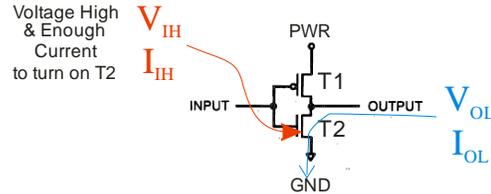
[TI]

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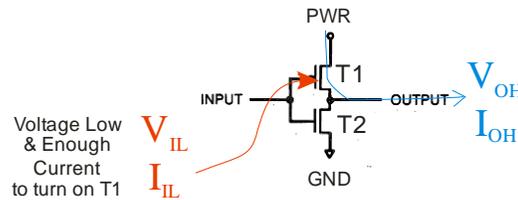
## Key Voltage & Current Specifications

### ◆ Input switching thresholds:

- $V_{IH}$  = Input Voltage that is seen as a “high” input
  - For example, any input above 2 Volts is High;  $V_{IH} = 2V$



- $V_{IL}$  = Input Voltage that is seen as a “low” input
  - For example, any input below 0.8 Volts is Low;  $V_{IL} = 0.8V$
  - In these examples: anything between 0.8V and 2.0V is indeterminate

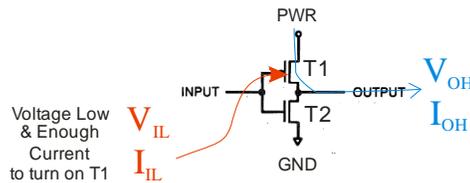


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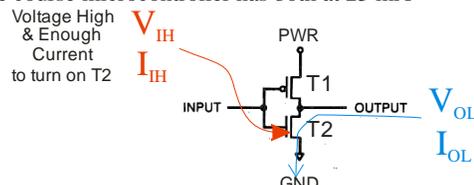
## Key Voltage & Current Specifications

### ◆ Output drive currents:

- $I_{OH}$  = Current driven if output is high
  - For example, a high output at 4.5V might drive .5 mA



- $I_{OL}$  = Current driven if output is low
  - For example, a low output at 0.5V might drive 25 mA
  - $I_{OL}$  is often much higher than  $I_{OH}$ ! And usually only a few mA for TTL chips
  - But, the course microcontroller has both at 25 mA

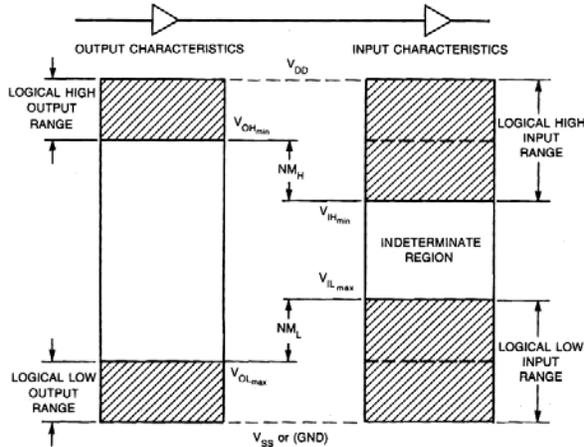


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## Noise Margin: Input vs. Output Voltage

◆ Real chips have three output voltages that matter:

- High enough to be a "1" --  $V_{OH} > V_{IH}$
- Low enough to be a "0" --  $V_{OL} < V_{IL}$
- Something in between – a "I'm not sure if I'm a 1 or a 0" voltage (this is **Not Good**)

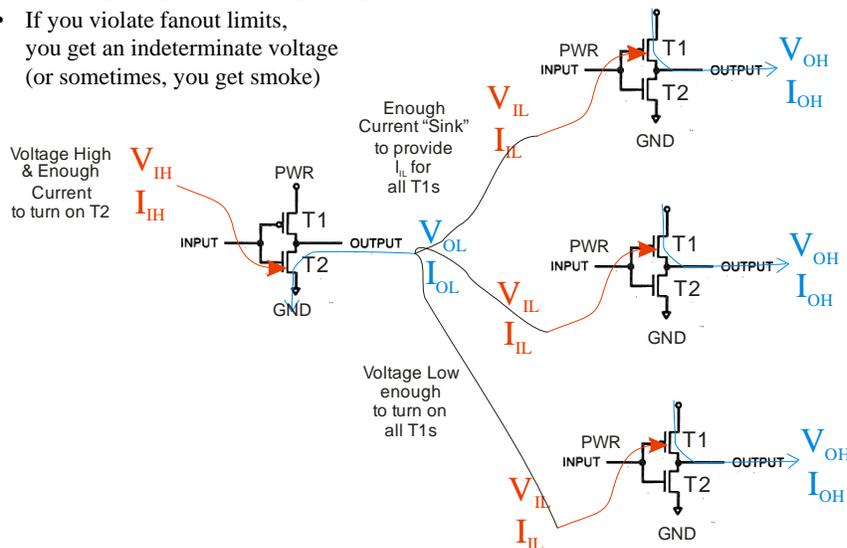


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## Fanout – How Many Gates Can You Drive?

◆ Fanout of 3 means an output can drive at most 3 inputs

- E.g.,  $V_{OL} < V_{IL}$  and  $\sum(I_{IL}) < I_{OL}$
- If you violate fanout limits, you get an indeterminate voltage (or sometimes, you get smoke)

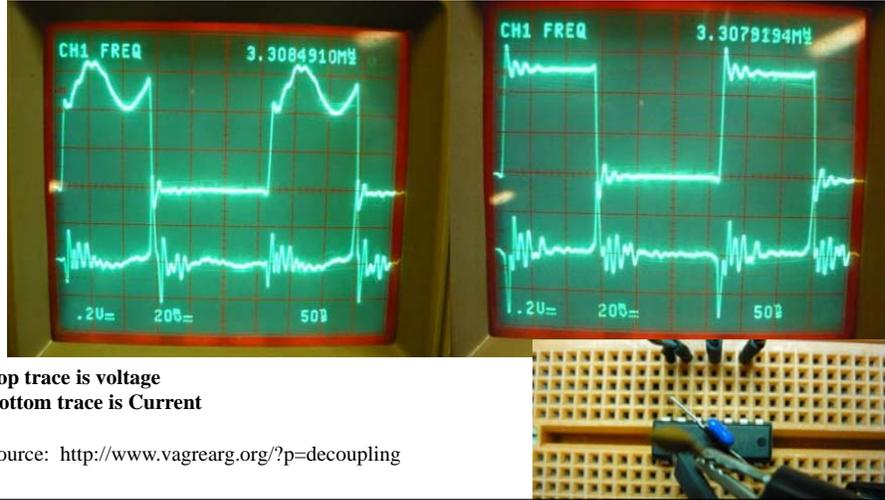


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## Decoupling Capacitors

### ◆ Use decoupling caps to reduce switching noise

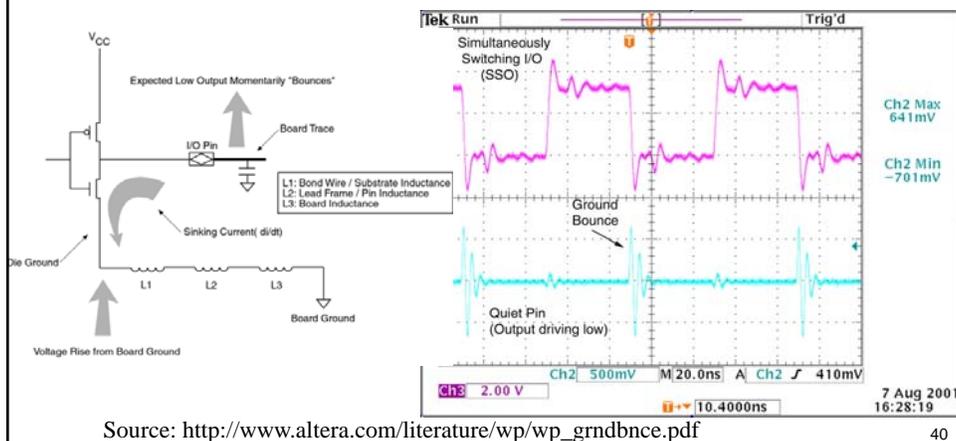
- Provides fast-response temporary power supply for switching
- Left: no cap Right: with capacitor



## Ground Bounce

### ◆ CMOS power is largely consumed halfway through switch

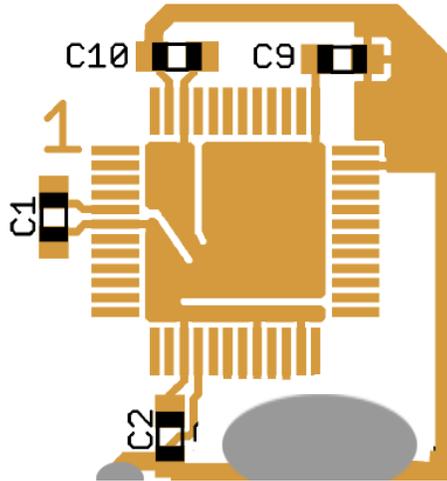
- Momentary near-short between power and ground when switching – near zero resistance
- This causes power to be pulled down and ground to be pulled up
  - Decoupling caps help with this too!
- Note that ground bounce of  $>V_{IL}$  on TTL causes “maybe” values



## Decoupling (“bypass”) capacitor placement

### ◆ Put capacitors as close to chip as possible

- Minimize total wire length between power and ground pins
- (picture is suggested layout for course CPU – note extra-wide ground trace!)



[Freescale]

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## Noise issues

### ◆ Electronic “noise” is a fact of life

- Digital signals are a nice fiction; real signals are analog
- Inductive/capacitive coupling among circuit traces
- Switching transients affecting power supplies

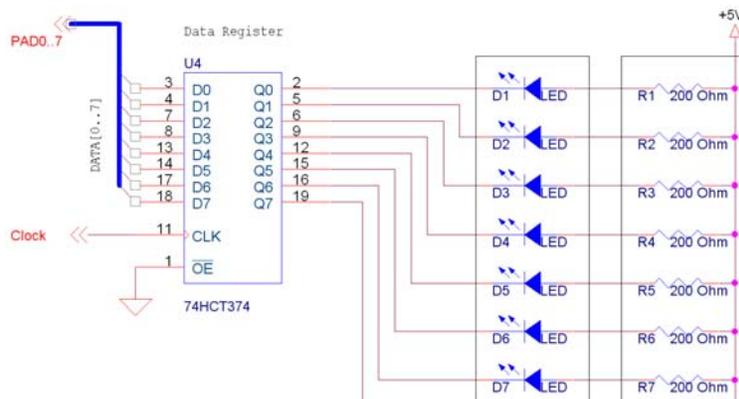
### ◆ Good design practices (for noise and other matters):

- Use decoupling capacitors to act as mini-power-supplies for chips
  - Use a capacitor as close as possible to power/ground pin pair on a chip
  - Generally this is enough under 50 MHz (usually 0.01 to 0.1 uF)
  - Above 50 MHz more care is required (but most small embedded systems are slow)
- Separate analog and digital portions of the PCB (don’t intermix traces)
  - Video, radio, and backlight power traces are especially nasty radiators of noise
  - Audio is especially sensitive to picking up interference from other traces
- Run ground traces on all sides of critical lines
- Dedicated layers for power and ground planes or grids
- Socket external interface chips that could get burned out via transients
- Put power on an un-populated PCB to check for power/ground faults

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## How Much $I_{OL}$ is Enough?

- Assume 2V drop across LED – how much current is drawn?
  - Assume  $V_{OL} = 0.5V$
  - Reminder – Ohm's Law:  $V=IR$
  - What is  $I_{OL}$ ?
- Does  $I_{OH}$  matter for this circuit?



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## Course Microcontroller Data Sheet Contents

- ▣ Chapter 1 MC9S12C and MC9S12GC Device Overview (MC9S12C128)
- ▣ Chapter 2 Port Integration Module (PIM9C32) Block Description
- ▣ Chapter 3 Module Mapping Control (MMCV4) Block Description
- ▣ Chapter 4 Multiplexed External Bus Interface (MEBIV3)
- ▣ Chapter 5 Interrupt (INTV1) Block Description
- ▣ Chapter 6 Background Debug Module (BDMV4) Block Description
- ▣ Chapter 7 Debug Module (DBGV1) Block Description
- ▣ Chapter 8 Analog-to-Digital Converter (ATD10B8CV2) Block Description
- ▣ Chapter 9 Clocks and Reset Generator (CRGV4) Block Description
- ▣ Chapter 10 Freescale's Scalable Controller Area Network (S12MSCANV2)
- ▣ Chapter 11 Oscillator (OSCV2) Block Description
- ▣ Chapter 12 Pulse-Width Modulator (PWM8B6CV1) Block Description
- ▣ Chapter 13 Serial Communications Interface (S12SCIV2) Block Description
- ▣ Chapter 14 Serial Peripheral Interface (SPIV3) Block Description
- ▣ Chapter 15 Timer Module (TIM16B8CV1) Block Description
- ▣ Chapter 16 Dual Output Voltage Regulator (VREG3V3V2) Block Description
- ▣ Chapter 17 16 Kbyte Flash Module (S12FTS16KV1)
- ▣ Chapter 18 32 Kbyte Flash Module (S12FTS32KV1)
- ▣ Chapter 19 64 Kbyte Flash Module (S12FTS64KV4)
- ▣ Chapter 20 96 Kbyte Flash Module (S12FTS96KV1)
- ▣ Chapter 21 128 Kbyte Flash Module (S12FTS128K1V1)
- ▣ Appendix A Electrical Characteristics
- ▣ Appendix B Emulation Information
- ▣ Appendix C Package Information
- ▣ Appendix D Derivative Differences
- ▣ Appendix E Ordering Information

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## Lecture 2 Review

### ◆ General pinout of course microcontroller

- Types of pins
  - But not “what does pin 17 do” without a pinout diagram
- General voltages, speeds, packaging

### ◆ General electronic hardware

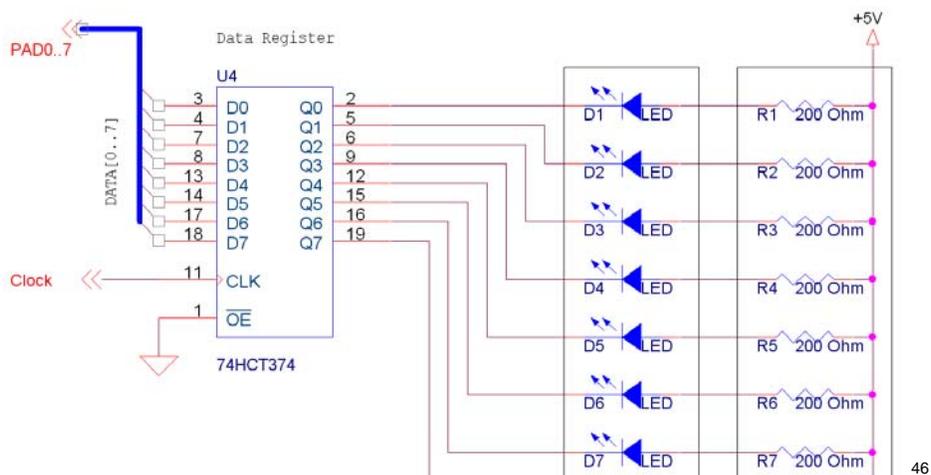
- Packaging types
- Where’s pin 1 on a package?
- Printed circuit board construction and related topics
- Circuit parameters and meanings (e.g., what does “ $I_{OH} = 4\text{ mA}$ ” really mean?)
- Be able to compute current through an LED
  - LED components are most expensive after CPU – almost \$5 apiece
  - Over-driving CPU outputs can easily burn out CPU module (about \$75)
  - Use resistors with LEDs – and get resistor value right!
- Good design practices

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## Lab Skills

### ◆ Be able to hook a simple circuit on a proto-board

- D-register (including chip insertion into the proto-board)
- LEDs
- Resistors



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